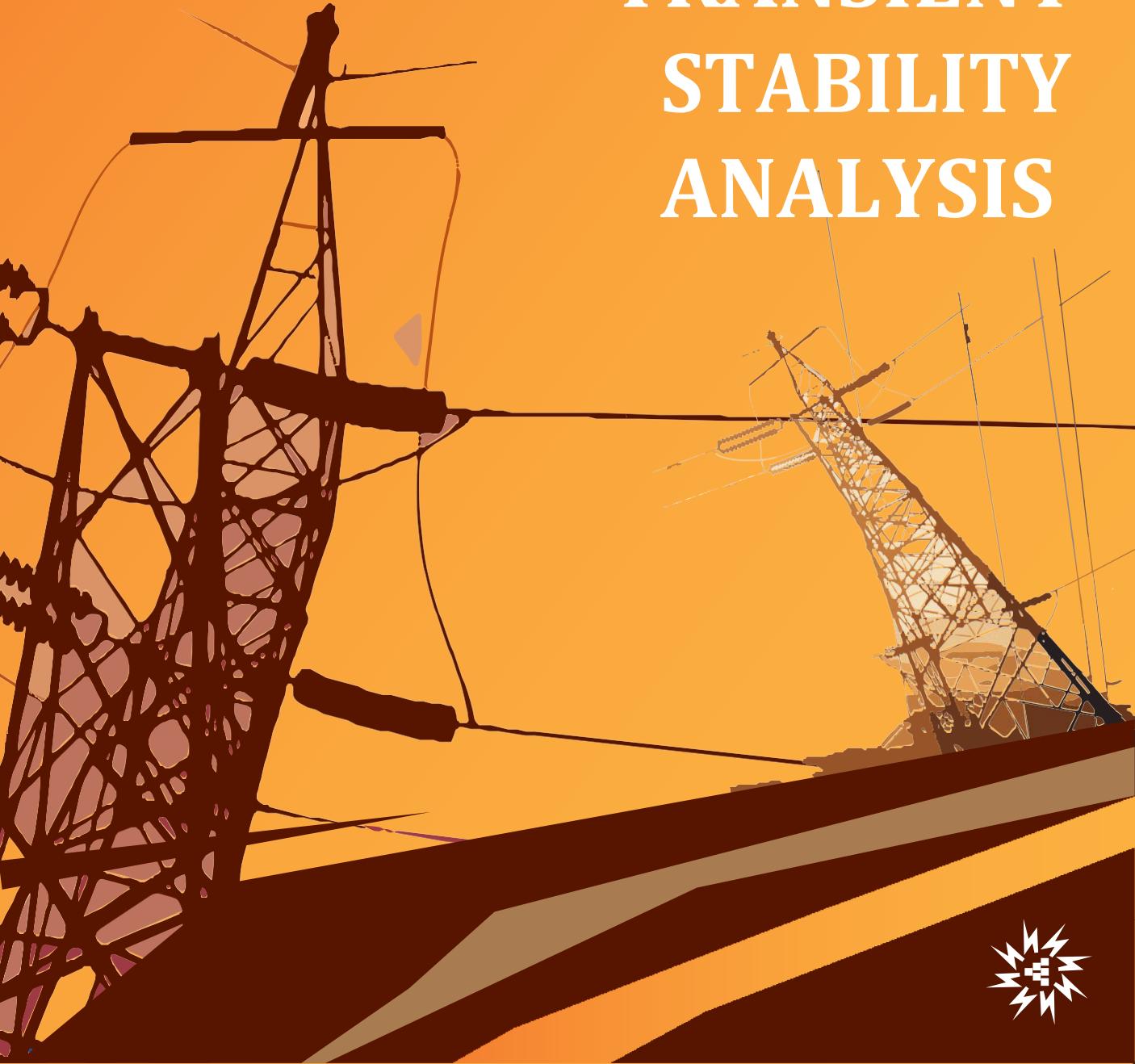


# TRANSIENT STABILITY ANALYSIS



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## 1. Introduction

---

**POWERTRS** is designed to perform the transient stability analysis for the given power system. The transient behavior of a power system, resulting from major disturbances such as a fault followed by switching operations, sudden rejection of load or generation, etc., is referred to as Transient Stability. Transient stability solution is obtained in time domain. Transient stability simulation studies are carried out to study these phenomena and the results enable to plan and coordinate the protection and control schemes efficiently. Critical clearing times of circuit breakers can be computed and protection zones of distance relays during transient swings can be adjusted. Proper restoration/islanding schemes can be suitably designed. Compared to load flow and short circuit studies, transient stability studies are more complex since they involve the electromechanical dynamics of rotating machines and their associated controls viz., excitation and governor systems. The period of investigation varies from fraction of a second when first swing stability is being determined, to over several seconds when multiple swing stability is to be examined.

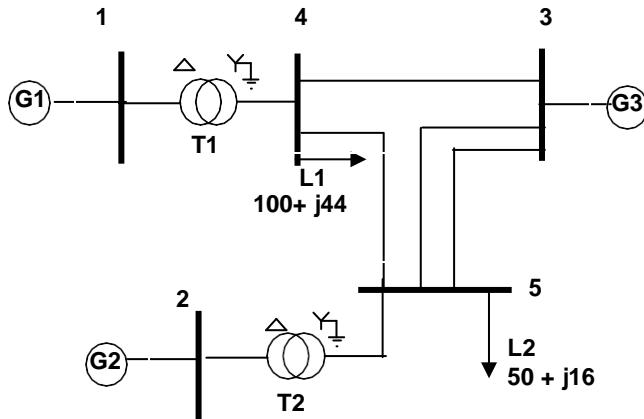
The program requires the base case load flow solution to establish the initial conditions. The program uses fast decoupled load flow method for the network solution, and implicit trapezoidal rule of integration method for the solution of differential equation representing the dynamics of machines, controllers, etc.

The program input data is through an ASCII file, the format of which is described in chapter 3. In chapter 5, case studies are given, wherein the data file preparation for typical transient stability studies are discussed along with the analysis of the results.

## 2. HOW TO SOLVE TRANSIENT STABILITY

### Example: Transient Stability Studies

Figure shows a single line diagram of a 5-bus system with three generating units, four lines and two transformers and two loads. Per-unit transmission line series impedances and shunt susceptances are given on 100 MVA base, generator's transient impedance and transformer leakage reactances are given in the accompanying table.



Values given are on 100 MVA Base. Frequency = 60 Hz.

If a 3 - phase fault occurs on line 4 - 5 near bus 4 and the fault is cleared by simultaneously opening the circuit breaker at the ends of the line 4-5 at 0.225 seconds (fault clearing time), plot the swing curve and comment on stability of machine 1 and machine 2

Transmission Line Details		
Bus - code	Impedance	Line charging
p-q	Zpq	Y'pq/2
3 - 4	0.007 + j0.04	j0.041
3 - 5(1)	0.008 + j0.047	j0.049
3 - 5 (2)	0.008 + j0.047	j0.049
4 - 5	0.018 + j0.110	j0.113

### Transformer Details:

T1 = 20/230 kV 400 MVA with Leakage reactance = 0.022  
 p.u T2 = 18/230 kV 250 MVA with Leakage reactance = 0.040 p.u

**Generator Details:**

G1 = 400 MVA, 20 kV, X'd = 0.067 pu, H = 11.2 MJ / MVA

G2 = 250 MVA, 18 kV, X'd = 0.10 pu, H = 8.0 MJ / MVA

G3 = 1000 MVA, 230 kV, X'd = 0.00001 p.u, H = 1000 MJ / MVA (Infinite Bus Modeling)

Generation and Load Details					
Bus Code 'p'	Generation		Load		Specified Voltage
	MW	Mvar	MW	Mvar	
1	350	71.2	0	0	1.03
2	185	29.8	0	0	1.02
3	800	0	0	0	1.0
4	0	0	100	44	Unknown
5	0	0	50	16	Unknown

**Interpretation according to MiP-PSCT:**

- Observe transmission line details. You will find lines connected to nodes 3 and 5 have common parameters.
- No of transmission line libraries = 3
- No of generator libraries = 3 (Three different generators)
- No. of transformer libraries = 2 (two different transformers)

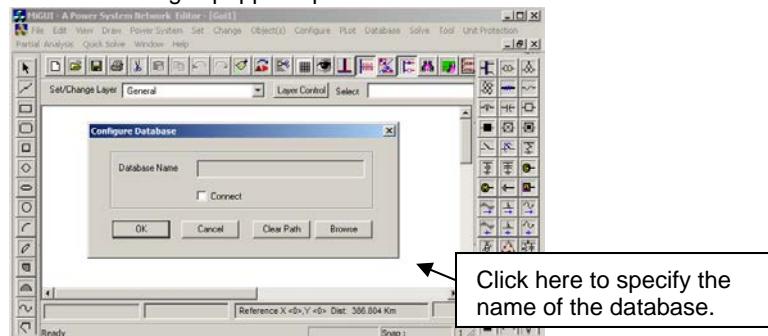
**Procedure to enter the data for performing studies, using MiP-**

**PSCT.** Following are the two methods.

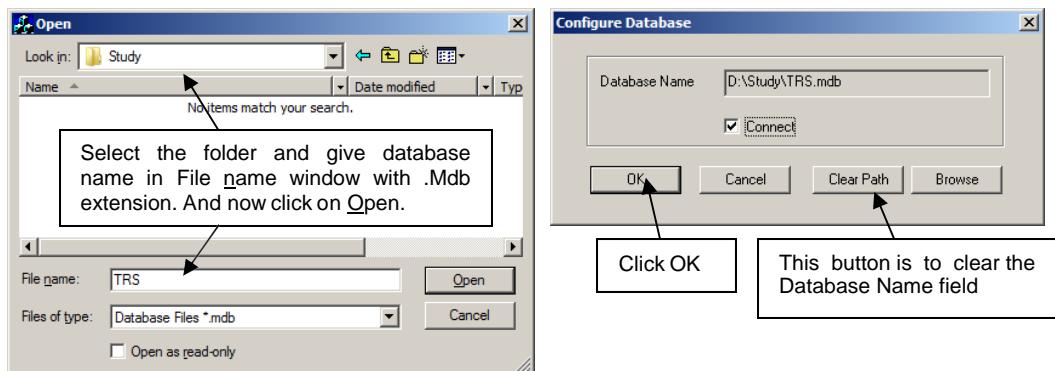
1. Drawing single line diagram and entering corresponding data in database manager separately.
2. Drawing single line diagram and entering the data simultaneously.

**Method 2 follows:****MiP-PSCT - Database Configuration**

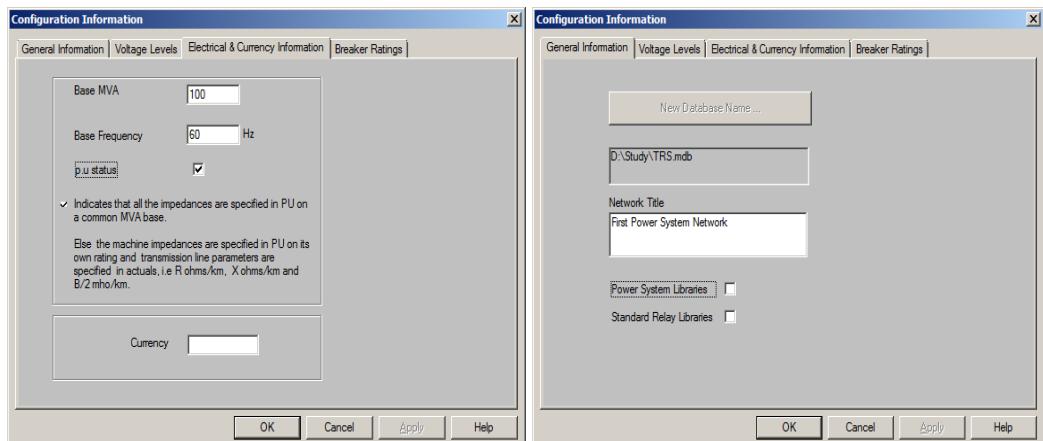
Open power system network editor. Select menu option **Database → Configure**. Configure Database dialog is popped up as shown below. Click **Browse** button.



**Open** dialog box is popped up as shown below, where you are going to browse the desired directory and specify the name of the database to be associated with the single line diagram. Click **Open** button after entering the desired database name. **Configure Database** dialog will appear with path chosen.



Click **OK** button on the **Configure Database** dialog. The dialog shown below appears.

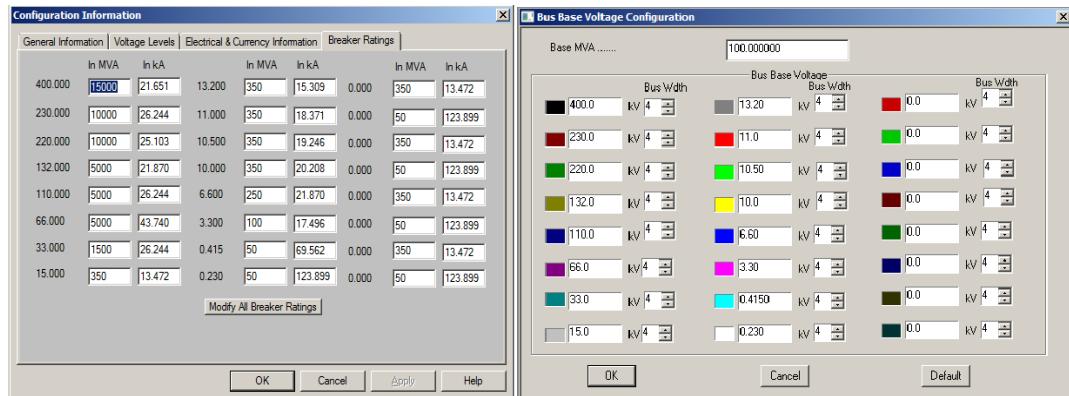


Uncheck the Power System Libraries and Standard Relay Libraries. For this example these standard libraries are not needed, because all the data is given on pu for power system libraries (like transformer, line\cable, generator), and relay libraries are required only for relay co-ordination studies. If Libraries are selected, standard libraries will be loaded into the database. Click **Electrical Information** tab. Since the impedances are given on 100 MVA base check the

pu status as shown. Enter the Base MVA and Base frequency as shown above. Click on Breaker Ratings button to give breaker ratings. Click **OK** button to create the database to return to Network Editor.

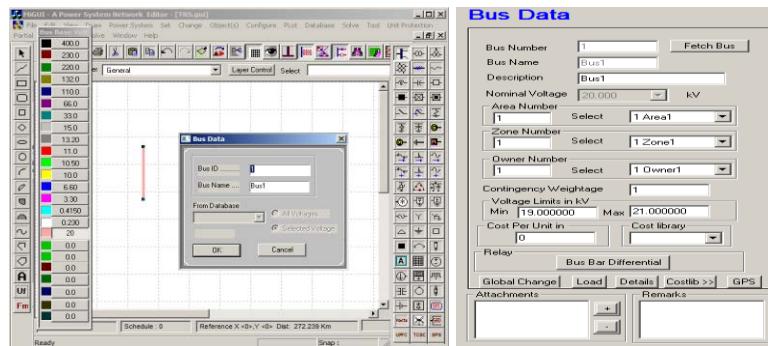
### Bus Base Voltage Configuration

In the network editor, configure the base voltages for the single line diagram. Select menu option **Configure→Base voltage**. The dialog shown below appears. If necessary change the **Base-voltages, color, Bus width** and click **OK**.



### Procedure to Draw First Element - Bus

Click on **Bus** icon provided on power system tool bar. Draw a bus and a dialog appears prompting to give the Bus ID and Bus Name. Click **OK**. Database manager with corresponding **Bus Data** form will appear. Modify the area number, zone number and contingency weightage data if it is other than the default values. If this data is not furnished, keep the default values. Usually the minimum and maximum voltage ratings are  $\pm 5\%$  of the rated voltage. If these ratings are different, modify these fields. Otherwise keep the default values.

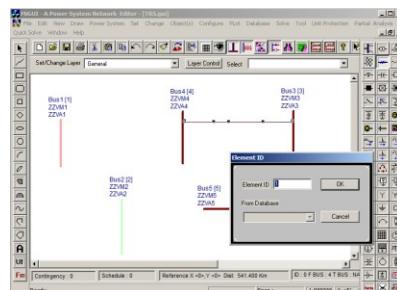


Bus description field can be effectively used if the bus name is more than 8 characters. If bus name is more than 8 characters, then a short name is given in the bus name field and the bus description field can be used to abbreviate the bus name. For example let us say the bus name is **Northeast**, then bus name can be given as **NE** and the bus description field can be **North East**. After entering data click **Save** , which invokes **Network Editor**. Follow the same procedure for remaining buses. Following table gives the data for other buses.

Bus Data					
Bus Number	1	2	3	4	5
Bus Name	Bus-1	Bus-2	Bus-3	Bus-4	Bus-5
Nominal voltage	20	18	230	230	230
Area number	1	1	1	1	1
Zone number	1	1	1	1	1
Contingency weightage	1	1	1	1	1

### Procedure to Draw Transmission Line

Click on **Transmission Line** icon provided on power system tool bar. To draw the line click in between two buses and to connect to the from bus double clicking LMB (Left Mouse Button) on the **From Bus** and join it to another bus by double clicking the mouse button on the **To Bus**. **Element ID** dialog will appear.



Enter **Element ID** number and click OK. Database manager with corresponding **Line\Cable Data** form will be open. Enter the details of that line as shown below.

**Line\Cable Data**

Number:	Fetch Line >>	Name: [Line1]	Maintenance
De-Rated MVA:	100	From Breaker	Type: <input checked="" type="radio"/> Current <input type="radio"/> Power
Rating I:	100 Mva	Rating	Amperes: [0]
Rating II:	100 Mva	Exits	pf: [0.8]
Number of Circuits:	1	To Breaker	Show Breaker SLD: <input type="checkbox"/> Yes
From Bus Number:	3 [Bus-2] (230.000)	Rating	SLD Notation: <input checked="" type="radio"/> Line <input type="radio"/> Cable <input type="radio"/> Breaker <input type="radio"/> Isolator
To Bus Number:	4 [Bus-4] (230.000)	Exits	NDP: <input checked="" type="radio"/> No <input type="radio"/> From Side <input type="radio"/> To Side
Line Length:	1 km	Structure Ref. No.:	4000 [Line4000]
Contingency Weightage:	1	Transmission Line Library >>	Line Details >>
Status:	<input checked="" type="radio"/> In Service <input type="radio"/> From End Open <input type="radio"/> To End Open <input type="radio"/> Out of Service	Commission Status:	<input checked="" type="radio"/> Existing <input type="radio"/> Proposed Year: [0]
From Side Open:	<input checked="" type="radio"/> TNOP <input type="radio"/> Maintenance <input type="radio"/> Fault <input type="radio"/> Others: [MNT]	To Side Open:	<input checked="" type="radio"/> TNOP <input type="radio"/> Maintenance <input type="radio"/> Fault <input type="radio"/> Others: [ ]

Enter **Structure Ref No.** as **4000** and click on **Transmission Line Library >>** button. **Line & Cable Library** form will appear. Enter transmission line library data in the form as shown below for Line3-4.

**Line and Cable Library**

Structure Reference	Number : 4000	Name : Line4000	Fetch Line
Positive Sequence Resistance	0.007	pu	
Positive Sequence Reactance	0.04	pu	
Positive Sequence Susceptance (B/2)	0.041	pu	
Zero Sequence Resistance	0	pu	
Zero Sequence Reactance	0	pu	
Zero Sequence Susceptance (B/2)	0	pu	
Thermal Rating	100	MVA	Compute
Line Harmonic Number	0	Harmonic Library >>	
Cost per km	0	Cost Per Unit in	Thermal Curve>>
Attachments			
Remarks			

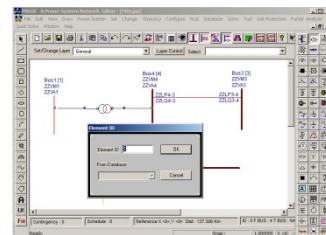
Enter other line libraries and element data details as per the following tables:

Transmission Line Libraries			
Structure Ref. No.	4000	4001	4002
Structure Ref. Name	Line-3-4	Line-3-5	Line-4-5
Positive Sequence Resistance	0.007	0.008	0.018
Positive Sequence Reactance	0.040	0.047	0.110
Positive Sequence Susceptance	0.041	0.049	0.113
Thermal Rating	100	100	100

Transmission Line Element Data Details				
Line Number	1	2	3	4
Line Name	Line3-4	Line3-5	Line4-5	Line3-5
De-Rated MVA	100	100	100	100
No. Of Circuits	1	1	1	1
From Bus No.	4	3	4	3
To Bus No.	3	5	5	5
Line Length	1	1	1	1
From Breaker Rating	5000	5000	5000	5000
To Breaker Rating	5000	5000	5000	5000
Structure Reference No.	4000	4001	4002	4001

## Procedure to Draw Transformer

Click on **Two Winding Transformer** icon provided on power system tool bar. To draw the transformer click in between two buses and to connect to the from bus double clicking LMB (Left Mouse Button) on the **From Bus** and join it to another bus by double clicking the mouse button on the **To Bus**. The **Element ID** dialog will appear. Click OK.



**Two Winding Transformer Data** form will be open. Enter the **Manufacturer Ref. Number** as **30**. Enter transformer data in the form as shown below. Click on **Transformer Library >>** button.

Transformer Number: 2T11  
 Status: In Service  
 Commission Status: Existing  
 Secondary Voltage: 20.000 kV  
 From Bus Number: Bus 1 [Bus 1] (220.000)  
 To Bus Number: Bus 4 [Bus 4] (220.000)  
 Control Bus Number: Bus 1 [Bus 1] (220.000)  
 No. of Units in Parallel: 1  
 Contingency Weightings: 1  
 De-Rated MVA: 400 MVA  
 Rating I: 400 MVA  
 Rating II: 400 MVA  
 P% Grounding Resistance: 0 ohms  
 Sec Grounding Resistance: 0 ohms  
 P% Grounding Resistance: 0 ohms  
 Sec Grounding Resistance: 0 ohms

Enter transformer library details as shown below. Click **Save** button and close the screen. Transformer element data form will appear. Click **Save** button, which invokes Network Editor. In the similar way enter other transformer details.

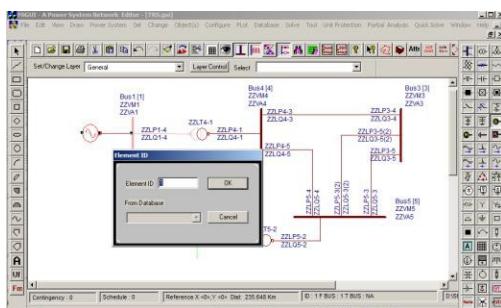
Manufacturer Ref. Number: 30  
 MVA Rating: 400  
 Primary Voltage: 230.000 kV  
 Secondary Voltage: 20.000 kV  
 Minimum Tap Number: 1  
 Minimum Tap Voltage: 218.500 kV  
 Maximum Tap Number: 9  
 Maximum Tap Voltage: 241.500 kV  
 pu on Common MVA Base:  
 Pos. Seq. Impedance: 0.022  
 Pos. Seq. X to R Ratio: 9999  
 Zero Seq. Impedance: 0.022  
 Zero Seq. X to R Ratio: 9999  
 Transformer losses:  
 Noload: 0 W  
 Copper: 0 W  
 Update X/R ratio:   
 Winding Configuration:  
 Primary: Y Y   
 Secondary: Y Y   
 Phase displacement: 0°  
 Magnetization Curve Data in pu on Common MVA Base:  
 Primary Winding:   
 Secondary Winding:   
 Residual Flux:  
 Phase A: 0  
 Phase B: 0  
 Phase C: 0  
 - I-V Characteristics:  
 1 in % V in pu:   
 Add:   
 Delete:   
 Thermal Curve:   
 Cool Per Unit:

Transformer Library Detail		
Manufacturer ref. No.	30	31
Manufacturer Name	2T30	2T31
MVA Rating	400	250
Primary Voltage	230	230
Secondary Voltage	20	18
Minimum Tap	1	1
Maximum Tap	9	9
Minimum Tap Voltage	218.5 ( 230 * 0.95)	218.5 ( 230 * 0.95)
Maximum Tap Voltage	241.5 ( 230 * 1.05)	241.5 ( 230 * 1.05)
Positive Sequence Impedance	0.022	0.040
R/X Ratio	9999 (R is Negligible)	9999 (R is Negligible)

Transformer Element Detail		
Transformer Number	1	2
Transformer Name	2T1	2T2
From Bus Number	4	5
To Bus Number	1	2
Control Bus Number	1	2
Number of Units in Parallel	1	1
Manufacturer ref. Number	2T30	2T31
De Rated MVA	400	250
From Breaker Rating	5000	5000
To Breaker Rating	350	350
Nominal Tap Position	5	5

### Procedure to Draw Generator

Click on **Generator** icon provided on power system tool bar. Draw the generator by clicking LMB (Left Mouse Button) on the **Bus1**. The **Element ID** dialog will appear. Click **OK**.



**Generator Data** form will be opened. Enter the **Manufacturer Reference No** as 30. Enter generator data in the form as shown below.

The Generator Data form contains the following key input fields:

- Number:** 30
- Name:** Gen1
- Bus No:** 1 [Bus1] (20.000)
- Units in Parallel:** 1 GT
- Specified Voltage:** 1.0300 Pu 20.6000 kV
- De-Rated MVA:** 400
- Scheduled Power:** 350 MW
- Reactive Power - Minimum:** 71.2 Mvar
- Reactive Power - Maximum:** 71.2 Mvar
- Breaker Rating:** In MVA: 350 In kA: 96.703
- Real Power Optimization Data:**
  - Real Power - Minimum: 0 MW Cost Coefficient C0: 0
  - Real Power - Maximum: 0 MW Cost Coefficient C1: 0
  - Real Power - Maximum: 0 MW Cost Coefficient C2: 0
- Status:** In Service
- Neutral Grounding Resistance:** 0 ohms
- Neutral Grounding Reactance:** 0 ohms
- Grounding Through Transformer:** Calculate
- Model Type:**
  - Infinite Bus Modeling (Xd)
  - Transient Modeling (Xd & Xq)
  - Sub Transient Modeling (Xd & Xq)
- AVR Ref No:** 0 [AVR] Type 0 AVR Library
- AVR FFB Name:** 0 Type 0 AVR Library
- Turbine Gov Ref No:** 0 Type 0 TG Library
- Tur Governor Name:** 0 Tur Governor

Click on **Generator Library >>** button. Enter generator library details as shown below.

The Generator Library form displays the following generator parameters:

- Ref. Number:** 30
- MVA Rating:** 400
- MW Rating:** 350
- kV Rating:** 20
- Armature Resistance (Ra):** 0 pu
- Direct Axis Reactance (Xd):** 0 pu
- Quadrature Axis Reactance (Xq):** 0 pu
- Negative Seq. Reactance (Xn):** 0 pu
- Zero Seq. Reactance (Xo):** 0 pu
- pu on Common MVA Base:** 0 pu
- Potier Reactance (Xp):** 0 pu
- Direct Axis Transient Reactance (Xd'): 0.067 pu**
- Quadrature Axis Transient Reactance (Xq'): 0 pu**
- Direct Axis Sub-Transient Reactance (X'd): 0 pu**
- Quadrature Axis Sub-Transient Reactance (X'q): 0 pu**
- Direct Axis Open Circuit Transient Time Constant (T'do): 0**
- Quadrature Axis Open Circuit Transient Time Constant (T'qo): 0**
- Direct Axis Open Circuit Sub-Transient Time Constant (T'd): 0**
- Quadrature Axis Open Circuit Sub-Transient Time Constant (T'q): 0**
- Inertia in MJ/MVA:** 11.2
- Damping Factor:** 0
- Winding Connections:** Y, Y0, △
- Mass Details:**
  - Mass Number:** 0
  - Inertia:** 0
  - Damping Factor:** 0
  - Stiffness Co-efficient:** 0
  - MJ/MVA:** Counter
  - pu torque/Elec. Rad:** Delete
- Cost Per Unit in:** 0
- Thermal Curves:** Thermal>>

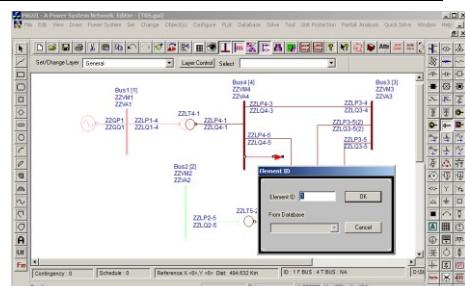
Enter other generator library and element details as per the following table.

Generator Library Details			
Reference Number	30	31	32
Manufacturer Name	BHEL-1	BHEL-2	BHEL-3
MVA Rating	400	250	1000
MW Rating	350	185	800
kV Rating	20	18	230
Ra	0	0	0
Xd	0	0	0
Xq	0	0	0
Xn	0	0	0
Xo	0	0	0
Xp	0	0	0
X'd	0.067	0.10	0.00001
X'q	0	0	0
X d	0	0	0
X q	0	0	0
Inertia MJ/MVA	11.2	8.0	1000

Generator Element Details			
Name	GEN-1	GEN-2	GEN-3
Bus Number	1	2	3
Manufacturer Ref. Number	30	31	32
Number of Generators in Parallel	1	1	1
Capability Curve Number	0	0	0
De-Rated MVA	400	250	1000
Specified Voltage	20.6	18.36	230
Scheduled Power	350	185	800
Reactive Power Minimum	71.2	29.8	0
Reactive Power Maximum	71.2	29.8	600
Breaker Rating	350	350	10000
Type of Modeling	Infinite	Infinite	Infinite

### Procedure To Draw Load

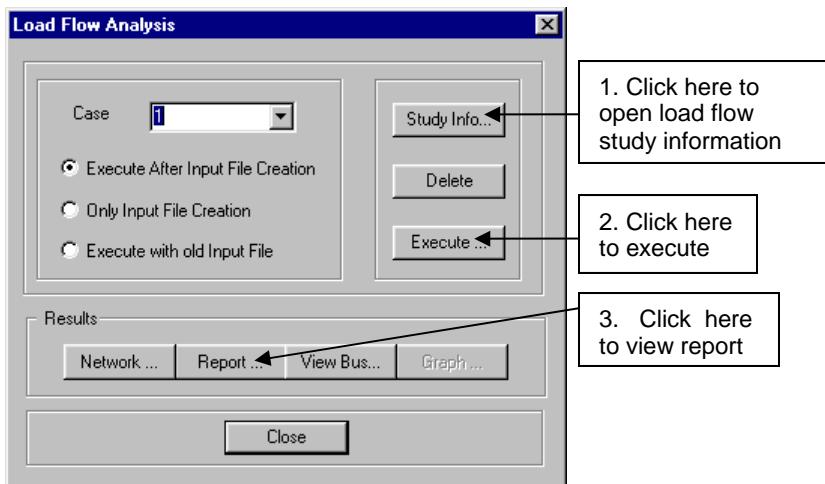
Click on **Load** icon provided on power system tool bar. Draw the load by clicking LMB (Left Mouse Button) on the **Bus4**. The **Element ID** dialog will appear. Click **OK**.



Load Data form will be opened. Enter the load details as shown below.

Connect other load ( $50 + j16$ ) to bus 5.

To solve load flow studies choose menu option **Solve → Load Flow Analysis** or click **LFA** button on the toolbar, which is on the right side of the screen. Load flow analysis screen appears.



## The results of load flow are shown below:

ITERATION COUNT	MAX P NUMBER	MAX P PER UNIT	MAX Q NUMBER	MAX Q PER UNIT
1	1	3.500	4	1.263
2	4	0.087	4	0.016
3	4	0.002	4	0.000
4	4	0.000	4	0.000
5	4	0.000	1	0.000
6	1	0.000	1	0.000

Number of p iterations : 3 and Number of q iterations : 5

### BUS VOLTAGES AND POWERS

NODE NO.	FROM NAME	V-MAG P.U.	ANGLE DEGREE	MW GEN	MVAR GEN	MW LOAD	MVAR LOAD	MVAR COMP
1	Bus1	1.0300	8.90	350.000	71.200	0.000	0.000	0.000
2	Bus2	1.0200	6.39	185.000	29.800	0.000	0.000	0.000
3	Bus3	1.0000	0.00	-380.503	-26.497	0.000	0.000	0.000
4	Bus4	1.0175	4.68	0.000	0.000	100.000	44.000	0.000
5	Bus5	1.0109	2.27	0.000	0.000	50.000	16.000	0.000

NUMBER OF BUSES EXCEEDING MINIMUM VOLTAGE LIMIT (@ mark) : 0

NUMBER OF BUSES EXCEEDING MAXIMUM VOLTAGE LIMIT (# mark) : 0

NUMBER OF GENERATORS EXCEEDING MINIMUM Q LIMIT (< mark) : 1

NUMBER OF GENERATORS EXCEEDING MAXIMUM Q LIMIT (> mark) : 0

### LINE FLOWS AND LINE LOSSES

SLNO	CS	FROM NODE	FROM NAME	TO NODE	TO NAME	FORWARD MW	FORWARD MVAR	LOSS MW	LOSS MVAR	% LOADING
1	1	4	Bus4	1	Bus1	-349.988	-44.745	0.0026	26.4537	
86.7#										
2	1	5	Bus5	2	Bus2	-184.999	-16.301	0.0013	13.4999	
73.5\$										
3	1	4	Bus4	3	Bus3	210.573	11.960	3.0157	8.8876	
207.3!										
4	1	4	Bus4	5	Bus5	39.418	-11.215	0.2702	-21.5963	
40.3^										
5	1	3	Bus3	5	Bus5	-86.473	-11.712	0.6019	-6.3713	
87.3#										
6	1	3	Bus3	5	Bus5	-86.473	-11.712	0.6019	-6.3713	
87.3#										

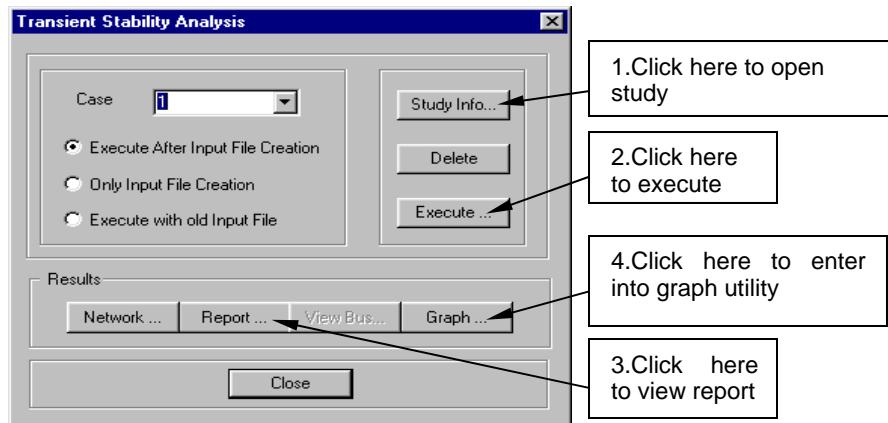
```
! NUMBER OF LINES LOADED BEYOND 125% : 1
@ NUMBER OF LINES LOADED BETWEEN 100% AND 125% : 0
# NUMBER OF LINES LOADED BETWEEN 75% AND 100% : 3
$ NUMBER OF LINES LOADED BETWEEN 50% AND 75% : 1
^ NUMBER OF LINES LOADED BETWEEN 25% AND 50% : 1
& NUMBER OF LINES LOADED BETWEEN 1% AND 25% : 0
* NUMBER OF LINES LOADED BETWEEN 0% AND 1% : 0
```

This will become the initial condition for transient stability analysis

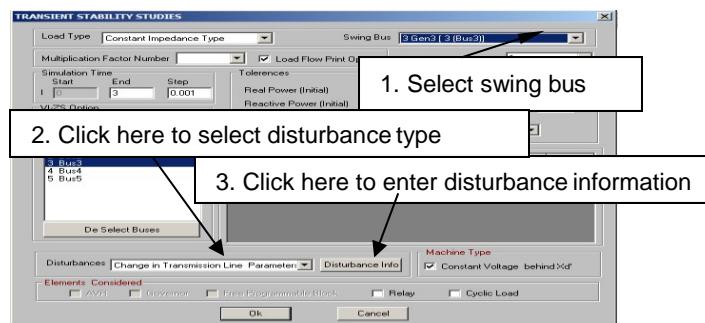
**Note:** You have to get the same results to conduct transient stability study.

### Executing transient stability study:

Click on **Solve → Transient stability analysis.**

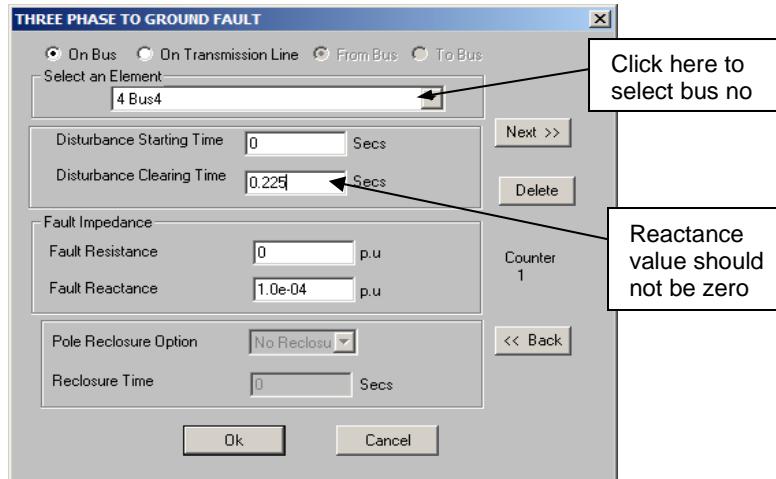


On **Transient Stability Studies** screen click on **Study Info....button.**



Enter all the details as shown:

To simulate 3 phase to ground fault, select the **Disturbances** as *Three Phase To Ground Fault* from the disturbance list and click on **Disturbance Info** button to enter the fault data.

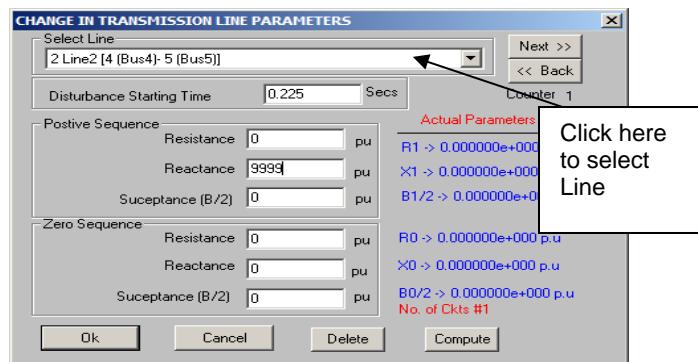


Fault is on bus 4 so select bus 4 from the Bus number list box.

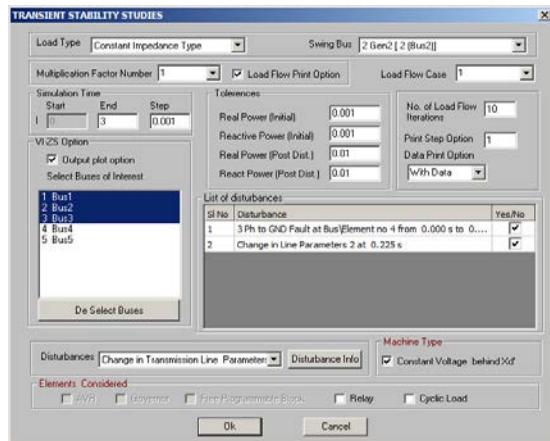
Click **OK** to return to previous form.

To account the effect of opening of breaker, in the disturbance list select *Change in transmission Line Parameters* and click on **Disturbance Info** button.

In this, select line between bus 4 and bus 5. Give disturbance starting time as 0.225 secs and make positive sequence resistance as zero and reactance very high accounting for opening of the line (let us say 9999).



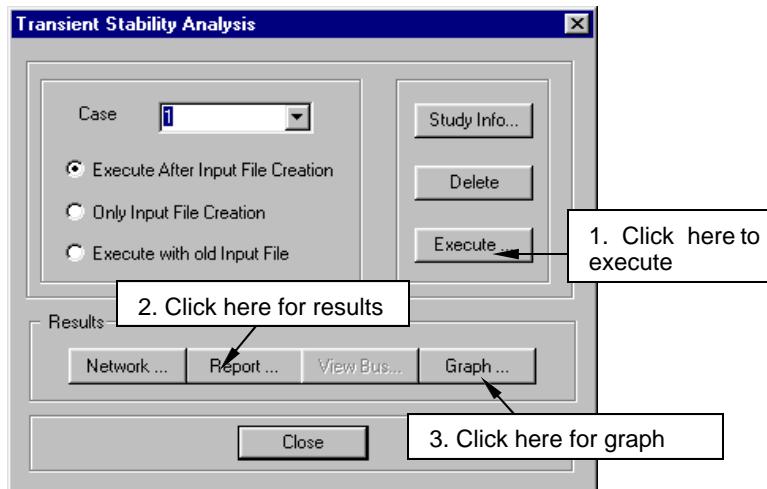
Finally you will return to the previous dialog. Here list of disturbances applied on the network are listed as shown below. Click **OK** button to return to **Solve** dialog.



On the **Solve** dialog box, click Execute button to execute transient stability study.

#### Results Observation:

The results can be observed by clicking **Report** button. The results can be best analyzed using graph. For this click on **Graph** button.



**Part of Report is shown below:**

```

Time = 0.00000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta    Freq   Pgen   Qgen   Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.   MW     MVAR   MW      pu/PU
-----
 1 Bus1       1.03      8.9     20.8     60     350    71.2    350     1.1
 2 Bus2       1.02      6.39    16.2     60     185    29.8    185     1.06
 3 Bus3       1          0 -0.00218     60    -381   -26.2   -381      1

Maximum rotor angle difference : 20.84351 b/w buses : 3 and 1

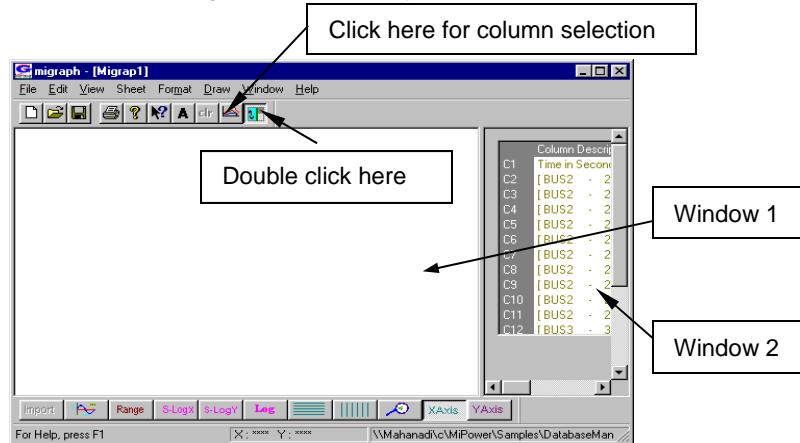
3 phase fault 0.00000      4      Bus4

Time = 0.00100 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta    Freq   Pgen   Qgen   Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.   MW     MVAR   MW      pu/P.U.
-----
 1 Bus1       0.275     20.1     20.8     60     5.93   339     350     1.1
 2 Bus2       0.908     6.55    16.2     60     162    129     185     1.06
 3 Bus3       1 -0.00455 -0.0022    60     414 3.02e+003   -381      1

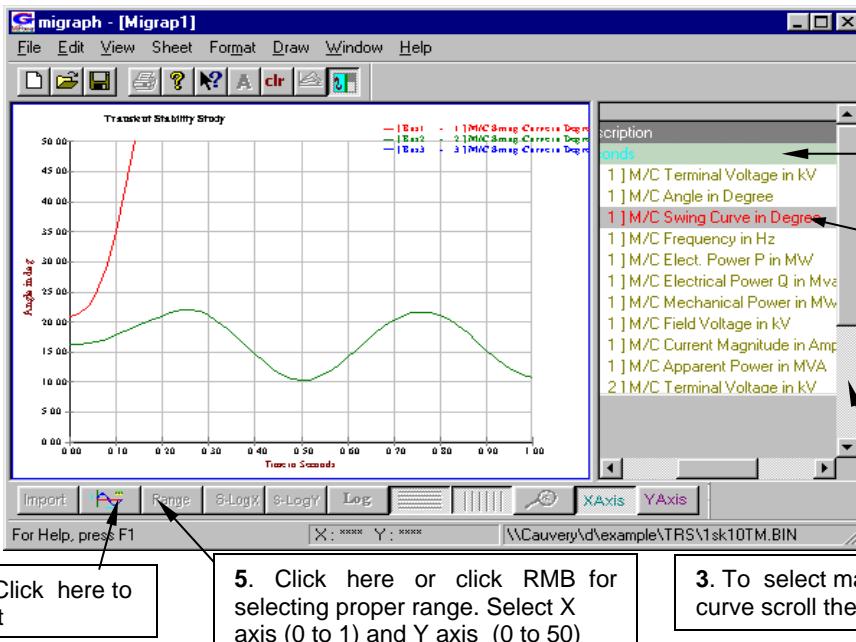
Maximum rotor angle difference : 20.84437 b/w buses : 1 and 3

```

Click Graph button on **Solve** dialog box , Graph Utility screen will open as shown below.



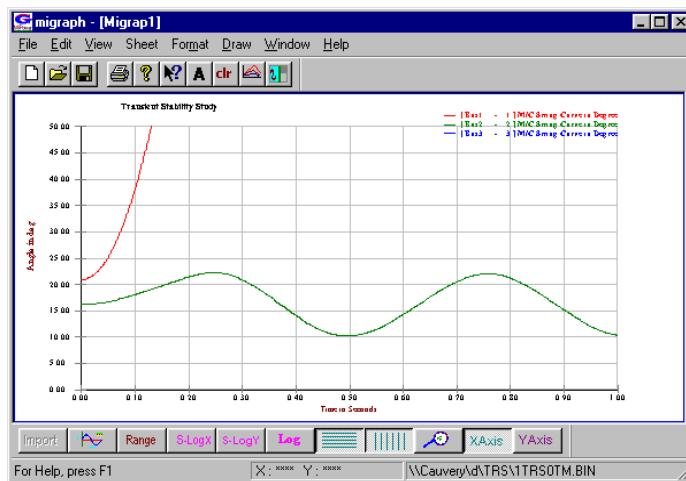
Graph editor will open the corresponding plot file of the study. Window 1 is used for displaying the graphs and window 2 holds the plot variables like time in seconds, swing curve of machines, machine internal angle, machine voltage, machine current etc. User has to choose plot variables in the 2<sup>nd</sup> window.



Final output is shown below

Comment: As seen from the graph

- ❖ Machine 1 turns out to be unstable and machine 2 is stable.



Exercise: For different clearing times conduct studies and observe the swing curves

Hint: Take clearing time = 0.05sec and execute transient stability.

### 3. INPUT FILE FORMAT

---

This chapter gives the input file format, which helps, in creating an input file or manipulating the input file created by integrated mode.

Input data to **POWERTRS** is through an ASCII file. If **POWERTRS** is run in the MiP-PSCT integrated environment, input file is automatically generated using the centralized database, whenever execution of **POWERTRS** is selected. The Input file format is “**1Grid0T.dat0**”, where **1** represents Case Number, **Grid** – Database Name, **0** – Contingency Number, **T** – Study Code - Transient Stability, **dat** – File type – Input, **0** – Schedule Number. Results are written to file “**1Grid0T.out0**”. Graphs files generated by the **POWERTRS** are **1Grid0TM.bin**, **1Grid0TL.bin** & **1Grid0TF.bin**(if any FPB is present in the network). **1Grid0TM.bin**, which contains plot information regarding machines at the selected V-I-Z-S buses present in the network. **1Grid0TL.bin**, which contains plot information regarding lines and other elements present in the network. **1Grid0TF.bin**, which contains plot information regarding free programmable blocks present in the network.

If the input file is prepared by the user according to the format provided in this chapter, there is no restriction on the file name, it is user-defined name. The output files are generated with user-defined filename plus default extensions. About file extensions it has been explained in the table 4.1.

The input data is read in free format. Input data is divided into different heads called streams for explanation purposes. '*int*' is used to indicate that the data type is an integer. '*float*' is used to reference the floating point (real) variable. Character streams (string) are indicated by '*char*' type.

---

#### **Stream 1: System Description**

This consists of 3 lines of data for the description of the power system for which the study is done. Each line data is of char type, and maximum number of alphanumeric characters (including blanks) in a line should not exceed 80. Any useful information, which has to appear in the report file ("TRSOUT") can be given in this stream.

The comment lines can be given in the data file by entering '%' sign in the first column. Comment line is not written in the output file. These lines are simply read and skipped. However, if the comment line has to appear in the output file also, then one more '%' sign should appear in the second column. In the two statements appearing below, the first line does not appear in the output file, while the second line appears in the output file.

% This comment line does not appear in the output file.

%% This comment line appears in the output file.

## Stream 2: System Size Specification

This consists of a line of data, which specifies the system size. Data types/specifications are separated by blanks. Since the data is read in free format, data appearing in a line can be given in successive lines also. Table 3.1 gives the data appearing under different columns of this stream.

Col No.	Description	Type	Min	Max
1.	Maximum Bus Number	Int	1	99999999
2.	Actual number of buses	Int	1	99999
3.	Number of 2 winding transformers	Int	0	5000
4.	Number of 3 winding transformers	Int	0	1000
5.	Number of transmission lines	Int	0	5000
6.	Number of series reactors (inductors)	Int	0	5000
7.	Number of series capacitors	Int	0	5000
8.	Number of bus couplers	Int	0	5000
9.	Number of shunt reactors (inductors)	Int	0	5000
10.	Number of shunt capacitors	Int	0	5000
11.	Number of shunt impedances	Int	0	5000
12.	Number of generators	Int	1	5000
13.	Number of motors	Int	0	5000
14.	Number of loads	Int	0	5000
15.	Number of load characteristics	Int	0	5000
16.	Number of under frequency relays	int	0	1000
17.	Number of voltage relays	int	0	1000
18.	Number of over current relays	int	0	1000
19.	Number of Distance relays	int	0	20
20.	Number of filters	int	0	20
21.	Number of cyclic loads	int	0	5
22.	Number of voltage regulators	int	0	1000
23.	Number of governors	int	0	1000
24.	Number of static var compensators	int	0	100
25.	Number of HVDC converters	int	0	20
26.	Number of DC links	int	0	10
27.	Number of free programmable blocks	int	0	100
28.	Number of Wind Turbines	Int	0	5000
29.	Number of Curves in wind turbine	Int	0	5000
30.	Number of Detailed curves in wind turbine	Int	0	100

Explanations for the entries in table 3.1 are as follows -

- In **POWERTRS** bus numbers need not be assigned continuously and there can be cases wherein some buses are deleted. Maximum bus number in column 1 is the largest bus number used.

- Actual number of buses refers to total buses that are physically present in the system.
- Two winding transformers, three winding transformers, lines, series reactors (inductor), series capacitors and bus couplers are together referred as series elements (branches). Maximum number of series elements should not exceed 2500. Each three winding transformer results in three series elements, since equivalent Star connection data is considered. Sum of total number of two winding transformers and 3 times the number of 3 winding transformers should not exceed 1000. Even though the terminology bus coupler is used in column 8 of table 3.1, it can refer to switches, isolators and disconnecting switches, and are modeled as low impedance paths.
- Shunt reactors (inductor), shunt capacitors and shunt impedances are together referred as shunt elements. Maximum number of shunt elements should not exceed 1000. In **POWERTRS** transformer positive and zero sequence impedances are modeled depending on the winding connection. Zero sequence modeling will have connection to ground from primary or secondary of the transformer, if the transformer winding is delta connected on one side and star-grounded on the other side. Numbers of shunt impedances are equal to the sum of number of actual shunt connections (whose data are given in impedance form) that exist in the system and the shunt impedances that result due to the modeling of the transformer.
- In **POWERTRS** loads can be modeled as constant power load or constant current load or constant impedance load or a combination of all the three, along with frequency correction. Different loads can refer to the same load characteristic. Number of load characteristics is equal to the different characteristics referenced in the load data.
- **POWERTRS** computes the frequency at each time interval at the selected buses other than the generator bus. Also, if the frequency goes below the specified limit, it is possible to trip the series element or shunt element. In case of loads, loads can be tripped partly or completely. Under frequency relays monitor the bus frequency and are set to open the desired breaker. Hence in **POWERTRS** different series and shunt elements can refer to same relay characteristics. Number of frequency relays is equal to different relays referenced in the series element data and shunt element data (including generator and load).
- **POWERTRS** computes the bus voltage magnitude at each time interval at all the buses. Also, if the voltage goes below the specified limit, it is possible to trip the series element or shunt element. In case of loads, loads can be tripped partly or completely. Under voltage relays monitor the bus voltage and are set to open the desired breaker. Hence in **POWERTRS** different series and shunt elements can refer to it under voltage relay characteristics. Number of voltage relays is equal to different relays referenced in the series element data and shunt element data (including generator and load).
- Over current relays are used in the power system to safeguard the equipments from overloading and from severe disturbances arising from faults. In **POWERTRS** 3 seconds and 1.3 seconds over current relays are modeled. Number of over current relays for which the data is provided is entered in column 18.

- Distance relays are modeled in **POWERTRS** using various characteristics. Number of distance relays for which the data is provided is given in column 19.
- An unique feature of specifying the user defined filter is provided in **POWERTRS**. Total number of filters in the system is given in column 20 and should not exceed 20.
- Rolling mill loads are cyclic in nature. Number of cyclic loads in the system is given in column 21.
- POWERTRS** supports standard IEEE representations for voltage regulators and prime movers and speed governors. In addition, free programmable blocks are supported to model any other type of controllers. Total number of free programmable blocks in the system is given in column 27. For more information on free programmable block representation refer the manual – **PowerFPB**.
- Change in wind speed disturbance is only for WT3 type model.
- Change in Wind Turbine Generator generation disturbance is only for WT1, WT2 and WT4 type models.
- Wind Turbine Generator starting disturbance is applicable only for WT1 & WT2.

### Stream 3: Program Control Inputs

Different control inputs are read by **POWERTRS** to control the program flow, results printing and model selection. These inputs are specified under this stream. Data appearing in different columns of line 1 of this stream are given in table 3.2

**Table 3.2 : Program Control Inputs - Line 1**

Col No.	Description	Type	Min	Max
1.	Number of zones	int	0	351
2.	Number of disturbances	int	0	100
3.	Number of nodes for V-I-Z-S output	int	0	20
4.	Number of iterations in load flow analysis	int	5	200
5.	Number of time steps for print	int	1	10000
6.	Index for Load type during post disturbances	int	0	1
7.	Index for load flow print	int	0	1
8.	Index for Voltage impedance print	int	0	1
9.	Index for data details print	int	0	1
10.	Reference bus for relative swing computation	int	0	99999999

Explanations to entries given in table 3.2 are as follows -

- In power system, the equipments are owned by different utilities, and in a same utility, equipments belong to different zones. Hence each bus is associated with a number called zone. All the equipment (shunt elements) connected to the bus are attributed to the zone of the bus. In case of series elements, the line belongs to the zone of the from bus (sending bus). Number of zones in the given power system data are given in column 1.

- It is possible to specify a number of disturbances at different time intervals. Total numbers of disturbances are given in column 2.
- For series elements connected between specified numbers of buses, it is possible to get the voltage, current, impedance and power at the desired time interval. Total number of such buses is given in column 3. If the graph of generator variables is to be plotted, then corresponding generator buses should be included in this list.
- Maximum numbers of iterations refer to the iteration number after which the fast-decoupled power flow iteration used in **POWERTRS** is terminated. This number is usually in the range 10-20.
- Time step for transient stability study is usually in the range 0.01 to 0.025 seconds. While conducting the study for larger duration, it is not necessary to print or plot the values at each time interval. Hence facility is given in terms of print interval time step to control the printing. If the simulation time step is 0.02 seconds, and the print interval time step is 10, then at every 0.1 seconds the printing of results is done.
- Load type during post disturbance is interpreted as -
  - 0: Impedance type of load.
  - 1: As per the load model specified in the load characteristic.
- Index for load flow print is interpreted as - 0 or 1 where
  - 0: No printing of load flow results.
  - 1: Printing of load flow results
- Index for voltage impedance print is interpreted as -
  - 0: No print of voltage at bus, current in a line, and impedance seen by the distance relay.
  - 1: Print of above quantities.
- Index for data details print is interpreted as -
  - 0: No printing of data
  - 1: Data read is printed

If the swing bus is zero absolute swing of each generator is given. If the bus is other than zero, swing relative to this bus angle is given.

### **Stream 3: Line 2: V-I-Z-S Bus Data**

This line data is to be provided, only if the number of V-I-Z-S print buses are greater than 0. Bus numbers corresponding to V-I-Z-S print are given in this line. Hence total number of columns of data is equal to the number of V-I-Z-S buses. All the fields are of integer type, separated by one or more blanks.

### **Stream 3: Line 3 - Model Selection Parameters**

In this line, 9 fields are given to select the model for transformer resistance, circuit breaker impedance etc. Table 3.3 gives the values that appear in different columns of this line.

Table 3.3 : Model selection parameters				
Col No.	Description	Type	Min	Max
1.	Base MVA	float	0.0	1.0e6
2.	Base Frequency	float	0.1	100.00
3.	Transformer R/X ratio	float	0.0	1.0
4.	Circuit breaker resistance in pu	float	0.0	1.0e2
5.	Circuit breaker reactance in pu	float	0.0001	1.0e2
6.	Initial real power tolerance in pu	float	1.0e-4	0.1
7.	Initial reactive power tolerance in pu	float	1.0e-4	0.1
8.	Post disturbance real power tolerance in pu	float	1.0e-4	0.1
9.	Post disturbance reactive power tolerance in pu	float	1.0e-4	0.1

Explanations to entries in table 3.3 are as follows -

- Load and generation data are accepted in actual values i.e., MW for real power and Mvar for reactive power etc. Series and shunt elements' parameters given in the data file are in pu system. Base MVA is the power base considered to compute the pu quantities.
- Transformer R/X ratio (ratio of resistance to reactance) is usually 0.05. In certain cases, the resistance value is unknown and hence R/X ratio is used to compute the resistance value, when the reactance value is given. If the transformer resistance is 0.0, then the resistance is computed as the product of R/X ratio and the transformer reactance. R/X ratio should be given as zero to neglect the transformer resistance in the computation. Entry in column 2 of table 3.3 corresponds to transformer R/X ratio.
- Two techniques are used to model the circuit breaker or switches in closed position. One technique is to merge buses connected between the circuit breakers and treat the buses as single bus for all computation purposes. Other technique is to consider the circuit breaker as a low impedance path. Later is used in the modeling of circuit breakers in **POWERTRS**. In this model the resistance value of circuit breaker is zero and reactance value is 0.0001 p.u. But if the impedances of other elements are relatively large, then the circuit breaker impedance can also be of higher value. Resistance and reactance values of circuit breaker in p.u are given in columns 3 and 4 of table 3.3, respectively. In some applications (especially for distribution systems), higher values are to be used for these two quantities. Since **POWERTRS** requires the solved base case load flow, circuit breaker resistance and reactance used while solving the load flow should be given here also.
- Real and reactive power tolerances are in p.u on the given base. These values are used to check the convergence of fast-decoupled load flow. During each iteration, maximum real and reactive power mismatch at all buses are computed. When maximum real power mismatch is less than the real power tolerance and the maximum reactive power mismatch is less than the reactive power tolerance, convergence is achieved. On hundred MVA base 0.001 p.u is generally an acceptable value for tolerance, which results in 0.1 MW real power error. If all the load values are relatively large, then tolerance value can be as high as 0.1 p.u on 100 MVA base. Tolerance values for pre-disturbance and post disturbance is given separately. The values can be same for both the cases.

### Stream 3: Line 4 - Variable Time Step Data

**POWERTRS** has the facility to consider different time steps for different intervals of study time. Table 3.4 gives the values that appear in different columns of this line.

<b>Table 3.4 : Variable Time Step Data</b>				
<b>Col No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
1.	End time for interval 1 in seconds	float	0.025	1.0e3
2.	Time step for interval 1 in seconds	float	0.001	0.1
3.	End time for interval 2 in seconds	float	0.025	1.0e3
4.	Time step for interval 2 in seconds	float	0.001	0.1
5.	End time for interval 3 in seconds	float	0.025	1.0e3
6.	Time step for interval 3 in seconds	float	0.001	0.1
7.	Maximum simulation time in seconds	float	0.025	1.0e3
8.	Time step for interval 4 in seconds	float	0.001	0.1

Explanations to entries given in table 3.4 are as follows –

Starting time is always at  $t = 0.0$  seconds.

End of each time interval is measured from the starting time i.e.,  $t = 0.0$  seconds.

It is assumed that the end of each time intervals is in the increasing order.

Maximum simulation time is the duration for which **POWERTRS** should run.

Normal value for maximum simulation time is 3 seconds, and the time step is 0.025 seconds.

### Stream 3.1 New Stream: Zone wise Multiplication Factor

In this stream, for each zone, (a) Zone number, (b) Print option, (c) real power multiplication factor and (d) reactive power multiplication factor are read. Zone zero corresponds to global change.

### Stream 4: Disturbance Data

In this stream, disturbance data is given. Numbers of lines in this stream are equal to the number of disturbances as specified earlier. Each line consists of 12 fields. Fields are separated by a blank. Exact value that appears under each column depends on the disturbance type. Table 3.5 gives the values that appear under different columns.

**Table 3.5 - System Specification – Line 6 : Multiplication factors**

Col	Description	Type	Min	Max
1.	Circuit breaker resistance in pu	float	0.0	1.0
2.	Circuit breaker reactance in pu	float	1.0e-5	1.0
3.	Transformer R/X ratio	float	0.0	1.0
4.	Transformer zero sequence impedance multiplication factor	float	0.5	1.0
5.	Number of transmission voltage levels	int	1	20
6.	Transmission line voltage in kV	float	0.001	1.0e4
7.	Transmission line zero sequence resistance multiplication factor	float	0.0	10.0
8.	Transmission line zero sequence reactance multiplication factor	float	1.0	10.0
9.	Transmission line zero sequence admittance multiplication factor	float	0.5	1.0
10.	Generator negative sequence resistance multiplication factor	float	0.0	2.0
11.	Generator negative sequence reactance multiplication factor	float	0.5	2.0
12.	Generator zero sequence resistance multiplication factor	float	0.0	2.0
13.	Generator zero sequence reactance multiplication factor	float	0.5	2.0
14.	Load negative sequence impedance multiplication factor	float	0.1	2.0
15.	Load zero sequence impedance multiplication factor	float	0.1	2.0
16.	Series reactor zero sequence impedance multiplication factor	float	0.5	2.0
17.	Shunt reactor zero sequence impedance multiplication factor	float	0.5	2.0

Explanations to entries given in table 3.5 are as follows -

- Disturbance number is the serial number of the disturbance. It should be given in the increasing order, with no numbers missing in between.
- Disturbance type in column 2 is interpreted as –
  1. Change in transformer/line parameters
  2. Change in shunt impedance load
  3. Change in real and reactive power of loads
  4. 3 Phase fault creation at a bus
  5. 3 Phase fault removal at a bus
  6. Change in number of generator sets at a bus
  7. Complete generation outage at a bus
  8. Simulation of single line to ground fault
  9. Clearing of single line to ground fault
  10. Reclosing of line with SLG fault cleared
  11. Loss of excitation at a generator
  12. Change in Shunt Impedance
  13. Change in Load Model
  14. Motor Start
  21. Wind Turbine Generator Starting
- Disturbance time is the time at which the disturbance is applied. The time is measured from the start of the simulation time i.e., 0.0 seconds. If no disturbance is to be considered, then this time should be larger than the maximum simulation time.

- Disturbance buses are interpreted depending on type of disturbance. For disturbance type 1, 9 and 10 the disturbance buses are from and to bus numbers of the series elements. For all other disturbances, both the numbers should be same and they refer to the bus number at which the disturbance is considered.
- New value fields are interpreted depending on the type of disturbance. The interpretation is -
  - For change in transformer/line parameters, the positive sequence resistance, reactance and susceptance (B/2) in p.u are given in new value 1 fields respectively. In case of transformer, this field is the new transformer tap. Zero sequence resistance, reactance and susceptance (B/2) in p.u are given in new value 2 fields respectively. The values are for the new configuration. Hence to consider the opening of a line, resistance of the line is given as 0.0 p.u, reactance as 999.9 p.u and susceptance as 0.0 p.u for both positive and zero sequence values.
  - For change in shunt impedance load, positive sequence resistance and reactance values in p.u are given in new value 1, field 1 and 2 respectively. Zero sequence values are given in new value 2 fields.
  - For change in PQ load, new real power load in MW, new reactive power load in M VAr and new compensating MVAr at the bus are given in new value 1 fields. New value 2 fields are ignored.
  - For three phase fault, the fault impedance resistance and reactance in p.u are given in new value 1, fields 1 and 2 respectively. Other fields are ignored.
  - For three phase fault removal, the fault impedance resistance and reactance in p.u that are to be removed are given in new value 1, fields 1 and 2 respectively. Other fields are ignored. Normally this value is same as the one given in case of application of 3 - phase fault.
  - For change in number of generator sets at a bus, the old and new real generator ratings in MW are given in new value 1 field 1 and 2 respectively. Other fields are ignored. Since the ratio of old value to new value is of interest, old number of units and new number of units can also be given in new value 1 field 1 and 2 respectively.
  - For complete generation outage at a bus, the new value fields are ignored.
  - For fault types 8 to 9, new value fields are ignored.
- If the disturbance type is 9, then the SLG fault clearing type is interpreted as -
  - 0: Clearing of SLG fault applied at a bus.
  - 1: Single pole opening on from bus side.
- Disturbance type 10 is applicable, only if disturbance 9 is considered with clearing type as 1.
- For a line outage disturbance the line impedance will be changed. Till the line impedance is 999 the line is not physically open. Means if the network gets islanded with that line outage then to see that effect the line impedance should be given a value more than 999.
- Disturbance Wind turbine generator starting, is applicable only for WT1 and WT2 type wind generators

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### Stream 5: Generator Bus Numbers

In this stream all the bus numbers of synchronous and asynchronous machines connected to the system are given. The fields are of integer type and generator/motor bus numbers are separated by one or more blanks.

---

### Stream 6: Bus Data

In this stream of data, bus details are given. Total number of lines of data is equal to actual number of buses as given under system size specification stream. The data in columns of each line are given in table 3.6.

Table 3.7 - Bus				
Col No.	Description	Type	Min	Max
1.	Bus number	int	1	9999
2.	Bus status	int	0	1
3.	Zone number	int	1	20
4.	Bus voltage in kV	float	0.001	1.0e5
5.	Bus name	char	1	8
6.	Voltage magnitude in pu	float	0.5	2.0
7.	Voltage angle in degrees	float	-360.0	360.0
8.	Real power generation at bus in MW	float	-1.0e6	1.0e6
9.	Reactive power generation at bus in Mvar	float	-1.0e6	1.0e6
10.	Real power load at bus in MW	float	-1.0e6	1.0e6
11.	Reactive power load at bus in Mvar	float	-1.0e6	1.0e6
12.	Reactive compensation provided at bus in Mvar	float	-1.0e6	1.0e6

Explanations to entries given in table 3.6 are as follows –

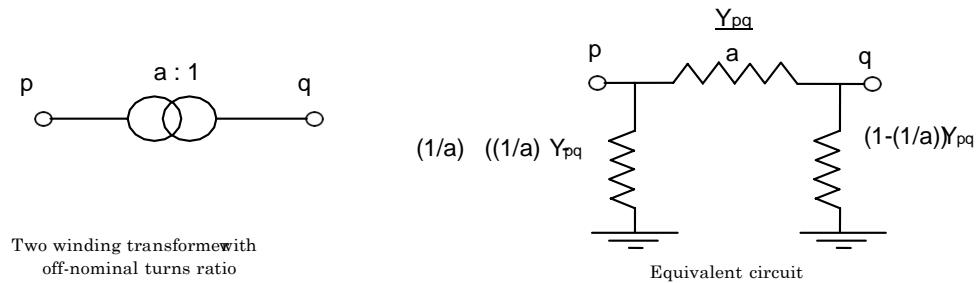
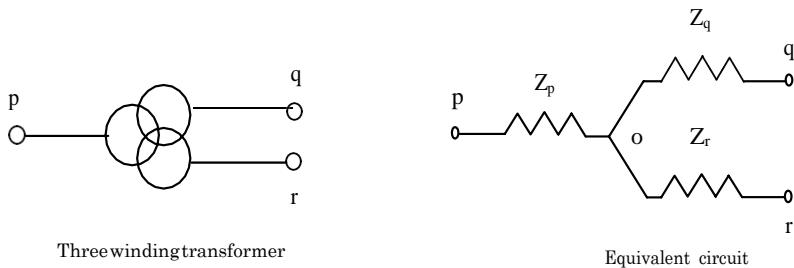
- Bus number refers to the number by which the buses are identified. Bus numbers need not be continuous and buses belonging to different zones can be referenced by having different starting numbers (i.e., buses in zone 1 can have the bus numbers from 1 to 200, buses in zone2 can have the numbers from 201 to 300 and so on. When input file is created through MiP-PSCT's integrated environment, the buses are numbered automatically and the numbers are transparent to the user.
- Island number is the island to which the bus belongs. This number is obtained from the load flow study. If there are no islands in the system, then this field is unity.
- As explained earlier, zone field refers to the zone number to which the bus belongs.
- Bus voltage entry given in column 4 of table 3.6 is in kilovolts and it is also the base voltage for the bus.
- Buses are more commonly referred by names rather than numbers. Bus name is a string of maximum 9 characters. Any alphanumeric characters can constitute the bus name. Bus name should be unique.
- Base case load flow solution's bus voltage magnitude in p.u, voltage angle in degrees, power generation at the bus (MW and MVA), load at the bus (MW, MVA) and

- Compensation in MVar) are obtained from the initial load flow run on the system under consideration.

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### Stream 7: Transformer Data

In this stream of data, transformer details are given. Figure 3.1 shows the modeling of the transformer with off nominal turn's ratio. Figure 3.2 shows the modeling of phase shifting transformer. Three winding transformers are modeled using equivalent star connection between the windings. Figure 3.3 shows the modeling of three-winding transformer. Total number of lines of data in this stream are equal to sum of number of 2-winding transformers and three times the number of three winding transformers. The data that appear in different columns of each line are given in table 3.7.

**Figure 3.1 - Two winding transformer representation****Figure 3.2 - Three winding transformer representation**

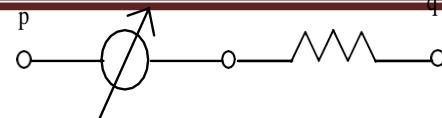
$$(a_s + j b_s) : 1$$

$$(a_s + j b_s) : 1$$

$$Y_{pq}$$



Phase shifting transformer



Equivalent circuit

### 3.3 Phase shifting Transformer Representation

**Table 3.7: Transformer Data**

Col.No.	Description	Type	Min	Max
1.	Connection status	int	0	3
2.	Numbers in parallel	int	1	10
3.	From bus number	int	1	99999999
4.	To bus number	int	1	99999999
5.	Positive sequence resistance in pu.	float	0.0	1.0e2
6.	Positive sequence reactance in pu.	float	1.0e-4	1.0e2
7.	Zero sequence resistance in pu.	float	0.0	1.0e2
8.	Zero sequence reactance in pu.	float	0.0	1.0e2
9.	Nominal tap setting in pu.	float	0.5	1.5
10.	Phase shift	float	0.0	360.0
11.	From side frequency relay number	int	0	20
12.	From side voltage relay number	int	0	20
13.	To side frequency relay number	int	0	20
14.	To side voltage relay number	int	0	20
15.	Transformer phase shift	float	0.0	360.0
16.	Primary winding configuration	Char		
17.	Secondary winding configuration	Char		

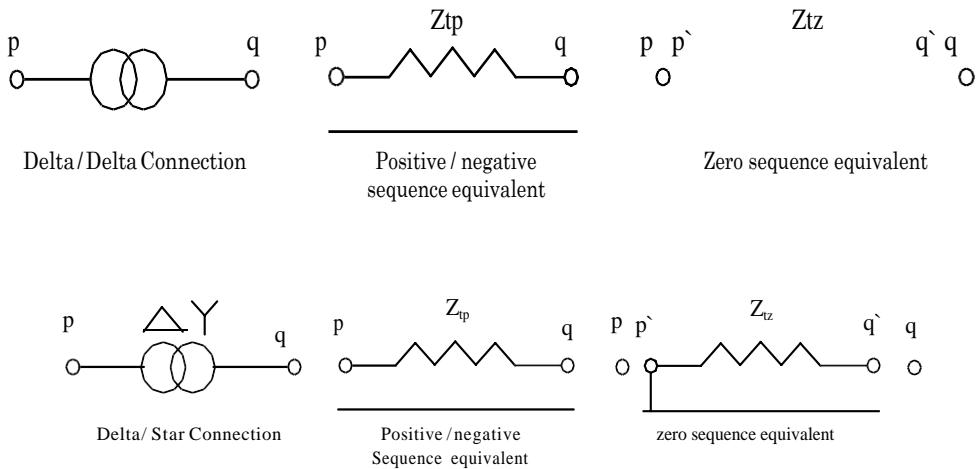
Explanations to entries given in table 3.7 are as follows -

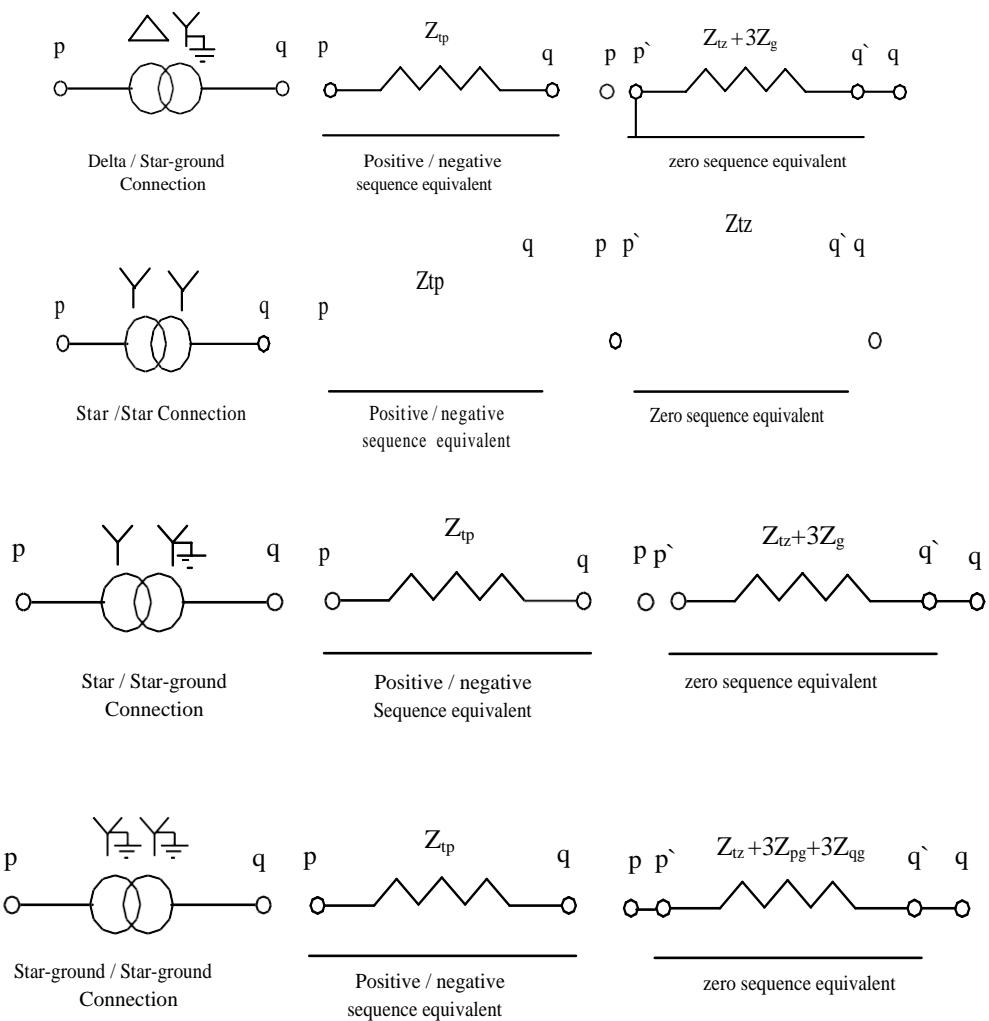
- Connection status is interpreted as
  - 0: Transformer is open on either ends.
  - 1: Transformer is open on from end.
  - 2: Transformer is open on to end.
  - 3: Transformer is closed on either ends.

Values 0 and 3 are of significant. If the status value is 3, then only the transformer is modeled in the analysis. Numbers in parallel is used for information purpose only.

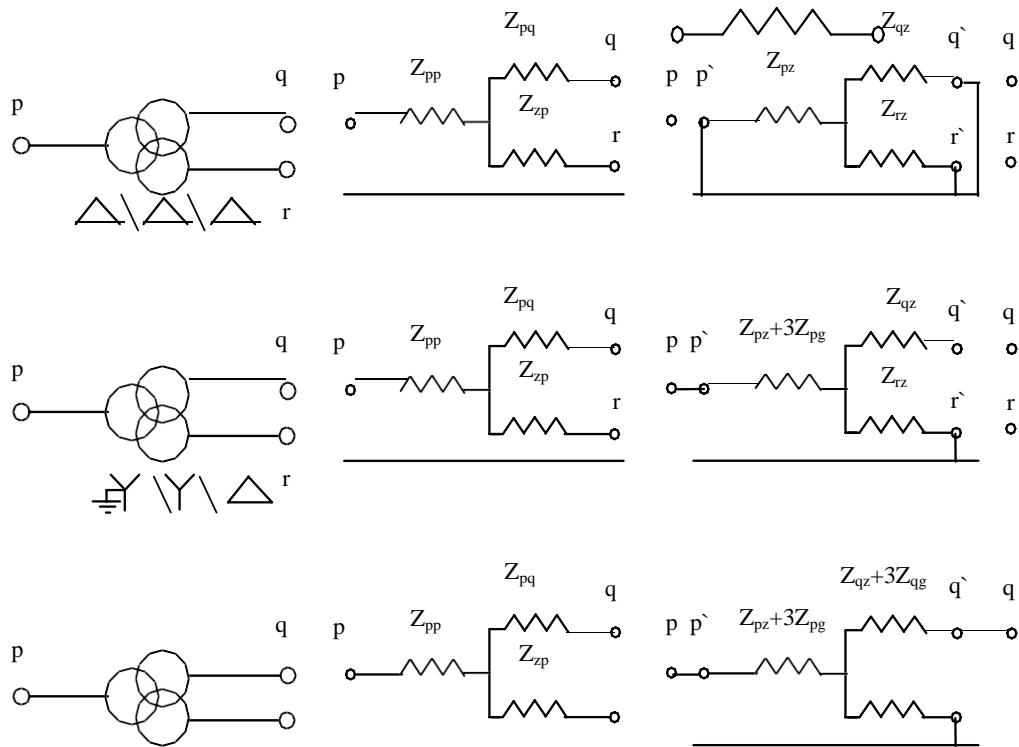
- From bus number and To bus number are the buses on either side to which the transformer is connected. The numbers must be present in the bus data stream.
- Transformer impedance values are in p.u on a common base for the equivalent circuit. i.e., if there are n transformers in parallel, then impedance value per transformer on its own rating is divided by n and then converted to a common base. If the resistance value is zero, effective resistance is computed by multiplying the transformer reactance by the r/x ratio.

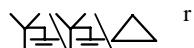
- Nominal tap setting is the tap setting at which the study is to be carried out. It is assumed that the transformer tap is provided on the from bus side. Hence, since the transformer taps are usually provided on the high voltage winding, it is always preferred to specify the from bus side as the high voltage bus number. In case of three-winding transformer, tap is specified from the HT winding to additional node arising because of the equivalent star connection representation. For branches from other two windings, the nominal tap is unity. At unity tap setting, one p.u voltage applied at the from bus produces one p.u voltage at the to bus on no load. In case of phase shifting transformers, the phase shift is represented in polar form. The phase shift magnitude is entered in the nominal tap position, while phase shift angle is provided in the phase shift position. Phase shift angle is in degrees.
- The 10<sup>th</sup> field is phase shift of phase shift transformer.
- The 15<sup>th</sup> field is phase shift due to the winding configuration.
- Zero sequence transformer connection exists in the branch information only if the transformer winding is grounded on either side. Otherwise transformer zero sequence reactance should be of high value (usually 999.99 PU). If the transformer is grounded through any impedance, times the ground impedance value should be added to the zero sequence impedance. Figures 3.4 and 3.5 shows the transformer positive and zero sequence network connections.





**Figure 3.4 - Positive, negative and zero sequence representation of two winding transformer for different connection.**





**Figure 3.5 positive, negative and zero sequence representation of three-phase transformer**

Frequency and voltage dependent tripping of transformer is possible in **POWERTRS**. Relay number to be referred for the transformer from and to side to isolate the transformer is given in columns 11 to 14.

### Stream 8: Transmission Line Data

In this stream of data, transmission line details are given. Lines/Cables are modeled using equivalent circuit as shown in figure 3.6.

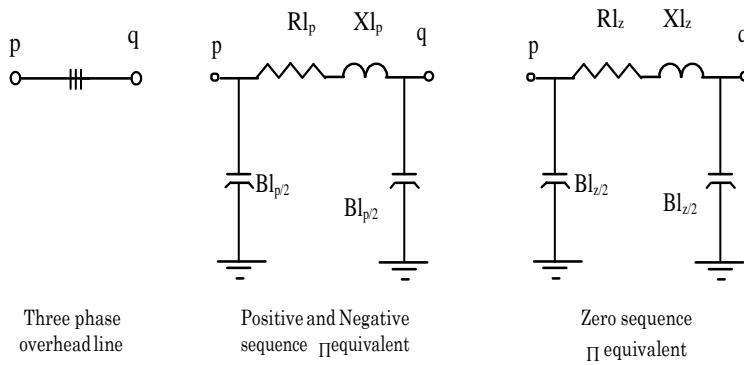


Figure 3.6 - Three phase over head line modeling

Total number of lines of data in this stream is equal to number of transmission lines as given in specification stream. The data that appears in different columns of each line are given in table 3.8.

Table 3.8 : Transmission Line Data				
Col No.	Description	Type	Min	Max
1.	Connection status	int	0	3
2.	Numbers of circuits	int	1	10
3.	From bus number	int	1	9999
4.	To bus number	int	1	9999
5.	Positive sequence resistance in p.u.	float	-1.0e3	1.0e3
6.	Positive sequence reactance in p.u.	float	-1.0e3	1.0e3
7.	Positive sequence susceptance (B/2) in p.u.	float	0.0	1.0e3
8.	Zero sequence resistance in p.u.	float	-1.0e3	1.0e3
9.	Zero sequence reactance in p.u.	float	-1.0e3	1.0e3
10.	Zero sequence susceptance (B/2) in p.u.	float	0.0	1.0e3
11.	From side frequency relay number	int	0	20
12.	From side voltage relay number	int	0	20
13.	To side frequency relay number	int	0	20
14.	To side voltage relay number	int	0	20

Explanations to entries given in table 3.8 are as follows -

- Connection status is interpreted as
  - 0: Line is open on either ends.
  - 1: Line is open on from end.
  - 2: Line is open on to end.
  - 3: Line is closed on either ends.

Values 0 and 3 are of significant. If the status value is 3, then only the line is modeled in the analysis.

- Number of circuits in parallel is used to modify the line impedance in the case of single pole opening.
- From bus number and to bus number are the buses on either side to which the line is connected. The numbers must be present in the bus data stream.
- Line impedance values are in p.u on a common base for the equivalent circuit. i.e., if there are n lines in parallel, then impedance value per line is divided by n and then converted to a common base.
- Frequency and voltage dependent tripping of line is possible in **POWERTRS**. Relay number to be referred for the line from and to side to isolate the line is given in columns 11 to 14.

### Stream 9: Series Reactor and Capacitor Data

In this stream, data for series reactor and capacitor are given. Series reactor and capacitor are modeled as series element consisting of resistance (usually zero or negligible value) in series with inductive or capacitive reactance. Figure 3.7 and 3.8 show the modeling of series inductor and capacitor respectively.

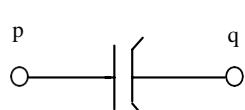


Series reactor

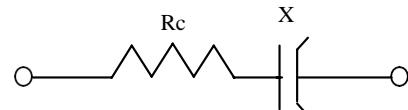


Equivalent circuit

Figure 3.7: Series reactor (inductor) representation



Series capacitor



Equivalent circuit

Figure 3.8: Series capacitor representation

Total number of lines of data in this stream is equal to the sum of number of series reactors and capacitors as given in specification stream. The data that appears in different columns of each line are given in table 3.9.

Table 3.9: Series Reactor/Capacitor Data

Col No.	Description	Type	Min	Max
1.	Connection status	int	0	3
2.	From bus number	int	1	9999
3.	To bus number	int	1	9999
4.	Positive sequence resistance in p.u.	float	0.0	1.0e3
5.	Positive sequence reactance in p.u.	float	1.0e-4	1.0e3
6.	Zero sequence resistance in p.u.	float	0.0	1.0e3
7.	Zero sequence reactance in p.u.	float	0.0	1.0e3
8.	From side frequency relay number	int	0	20
9.	From side voltage relay number	int	0	20
10.	To side frequency relay number	int	0	20
11.	To side voltage relay number	int	0	20

Explanations to entries given in table 3.9 are as follows -

- Connection status is interpreted as
  - 0: Series reactor/capacitor is open on either ends.
  - 1: Series reactor/capacitor is open on from end.
  - 2: Series reactor/capacitor is open on to end.
  - 3: Series reactor/capacitor is closed on either ends.

Values 0 and 3 are of significant. If the status value is 3, then only the reactor/capacitor is modeled in the analysis.

- From bus number and to bus number are the buses on either side to which the reactor/capacitor is connected. The numbers must be present in the bus data stream. Reactor/capacitor impedance values are in p.u on a common base.
- Resistance value of the reactor/capacitor is usually zero or of negligible value.
- Frequency and voltage dependent tripping of series reactor/capacitor is possible in **POWERTRS**. Relay number to be referred for the reactor/capacitor from and to side to isolate the reactor/capacitor is given in columns 8 to 11.

### Stream 10: Circuit Breaker Data

In this stream, data for circuit breakers and isolating switches are given. Switches are modeled as series element consisting of resistance (usually zero or of negligible value) and reactance (small non zero value) whose values are given in system specifications. Figure 3.9 shows the circuit breaker in closed position.

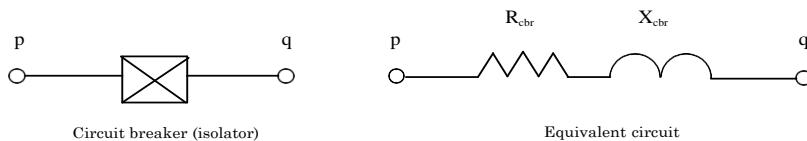


Figure 3.9 - Circuit breaker representation in closed position

Total number of lines of data in this stream is equal to the number of circuit breakers. The data that appears in different columns of each line are given in table 3.10.

Table 3.10: Circuit Breaker Data				
Col No.	Description	Type	Min	Max
1.	Connection status	int	0	3
2.	From bus number	int	1	9999
3.	To bus number	int	1	9999
4.	Frequency relay number	int	0	20
5.	Voltage relay number	int	0	20

Explanations to entries given in table 3.10 are as follows -

- Connection status is interpreted as
  - 0: Circuit breaker is opened.
  - 3: Circuit breaker is closed.
- Frequency and voltage dependent tripping of circuit breaker is possible in **POWERTRS**. Relay number to be referred to isolate the breaker is given in columns 4 and 5.

### Stream 11: Shunt Connection (Admittance) Data

In this stream, data for shunt reactors and capacitors in admittance form is given. Admittance value in pu consists of conductance and susceptance. For shunt inductive reactor, susceptance is negative and for shunt capacitor, susceptance value is positive. Conductance value is zero or of negligible value. Total number of lines of data in this stream is equal to the sum of shunt reactors and capacitors, whose values are given in admittance form. The data that appears in different columns of each line are given in table 3.11.

**Table 3.11 : Shunt Reactor/Capacitor (Admittance form) Data**

Col No.	Description	Type	Min	Max
1.	From bus number	int	1	9999
2.	Positive sequence conductance in p.u.	float	-1.0e-4	1.0e4
3.	Positive sequence susceptance in p.u.	float	-1.0e4	1.0e4
4.	Zero sequence conductance in p.u.	float	-1.0e-4	1.0e4
5.	Zero sequence susceptance in p.u.	float	-1.0e4	1.0e4
6.	Frequency relay number	int	0	20
7.	Voltage relay number	int	0	20

Explanations to entries given in table 3.11 are as follows -

- 'From bus number' is the bus number to which the shunt inductor/capacitor is connected.
- Usually the reactor/capacitor value will be specified in Mvar at the rated voltage. If the rated voltage is the base voltage at the bus, then the magnitude of susceptance value in p.u. is equal to the specified Mvar value in p.u. The sign is positive for capacitive reactor and negative for inductive reactor. Thus the susceptance value of 63 Mvar inductor at 420 kV is -0.57143 p.u on 100 MVA base at 400 kV. Similarly, susceptance value of 50 MVAR capacitor at 420 kV is 0.45351 p.u on 100 MVA base at 400 kV.
- Frequency and voltage dependent tripping of reactor/capacitor is possible in **POWERTRS**. Relay number to be referred to isolate the breaker is given in columns 6 and 7.

### Stream 12: Shunt Connection (Impedance) Data

In this stream, data for shunt reactors and capacitors in impedance form is given. Impedance value in p.u consists of resistance and reactance. For shunt inductive reactor, reactance is positive and for shunt capacitor, reactance value is negative. Resistance is zero or of negligible value. In some particular system studies, shunt element data is readily available in impedance

form. Also, in some studies loads are represented in impedance form. When a network is reduced, all the loads can be lumped at a bus as impedance load. In these cases this stream of data is used. Because of the transformer winding connection, if there results any ground connection for zero sequence network, then that information is also given in this stream. Since corresponding positive sequence network has no ground connection, a high value is given for positive sequence reactance (usually 999.99 p.u.).

Total number of lines of data in this stream is equal to the shunt impedance number as given in specification stream. The data that appears in different columns of each line are given in table 3.12.

Table 3.12 : Shunt Impedance Data				
Col No.	Description	Type	Min	Max
1.	From bus number	int	1	9999
2.	Positive sequence resistance in p.u.	float	0.00	1.0e3
3.	Positive sequence reactance in p.u.	float	-1.0e3	1.0e4
4.	Zero sequence resistance in p.u.	float	0.00	1.0e3
5.	Zero sequence reactance in p.u.	float	-1.0e3	1.0e4

Explanations to entries given in table 3.12 are as follows -

- 'From bus number' is the bus number to which the shunt impedance is connected.
- If the load power at the nominal voltage (base voltage) is known, then the impedance value in p.u is computed as the reciprocal of the conjugate of the complex power in p.u. Thus the p.u resistance and reactance values of 80 MW and 60 Mvar load are 0.8 and 0.6 respectively on 100 MVA base.
- If the transformer is delta connected on primary and star grounded on secondary, then zero sequence shunt connection exists from the transformer secondary bus to ground. Also if the transformer is star grounded on primary and delta connected on secondary, then zero sequence shunt connection exists from the transformer primary to ground. In either case positive sequence reactance value is high i.e., approximately 999.0 p.u.

### Stream 13: Filter Data

In this stream of data, filter details are given. For each filter, the bus numbers to which the filter is connected and the number of branch elements (Resistor, Inductor, and Capacitor) that constitute the filter are given followed by the actual filter data. Hence total number of lines of data in this stream is equal to sum of number of filters as given in the specification stream and sum of number of filter branches of each filter. The data that appears in different columns of each line for a filter branch are given in table 3.13.

<b>Table 3.13: Filter Data</b>				
<b>Col No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
1.	Filter branch number	int	0	20
2.	From node	int	0	9999
3.	To node	int	0	9999
4.	Filter element type	int	1	3
5.	Element value	float	0.0	1.0e4

Explanation to entries in the table 3.13 is as follows -

- Branch number is the serial number of the filter branch. Total number of branches per filter should be less than 20.
- Filter nodes are numbered in order considering the reference node (ground) as 0 and the bus to which the filter is connected as 1. From and to filter nodes refer to the node numbers of the filter, between which the basic filter element is connected.
- Filter element type is interpreted as -
  1. Resistor, element value unit is in Ohm.
  2. Inductor, element value unit is in Henry.
  3. Capacitor, element value unit is in Farad.

In the transient stability study, the equivalent shunt admittance in p.u, from the filter bus to the ground is computed at the specified system frequency, bus voltage and base MVA. If a filter at bus say 8, consists of resistor, inductor and capacitor connected as shown in figure 3.10, then the data appearing for the filter is as follows -

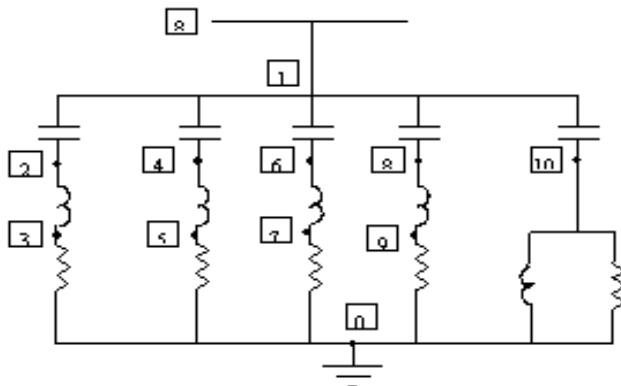


Figure 3.10: Example of a Filter Data

Bus = 8		Filter Branch Elements = 15		
Branch	From Node	To Node	Branch Element Type	Active Value
1	1	2	3	000.417e-6
2	2	3	2	000.974
3	3	0	1	037.000
4	1	4	3	000.417e-6
5	4	5	2	000.497
6	5	0	1	026.600
7	1	6	3	000.417e-6
8	6	7	2	000.201
9	7	0	1	016.900
10	1	8	3	000.417e-6
11	8	9	2	000.145
12	9	0	1	014.400
13	1	10	3	000.417e-6
14	10	0	2	0.085
15	10	0	1	452.00

Only values need to be entered

### Stream 14: Load Data

In this stream of data, load details are given. Total number of lines of data in this stream is equal to number of loads as given in specification stream. The data that appears in different columns of each line are given in table 3.14.

Table 3.14: Load Data				
Col No.	Description	Type	Min	Max
1.	Load bus number	Int	1	9999
2.	Real power load in MW	Float	-1.0e6	1.0e6
3.	Reactive power load in Mvar	Float	-1.0e6	1.0e6
4.	Compensating Mvar	Float	-1.0e6	1.0e6
5.	Load characteristic number	int	0	20
6.	Load frequency relay number	int	0	20
7.	Load voltage relay number	int	0	20

Explanations to entries given in table 3.14 are as follows -

- Load bus number is the bus number to which the load is connected. This number should be provided in the bus data stream.
- Real power and reactive power load values are the scheduled values at the scheduled frequency and nominal voltage. Nominal voltage is equal to the base voltage at the bus. Scheduled frequency is read under system specification stream. This is normally either 50 Hz or 60 Hz.
- Loads are modeled as constant power load or constant current load or constant impedance load or as a combination of all, including the frequency dependency. Modeling of the load is determined by the load characteristic number. If the load characteristic number is zero, then the loads are modeled as constant power type. At any bus i, the expressions for loads are given by

#### For Load char. Number Less than or Equal to 50

$$P_L^i = P_{LO}^i (1 + cp_f^i \Delta f) (cp_p^i + cp_i^i V^i + cp_z^i V^i V^i)$$

$$Q_L^i = Q_{LO}^i (1 + cq_f^i \Delta f) (cq_p^i + cq_i^i V^i + cq_z^i V^i V^i)$$

For Const. P Load - Cp = 1, Ci = 0, Cz = 0

For Const. I Load - Cp = 0, Ci = 1, Cz = 0

For Const. Z Load - Cp = 0, Ci = 0, Cz = 1

#### For Load char. Number greater than 50

$$P_L^i = P_{LO}^i (1 + cp_f^i * \Delta f) (cp_p^i (V_i) + cp_z^i)$$

$$Q_L^i = Q_{LO}^i (1 + cq_f^i * \Delta f) (cq_p^i (V_i) + cq_z^i)$$

For Const. P Load -  $C_p = 1$ ,  $C_i = 0$ ,  $C_z = \text{Not Used}$

For Const. I Load -  $C_p = 1$ ,  $C_i = 1$ ,  $C_z = \text{Not Used}$

For Const. Z Load -  $C_p = 1$ ,  $C_i = 2$ ,  $C_z = \text{Not Used}$

where,

$P_L^i$  : Actual real power at the bus i in pu.

$$f = f - f_0$$

$P_{LO}^i$  : Scheduled real power at the bus i in pu.

$cp_f^i$  : Coeff. of frequency dependence for P at bus i

$cp_p^i$  : Constant power fraction for P at bus i.

$cp_i^i$  : Constant current fraction for P at bus i.

$cp_z^i$  : Constant impedance fraction for P at bus i.

$V^i$  : Magnitude of the voltage at bus i in pu.

$$\text{NOTE : } \sum (cp_p^i + cp_i^i + cp_z^i) = 1.0$$

$Q_L^i$  : Actual reactive power at the bus i in pu.

$Q_{LO}^i$  : Scheduled reactive power at the bus i in pu.

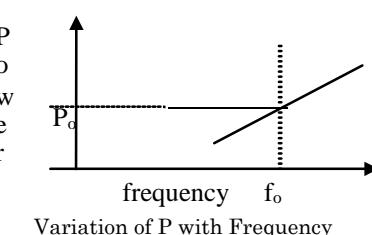
$cq_f^i$  : Coeff. of frequency dependence for Q at bus i.

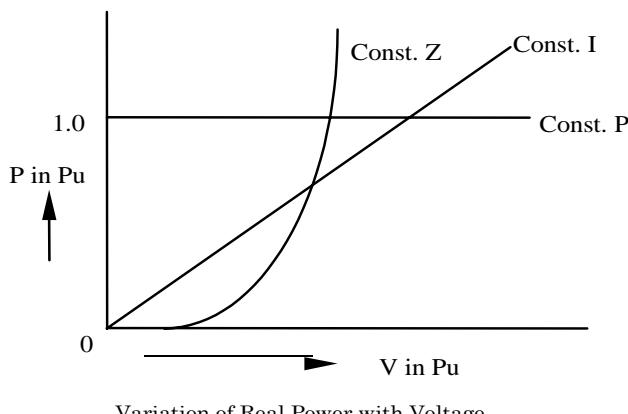
$cq_p^i$  : Constant power fraction for Q at bus i.

$cq_i^i$  : Constant current fraction for Q at bus i.

$cq_z^i$  : Constant impedance fraction for Q at bus i.

$$\sum (cq_p^i + cq_i^i + cq_z^i) = 1.0$$





where,

$c_{pf} = 2.5$ ,  $c_{pp} = 0.5$ ,  $c_{pi} = 0.3$ ,  $c_{pz} = 0.2$ , implies real power changes by 5% for 1 Hz. change in frequency, 50% of the load is constant power type, 30% of the load is constant current type and 20% of load is constant impedance type. If the voltage at a bus goes below the specified value, then the load model for that bus is switched from the given model to constant impedance model as explained in the "system specification stream".

- Compensating Mvar is the fixed compensation provided at the bus. It is assumed that irrespective of the bus voltage, compensating Mvar remains constant. If at a bus fixed capacitor or inductor is present, it is advisable to provide the compensation data as shunt impedance/admittance at the bus.
- Load characteristic number is the number given in the load characteristic data to be referred for the modeling of the load at the bus. Load characteristic is detailed under "load characteristic stream".
- Frequency and voltage dependent tripping of loads is possible in **POWERTRS**. Relay number to be referred to isolate the breaker is given in columns 4 and 5.

---

### Stream 15: Load Characteristic Data

In this stream of data, load characteristic details are given. Total number of lines of data in this stream is equal to number of load characteristics as given in specification stream. The data that appears in different columns of each line are given in table 3.15.

**Table 3.15: Load Characteristic Data**

<b>Col.No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
1.	Load characteristic number	int	1	9999
2.	Real power - constant power factor	float	0.0	1.0
3.	Real power - constant current factor	float	1.0	10.0
4.	Real power - constant impedance factor	float	0.0	1.0
5.	Reactive power - constant power factor	float	0.0	1.0
6.	Reactive power - constant current factor	float	0.0	1.0
7.	Reactive power - constant impedance factor	float	0.0	1.0
8.	Real power - frequency factor	float	0	20
9.	Reactive power - frequency factor	float	0	20

Explanations to entries given in table 3.15 are as follows -

- Loads are modeled as explained in load data. The Load characteristic number given here should match the one given under load data.
- Frequency factor of 0.05 implies the load changes by 5 percent for 1 p.u. change in frequency.

---

### **Stream 16: Island Data**

When base case load flow is done taking the generator and load regulation characteristics, the solution obtained may not be at the nominal system frequency for flat tie line power control. Hence **POWERTRS** accepts frequency of each island as additional input. This stream consists of two lines of data. In first line the total number of islands in the solved base case system is given. In the subsequent line, the frequency of each island is given. Fields are of float type and are separated by one or more blanks.

---

### **Stream 17: Machine Data**

In this stream of data, Machine details are given. Total number of lines of data in this stream is equal to the sum of number of synchronous and asynchronous machines as given under system specification field. For each synchronous machine (generator) 22 fields are read. Order of data input for each generator is given in table 3.16.

Table 3.16 : Generator Parameter Data

SI No.	Description	Type	Min	Max
1.	Generator bus number	int	1	9999
2.	Type of modeling	int	1	3
3.	Number of units	int	1	20
4.	Machine MVA rating	Float	0.0	1.0e6
5.	Inertia constant (H)	Float	1.0e-3	1.0e4
6.	Steady state resistance in p.u ( $r_a$ )	Float	0.0	1.0e2
7.	Direct axis transient reactance in p.u ( $x_d'$ )	Float	1.0e-4	1.0e2
8.	Quadrature axis transient reactance in p.u ( $x_q'$ )	Float	1.0e-4	1.0e2
9.	Steady state negative sequence reactance in p.u ( $x_n$ )	Float	1.0e-4	1.0e2
10.	Steady state zero sequence resistance in p.u ( $R_0$ )	Float	1.0e-4	1.0e2
11.	Steady state zero sequence reactance in p.u ( $x_0$ )	Float	1.0e-4	1.0e2
12.	Damping factor (df)	Float	0.0	1.0e2
13.	Steady state direct axis reactance in p.u ( $x_d$ )	Float	1.0e-4	1.0e2
14.	Steady state quadrature axis reactance in p.u ( $x_q$ )	Float	1.0e-4	1.0e2
15.	Potier reactance in p.u ( $x_p$ )	Float	1.0e-4	1.0e2
16.	Sub-transient direct axis reactance in p.u ( $x_d''$ )	Float	1.0e-4	1.0e2
17.	Sub-transient quadrature axis reactance in p.u ( $x_q''$ )	Float	1.0e-4	1.0e3
18.	Transient direct axis open circuit time constant in seconds ( $t_{d0}'$ )	Float	1.0e-4	1.0e3
	Transient quadrature axis open circuit	Float	1.0e-4	1.0e3
19.	time constant in seconds ( $t_{q0}'$ )			
20.	Sub-transient direct axis open circuit time constant in seconds ( $t_{d0}''$ )	float	1.0e-4	1.0e3
21.	Sub-transient quadrature axis open circuit time constant in seconds ( $t_{q0}''$ )	float	1.0e-4	1.0e3
22.	Frequency relay number	int	0	20
23.	Voltage relay number	int	0	20

Explanation for the entries in the table 3.16 is as follows -

- Generator bus number is the bus number to which the generator is connected. This number should match with the bus number present in the 'Generator Bus Data' stream.
- Type of modeling is interpreted as -
  1. Simple representation of voltage behind transient direct axis reactance.
  2. Representation with transient reactance and time constants.
  3. Representation with transient and sub-transient reactances and time constants.
- The machine data used for modeling depends on the type of model. But irrespective of the model, all the data values should be given as input. But the values not considered in the model are ignored.
- All the machine parameters are given in p.u on the machine rating for individual machines. Machine rating in MVA and number of units are used to convert the parameters to a common base.
- Since the machine parameters are per machine, number of units is read to convert the machine parameters to a common base.

- If the machine parameters are already available in common base for the equivalent system (considering number of machines in parallel), then machine rating is given as common base MVA and number of units in parallel as 1.
- Frequency and voltage dependent tripping of generator is possible in **POWERTRS**. Under frequency and under voltage relay numbers to be referred to isolate the generator is given in columns 21 and 22 respectively.

For asynchronous motors (induction motors), 14 fields are read for each motor. Figure 3.11 gives the modeling of Induction motor.

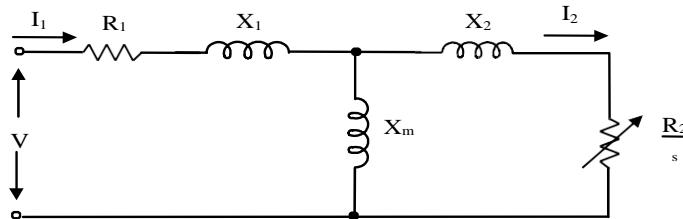


Figure 3.11 - Equivalent Circuit Diagram of Induction Motor

Table 3.17 gives the fields read for each induction motor.

Table 3.17 : Induction Motor Parameter Data

SI No.	Description	Type	Min	Max
1.	Motor bus number	int	1	9999
2.	Type of modeling	int	4	6
3.	Number of units	int	0	999
4.	Motor MVA rating	float	1.0e-3	1.0e6
5.	Inertia constant (H- MJ/ MVA) in seconds	float	1.0e-3	1.0e4
6.	Stator resistance in pu. ( $r_1$ )	float	0.0	1.0e2
7.	Stator reactance in pu ( $x_1$ )	float	1.0e-4	1.0e2
8.	Rotor resistance in pu ( $r_2$ ) at Slip = 1	float	1.0e-4	1.0e2
9.	Rotor reactance in pu ( $x_2$ ) at Slip = 1	float	1.0e-4	1.0e2
10.	Rotor resistance in pu ( $r_2$ ) at Slip = 0	float	1.0e-4	1.0e2
11.	Rotor reactance in pu ( $x_2$ ) at Slip = 0	float	1.0e-4	1.0e2
12.	Magnetizing reactance in pu ( $x_m$ )	float	1.0e-4	1.0e3
13.	Initial motor slip (s) in pu	float	0.0	1.0
14.	C1	float	0.0	1.0
15.	C2	float	0.0	1.0
16.	C3	float	0.0	1.0
17.	Motor rated power in MW	float	1.0e-4	1.0e2
18.	Mode	int	0	2
19.	Slip set (tap-cutoff-slip for sync. Motor)	float	0.10000	1.0
20.	Time Cut-off	float	0.0	1.0e2
21.	Auto tap	float	0.0	1.000

22.	Resistance-Start	float	1.0e-4	1.0e2
23.	Resistance-end	float	1.0e-4	1.0e2
24.	Frequency relay number	int	0	20
25.	Voltage relay number	int	0	20

Explanations for the entries in the table 3.17 are as follows -

- Motor bus number is the bus number to which the motor is connected.
- Model type is usually 4 for induction motor. Type 1 to 3 is reserved for generators. Model type 10 refers to Characteristic modeling of motor.

For Model type 4 –

- Motor parameters should be given in pu on a common base, selected for the study.
- During Motor starting on load the torque of the motor is given by,

$$T = T_c ( C_1 + C_2 N + C_3 N^2 )$$

where,

$T_c$  : No-load torque,

$C_1$  : Constant independent of Speed,

$C_2$  : Constant proportional to speed and

$C_3$  : Constant proportional to square of the speed.

Sum of these constants is  $1(C_1 + C_2 + C_3 = 1.0)$ .

If the sum of these constants is greater than 1.0, then the load modeling is considered from speed vs torque characteristics.

- If the initial slip is 1.0, motor is at stand still and the study is equivalent to starting of the motor. If the motor is already running, then corresponding slip value should be given.
- Mode is interpreted as  
0 – Auto-transformer /DOL start  
1 – Resistance start, the starting resistance and the ending resistance should be given  
2 – Star delta start  
• Slip set is the steady state slip of the motor in pu.  
• Time cut-off in seconds  
• The auto tap implies the auto transformer tap setting during starting in pu.  
• Frequency and voltage dependent tripping of motor is possible in **POWERTRS**. Under frequency and under voltage relay numbers to be referred to isolate the motor are given in columns 24 and 25 respectively.

In case of synchronous motor starting-

- Synchronous motor is considered as a generator of model type 3 with negative MW power. In initial stages of starting the motor is considered as induction motor and at the slip equal to tap-cutoff-slip the modeling is considered as synchronous motor.

- The input data is same as generator input data with the model type 6 in case of auto-transformer starting otherwise detailed model of generator (type 3) is to be considered. In addition to this data additional motor specific data has to be given. The sample form at is as follows.

Motor bus no	:	15	Bus name	:	BUS15
Model type	:	6	units	:	1
MVA	:	3.75	H	:	7.73000
Ra	:	0.00372	xd'	:	0.01013
xq'	:	0.02743	xn	:	0.16087
x0	:	2.24962	df	:	1.00000
xd	:	1.00000	xq	:	0.00000
xp	:	0.00000	xd"	:	0.00000
xq"	:	0.10000	tdo'	:	1.00000
tqo'	:	0.00000	tdo"	:	0.00000
tqo"	:	1.00000	Frequency Relay No	:	5
Voltage Relay No	:	0	c1	:	1.00000
c2	:	0.00000	c3	:	0.00000
p	:	1.00000	slip	:	0.00000
tap-cutoff-slip	:	0.06000	auto-tap	:	0.02400
Vfld	:	0.00000	rf-ext	:	0.0000

Here Vfld and rf-ext are not used at present.

If the sum of the constants C1+C2+C3 is greater than 1.0, then the load modeling is considered from speed vs torque characteristics. The motor data from column 1 to 25 is read. This is followed by number of characteristic points. For each point the Table 3.17 – a gives the fields read

**Table 3.17-a : Induction Motor Load Characteristic data**

SI No.	Description	Type	Min	Max
1.	Speed in pu	float	.1	1
2.	Power in pu	float	0.0	6

For Model Type 10 -

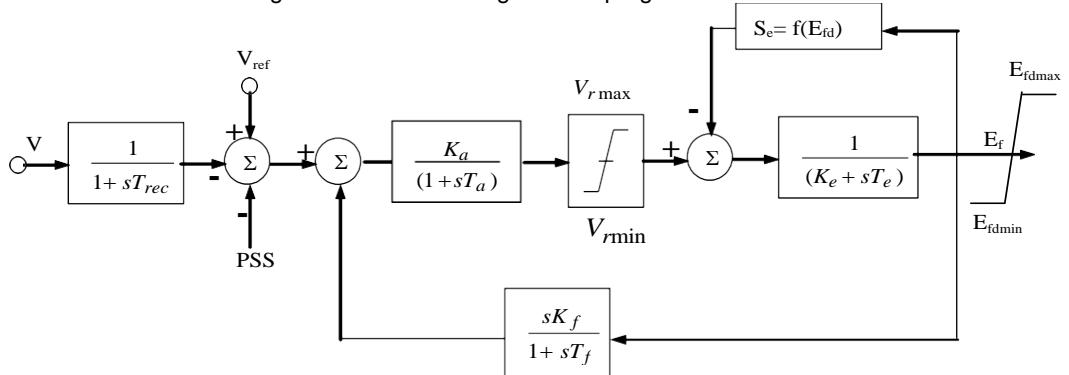
Column number 1 to 4 are read. This is followed by number of characteristic data. Table 3.17-b gives the fields read for each characteristic data. Number of lines of data is equal to number of characteristic data.

**Table 3.17-b : Induction Motor Characteristic data**

SI No.	Description	Type	Min	Max
3.	Time in seconds	float	1	9999
4.	Real power in pu	float	0	6
5.	Reactive power in pu	float	0	6

### Stream 18: Voltage Regulator Data

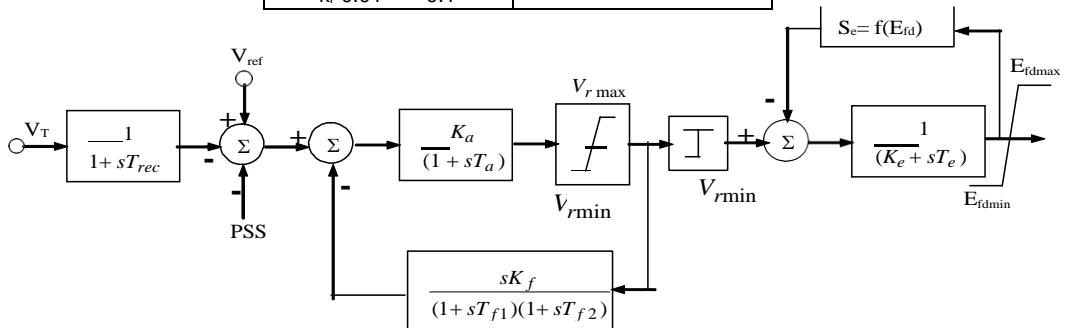
In this stream, voltage regulator details are given. Figures 3.11 to 3.16 give different IEEE types of regulators that are modeled in **POWERTRS**. Voltage regulators given under this stream should not include the regulators realized using the free programmable blocks.



**Figure 3.11 - Excitation System Type 1**

#### Typical Parameters

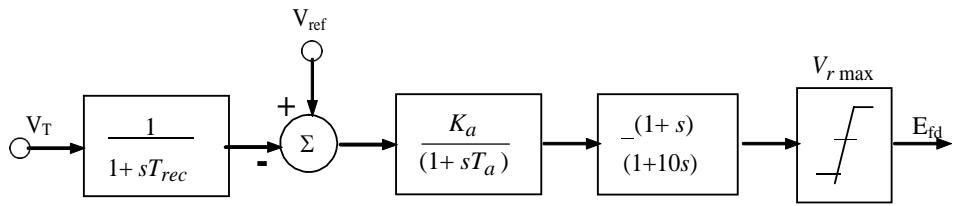
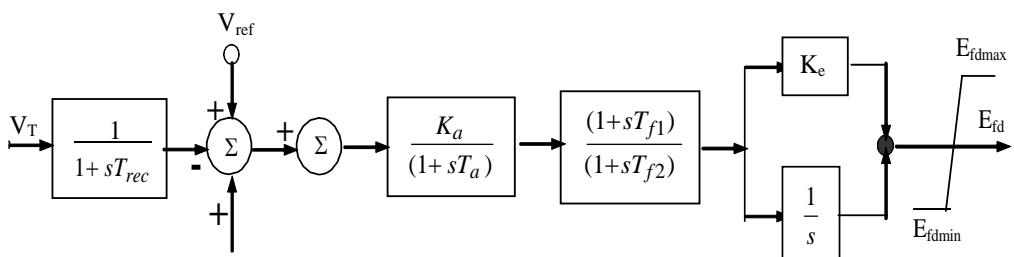
Parameter	Value	Parameter	Value
T <sub>rec</sub>	0.01 -- 0.10	T <sub>a</sub>	0.025 -- 0.2
T <sub>s</sub> T <sub>c</sub>	0.5 -- 1.0	T <sub>f</sub>	0.5 -- 1.0
K <sub>a</sub>	25 -- 200	K <sub>e</sub>	-0.5 -- 1.0
k <sub>f</sub>	0.01 -- 0.1		



**Figure 3.12- Excitation System Type - 2**

**Typical Parameters**

Parameter Value	Parameter Value
$T_{rec}$ 0.01 --- 0.05	$T_a$ 0.01 --- 0.05
$T_e$ 0.5 --- 1.0	$T_{f1} \geq 1.0$
$T_{f2} \approx 0.1$	$K_a$ 50--200-400-600
$K_e \approx 1.0$	$K_f$ 0.01 - 0.05

**Figure 3.13- Excitation System Type - 3****Figure 3.14-Excitation System Type-4**

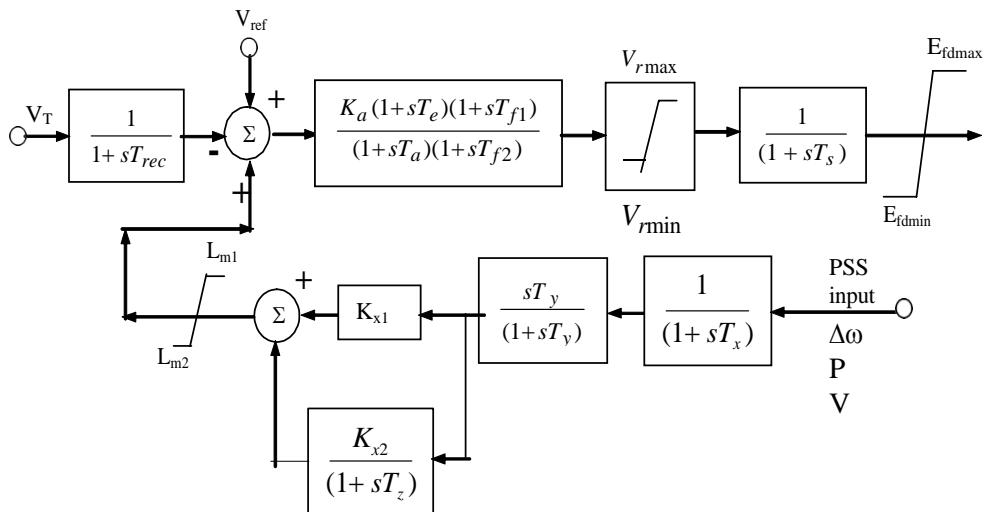


Figure 3.15 - Excitation System Type-5

**Typical Parameters**

Parameter	Value	Parameter	Value
$T_{rec}$	0.01 -- 0.025	$T_s$	0.025
$T_e \approx 1.0$		$T_{f1} \approx 0.06$	
$T_a$	40.0	$T_{f2} \approx 0.024$	
$k_a \approx 200.0$			

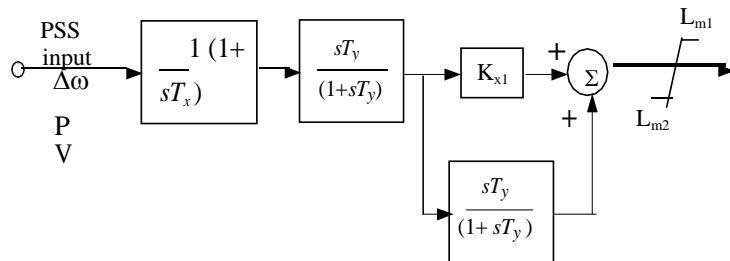


Figure 3.16 - Power System Stabilizer Type-1

For each regulator 18 fields are read. Data appearing under different fields for each regulator is given in table 3.18.

Table 3.18 : Voltage Regulator Details				
SI No.	Description	Type	Min	Max
1.	Bus number	int	1	9999
2.	Type of AVR	int	0	10
3.	PSS status	int	0	10
4.	Gain of amplifier ( $K_a$ )	float	0.0	100.0
5.	Time constant of amplifier ( $T_a$ )	float	0.0	10.0
6.	Gain of exciter ( $K_e$ )	float	-100.0	100.0
7.	Exciter time constant ( $T_e$ )	float	0.0	10.0
8.	( $V_k f$ )	float	0.0	10.0
9.	( $T_{f1}$ )	float	0.0	10.0
10.	( $T_{f2}$ )	float	0.0	100.0
11.	Input filter time constant ( $T_{rec}$ )	float	0.0	10.0
12.	( $V_{ls}$ )	float	0.0	100.0
13.	Saturation function value ( $V_{se1}$ ) at 0.75 times $E_{fdmax}$	float	0.0	10.0
14.	Saturation function value ( $V_{se2}$ ) at $E_{fdmax}$ ,	float	0.0	10.0
15.	Maximum regulator output ( $V_{max}$ )	float	0.0	10.0
16.	Minimum regulator output ( $V_{min}$ )	float	-10.0	0.0
17.	Maximum excitor output ( $E_{fdmax}$ )	float	0.0	10.0
18.	Minimum excitor output ( $E_{fdmin}$ )	float	-10.0	0.0

Explanations for the entries in table 3.18 are as follows -

- Figures 3.11 to 3.16 can be referred to know the significance of each value.
- Bus number refers to the generator bus number to which the regulator is associated.
- Type field is interpreted as 1 for IEEE type 1, ..., 5 for IEEE type 5.
- Even though in some block schematics, values indicated are not present, 18 fields should be given for each regulator. Gain value is given as 0.0 and time constant as 99.9 whenever the block or constant is not referred in the figure.
- PSS (power system stabilizer) status is interpreted as -
  - 0 : PSS is not present.
  - 1 : PSS is present.

If the PSS is present, then 7 additional fields are read for each PSS. Referring to the PSS figure 3.16, the float fields read in order are  $K_{x1}$ ,  $K_{x2}$ ,  $T_x$ ,  $T_y$ ,  $T_z$ ,  $Im_1$ , and  $Im_2$ . All the fields are separated by one or more blanks.

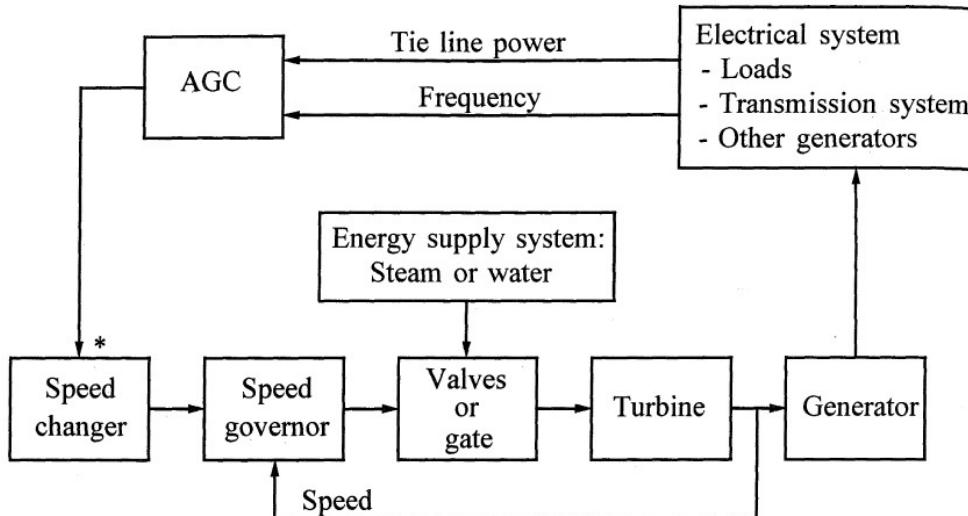
### Stream 19: Governor Data

In this stream of data, governor details are given. Figures 3.17 and 3.18 give modeling of governor for steam and hydro turbines respectively.

#### Speed Governor Systems:

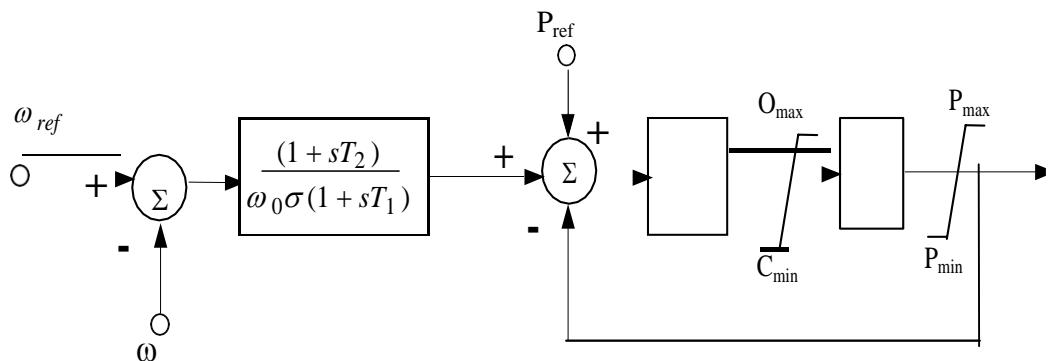
The prime source of electrical energy supplied by utilities is the kinetic energy of water and the thermal energy derived from fossil fuels and nuclear fission. The prime movers convert these sources of energy into mechanical energy that is in turn converted to electrical energy by synchronous generators. The prime movers governing systems provide a means of controlling power and frequency -a function commonly referred to as load - frequency control or automatic - generation control (AGC).

During increase or decrease of load, the governor system provides a means for controlling power and frequency.



\* AGC applied only to selected units

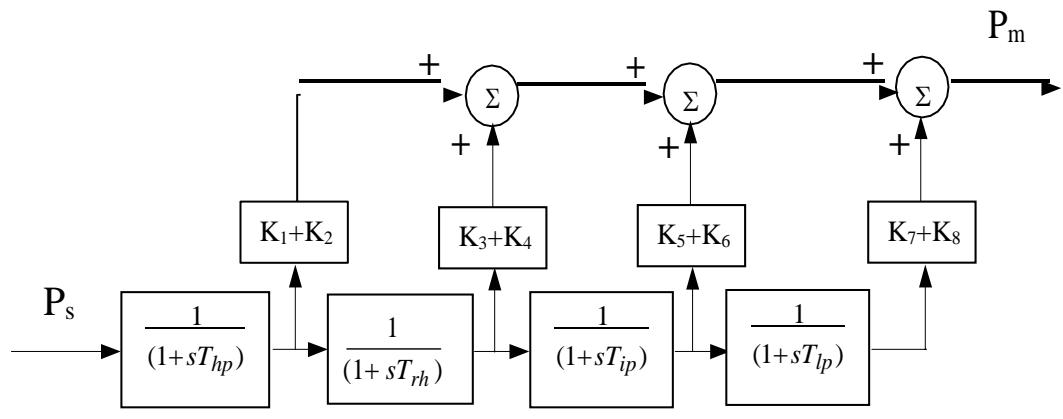
**Figure 3.17: Speed Governing System**



**Figure 3.18 (a) : Block schematic of Steam Governor System**

#### Typical Parameters

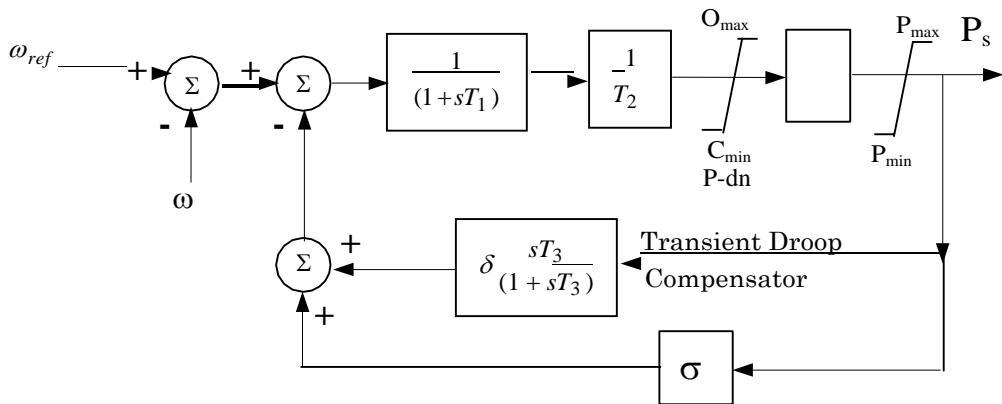
Parameter	Value	Parameter	Value
$\sigma$	0.04 - 0.05	$P_{max}$	1.00
$T_1$	0.10	$P_{min}$	0.00
$T_2$	0.03	$O_{max}$	0.10
$T_3$	0.40	$C_{min}$	-1.00



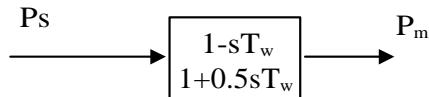
**Figure 3.18 (b) : Turbine System Model for Steam Turbines (Type - 1) Governor**

#### Typical Parameters

Parameter	Value	Parameter	Value	Parameter	Value
\$T_{hp}\$	0.26	\$k_1\$	0.2760	\$k_1 + k_2\$	VHP
\$T_{rh}\$	10.0	\$k_3\$	0.324	\$k_3 + k_4\$	HP
\$T_{ip}\$	0.5	\$k_5\$	0.4	\$k_5 + k_6\$	IP
\$T_{lp}\$	99.9	\$k_7\$	0.0	\$k_7 + k_8\$	LP



**Figure 3.19 (a) : Hydro Speed Governing System (Type - 2)**



**Figure 3.19 (b): Block Schematic of Hydro Turbine**

#### Typical Parameters

Parameter	Value	Parameter	Value
$\delta$	0.36	$P_{max}$	1.10
$\sigma$	0.04	$P_{min}$	0.00
$T_1$	0.05	$P_{up}$	0.10
$T_2$	0.20	$P_{down}$	-1.00
$T_3$	5.00	$T_w$	1.00

For steam turbine unit, 19 fields are read. Data appearing under different columns are given in table 3.19.

**Table 3.19 : Steam turbine - governor Data**

<b>SI No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
1.	Bus number	int	0	9999
2.	Governor type	int	0	10
3.	Number of units	int	1	10
4.	Governor droop	float	0.0	1.0
5.	Maximum power output of governor in pu	float	0.0	10.0
6.	Minimum power output of governor in pu	float	0.0	10.0

**Table 3.19 : Steam turbine - governor Data (Continued)**

<b>SI No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
7.	Power up in pu	float	0.0	10.0
8.	Power down in pu	float	-10.0	10.0
9.	Gain constants of turbine ( $K_1 + K_2$ )	float	0.0	10.0
10.	Gain constants of turbine ( $K_3 + K_4$ )	float	0.0	10.0
11.	Gain constants of turbine ( $K_5 + K_6$ )	float	0.0	10.0
12.	Gain constants of turbine ( $K_7 + K_8$ )	float	0.0	10.0
13.	Governor time constants $T_1$	float	0.0	1.0e3
14.	Governor time constants $T_2$	float	0.0	1.0e3
15.	Governor time constants $T_3$	float	0.0	1.0e3
16.	High pressure turbine time constant $T_{hp}$	float	0.0	1.0e3
17.	Reheat time constant $T_{rh}$	float	0.0	1.0e3
18.	Intermediate pressure turbine time constant $T_{ip}$	float	0.0	1.0e3
19.	Low pressure turbine time constant $T_{lp}$	float	0.0	1.0e3

Explanations for the entries in table 3.19 are as follows -

- Bus number is the generator bus to which the governor is connected.
- Governor type field should be 1 for steam turbine governor model.
- Number of units refers to number of generating units in parallel.
- Governor droop should be given as 0.04 if the droop is 4 percent. The droop is for per machine on its rating.
- Maximum and minimum power outputs of turbine are in p.u on machine rating.
- Rate of opening and closing of valve is per machine and the unit is p.u per second.
- Sum of gain constants  $K_1$  to  $K_8$  should be unity.

For hydro turbine unit, 13 fields are read. Data appearing under different columns are given in table 3.20.

**Table 3.20 : Hydro turbine - governor Data**

<b>SI No.</b>	<b>Description</b>	<b>Type</b>	<b>Min</b>	<b>Max</b>
1.	Bus number	int	0	9999
2.	Governor type	int	0	10

4.	Governor droop	float	0.0	1.0
5.	Transient droop	float	0.0	1.0
6.	Maximum power output of governor in pu	float	0.0	10.0
7.	Minimum power output of governor in pu	float	0.0	10.0
8.	Rate of valve opening in pu power/sec	float	0.0	10.0
9.	Rate of valve closing in pu power/sec	float	-10.0	10.0
10.	Governor time constants $T_1$	float	1.0e-4	1.0e3
11.	Governor time constants $T_2$	float	1.0e-4	1.0e3
12.	Governor time constants $T_3$	float	1.0e-4	1.0e3
13.	Water time constant $T_w$	float	1.0e-4	1.0e3

Explanations for the entries in table 3.20 are as follows –

- Bus number is the generator bus to which the governor is connected.
- Governor type field should be 2 for hydro turbine governor model.
- Number of units refers to number of generating units in parallel.
- Governor droop should be given as 0.04 if the droop is 4 percent. The droop is for per machine on its rating. Hydro governor systems have both permanent droop setting and transient droop setting.
- Maximum and minimum power outputs of turbine are in p.u on machine rating.
- Rate of opening and closing of valve is per machine and the unit is p.u per second.

### Stream 20: Wind Turbine Generator Data

In this stream of data, wind generator details are given. There are basically four IEEE standard models. They are as shown below.

Wind Turbine Model	Description
WT1	Squirrel cage induction generator type wind turbine
WT2	Variable rotor resistance induction generator type wind turbine (WT2)
WT3	Doubly fed induction generator type wind turbine (WT3) generally called as DFIG type model
WT4	Full converter type wind turbine (WT4)

WT1 Model: The mechanical power output of the wind turbine will come from pseudo governor model. The mechanical power output is given as input to the squirrel cage induction machine model. The electrical machine model will compute the real, reactive power generation, operating slip and other steady state operating parameters. Control flow block diagram is given below.

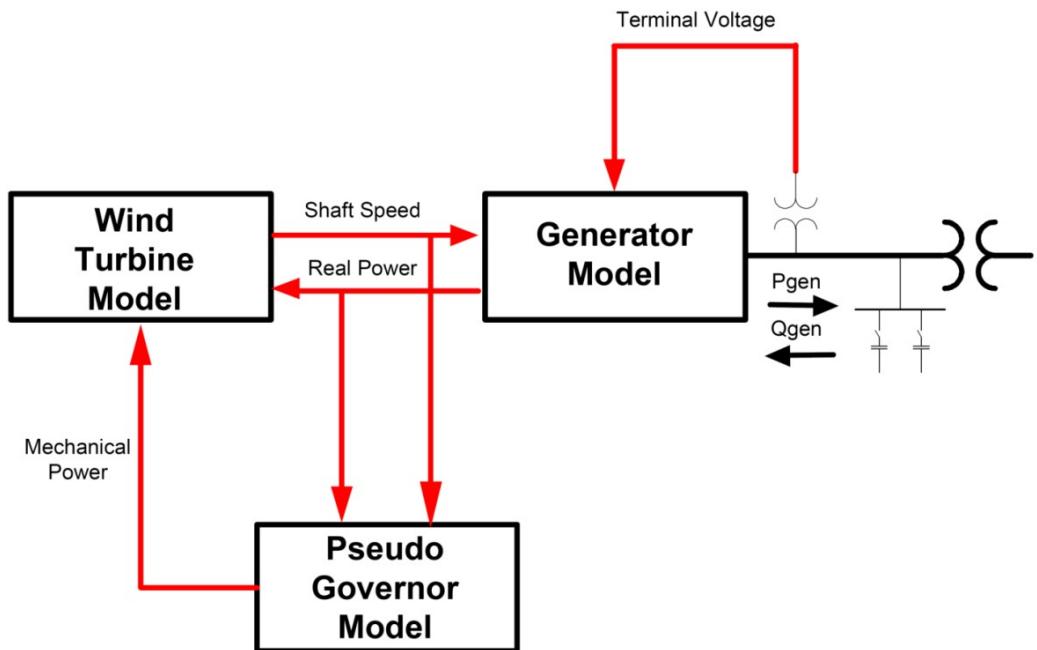


Figure 3.17: WT1 type Wind Turbine

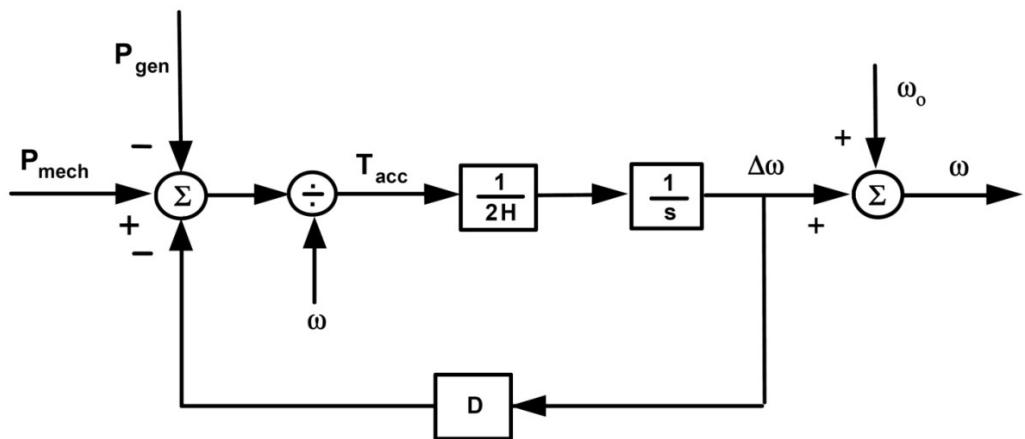


Figure 3.17: One mass model drive train system

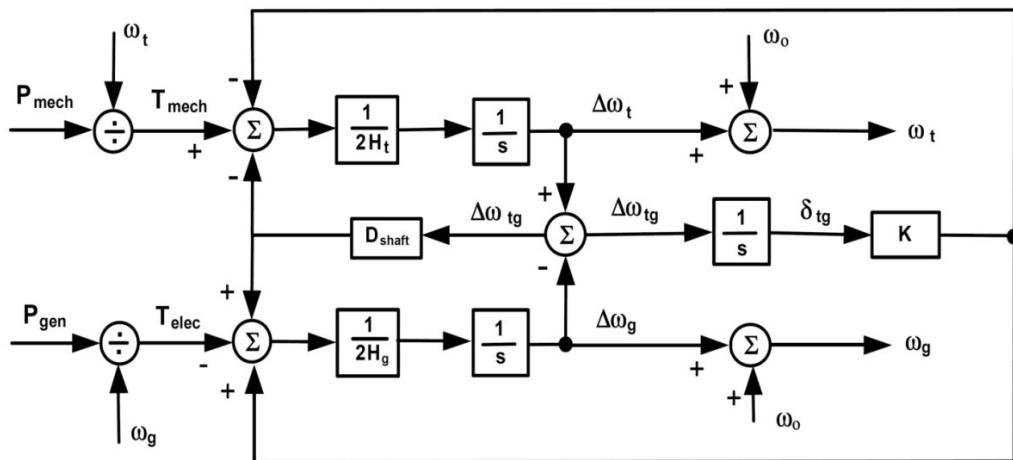


Figure 3.17: Two mass model drive train system

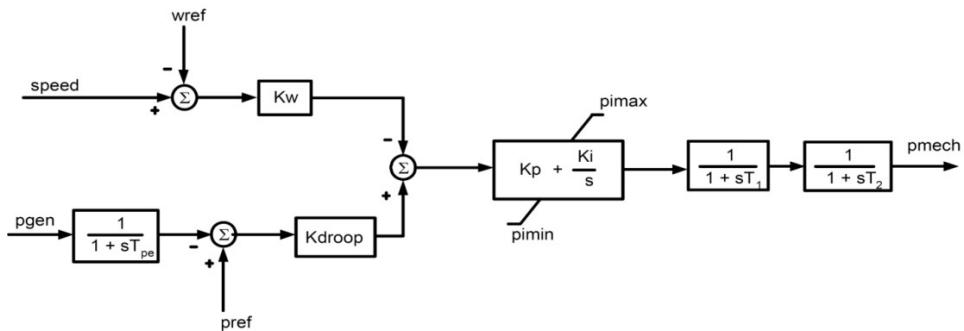


Figure 3.17: Pseudo Governor Model

WT2 Model: The mechanical power output of the wind turbine will come from pseudo governor model. The same is given as input to the induction machine model with rotor resistance controllable. The electrical machine model will compute the real, reactive power generation, operating slip and other steady state operating parameters. Control flow block diagram is given below.

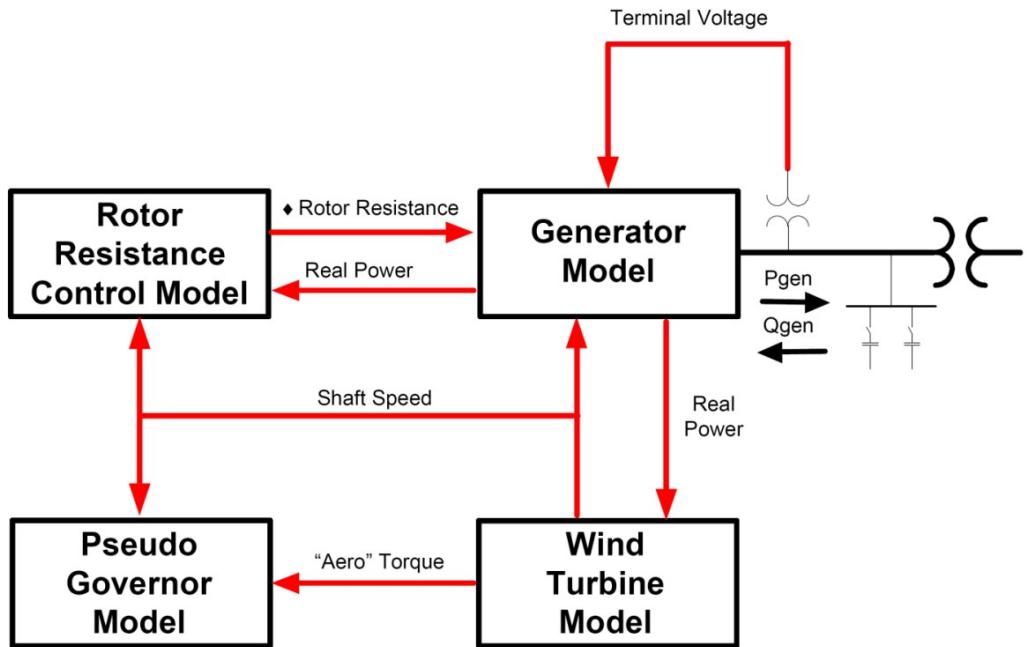


Figure 3.17: WT2 type Wind Turbine

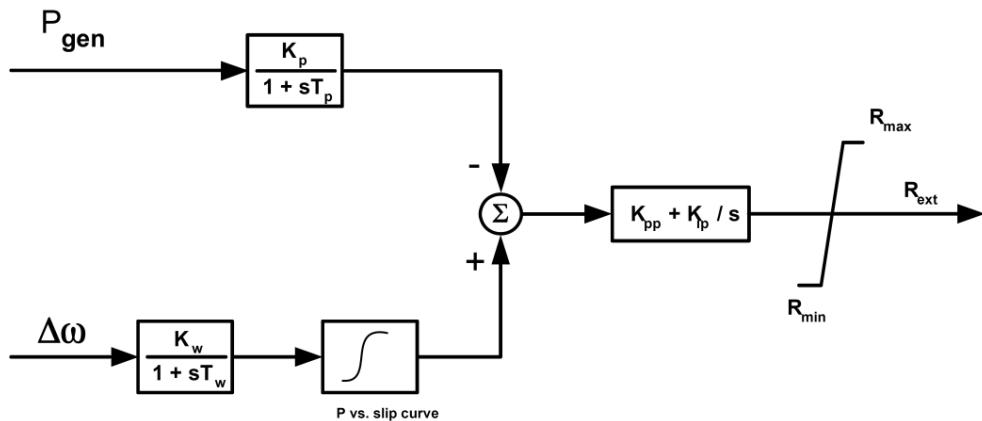


Figure 3.17: External Rotor Resistance Control model

WT3 Model: The mechanical power output of the wind turbine is calculated based on the power curve (Mechanical power to wind speed). Pitch regulation will be given by pitch control model. Power electronic converter block set & machine behavior will be replicated through converter control model and generator/converter model. Control flow block diagram is given below.

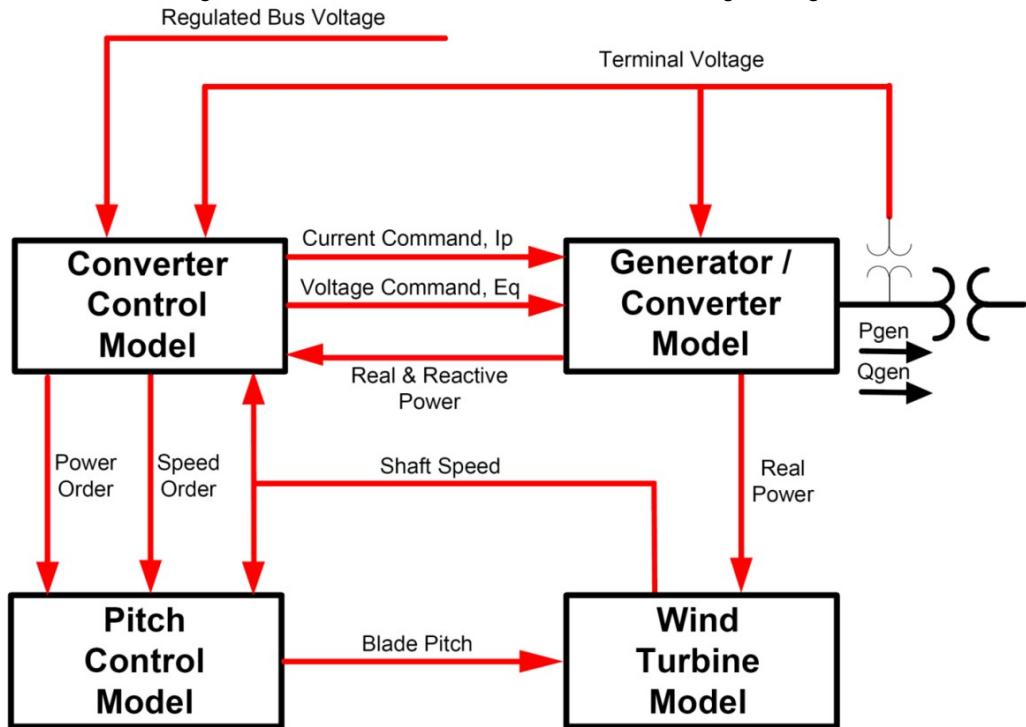


Figure 3.17: WT3 type Wind Turbine

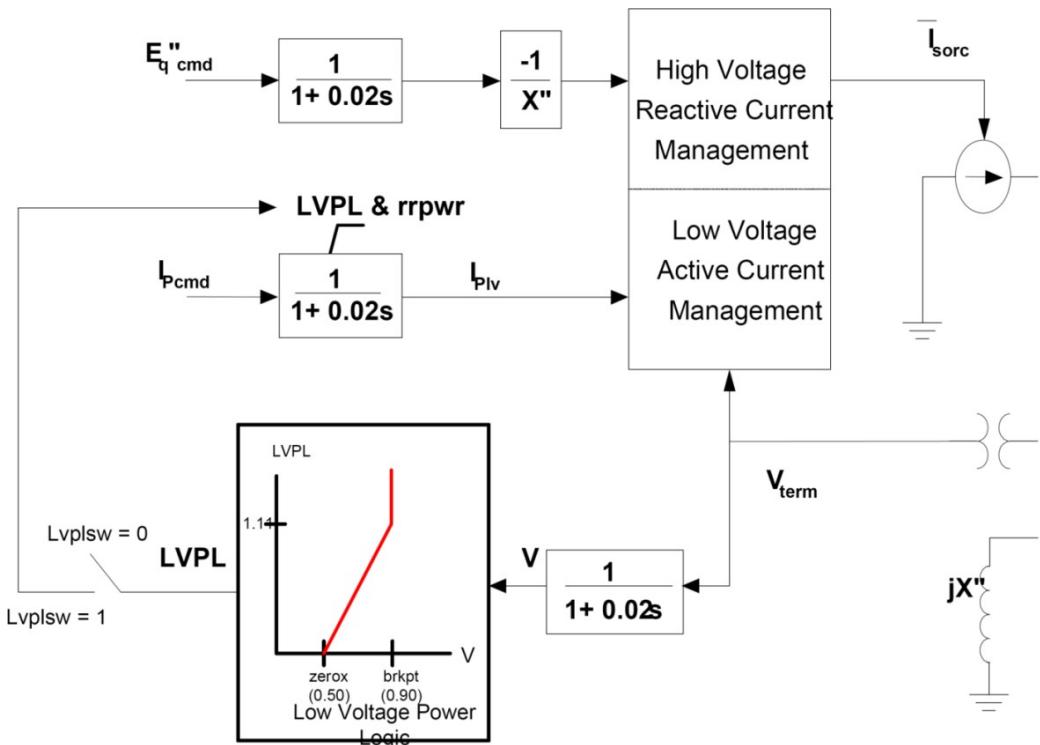


Figure 3.17: DFIG/Full Converter Generator Model

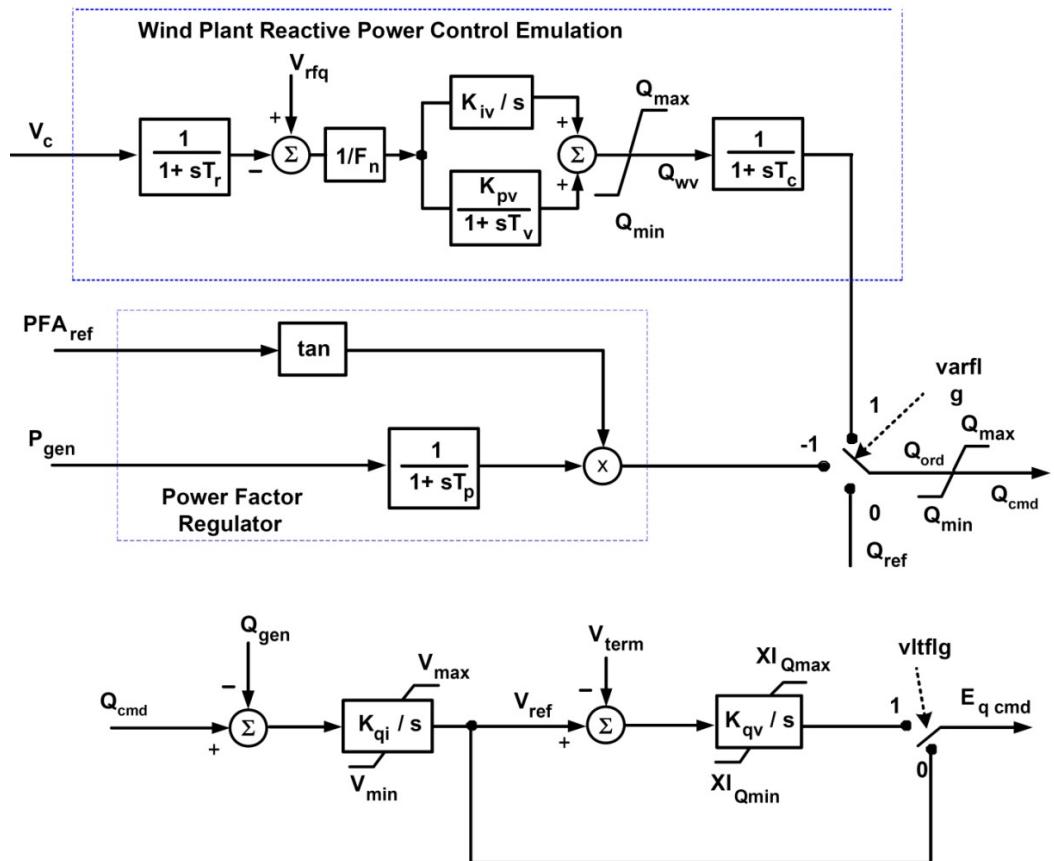


Figure 3.17: DFIG Reactive Power Control Model

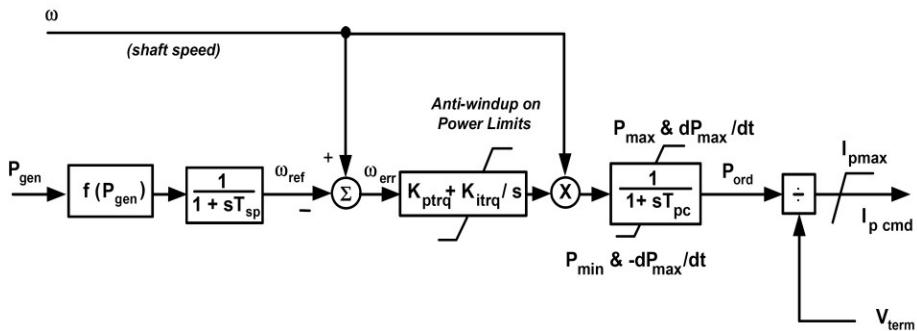


Figure 3.17: Active Power Control Model

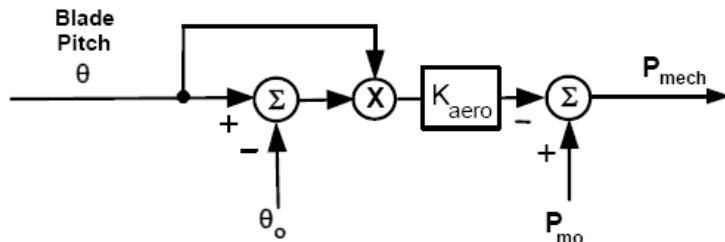


Figure 3.17: Aerodynamic Control Model

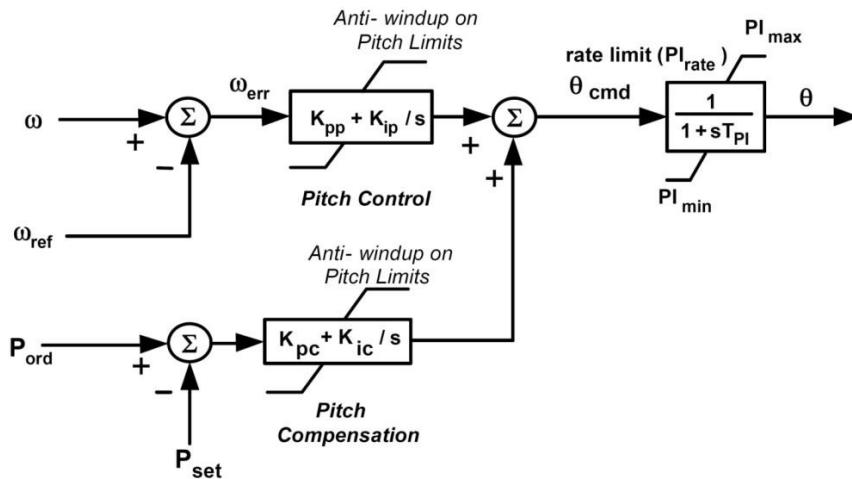


Figure 3.17: Pitch Control Model

WT4 Model: The mechanical power output of the wind turbine is calculated based on the power curve (Mechanical power to wind speed). Power electronic converter block set & machine behavior will be replicated through converter control model and generator/converter model. Control flow block diagram is given below.

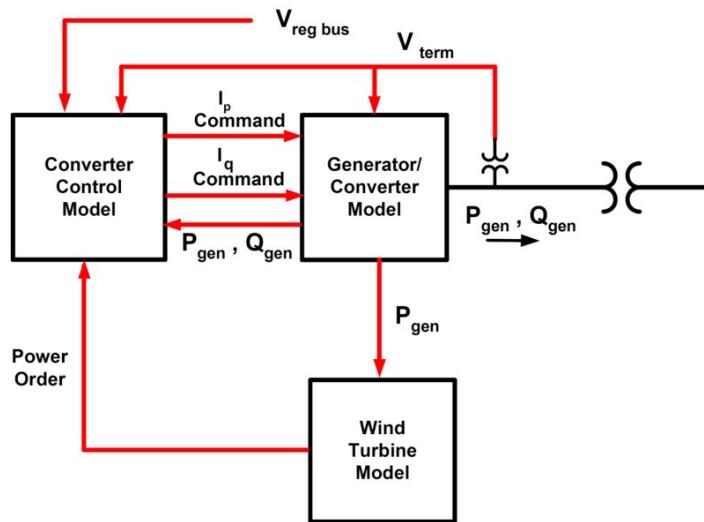


Figure 3.17: WT4 type Wind Turbine

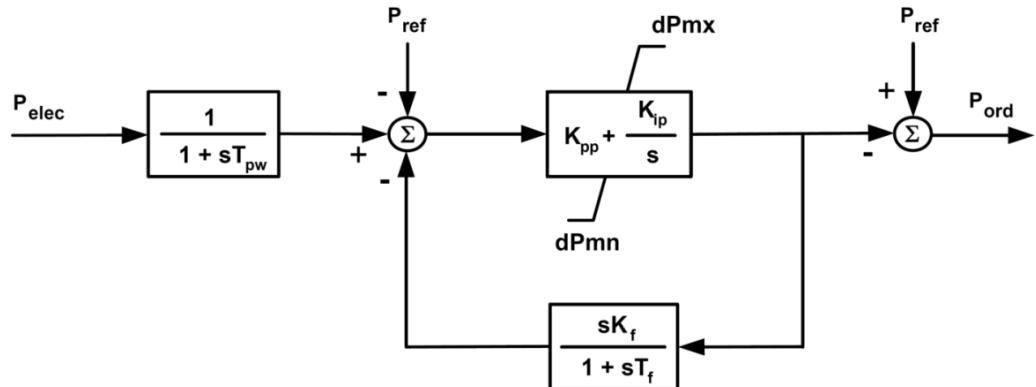


Figure 3.17: Turbine Model

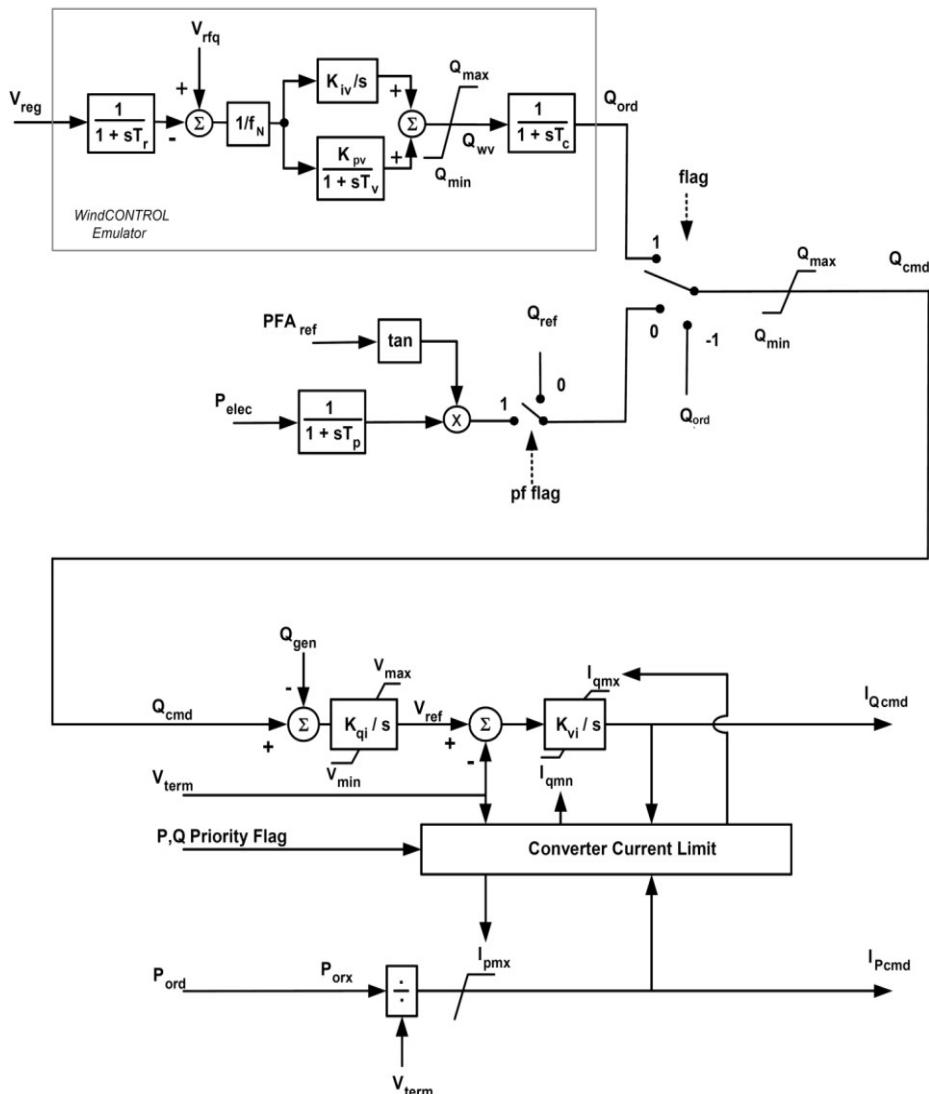


Figure 3.17: Converter Control Model

The data entry format for each model is different. The data that appears in different columns of each line for each model are given in Table 3.12, Table 3.13, Table 3.14, and Table 3.15 respectively.

**Table 3.12 – Wind Generator Data for WT1**

Col No.	Description	Type	Min	Max
1	Status	Int	0	3
2	WT Generator bus number	Int	1	9999
3	WT Generator model number	Int	1	4
4	No. of Turbines in the wind farm	Int	1	9999
5	MVA rating	Double	0.0	1.0e6
6	Drive Train model	Int	1	2
7	Shunt impedance of reactive power injection	Double	-1.0e6	1.0e6
8	No. of poles (only even numbers)	Int	2	9999
9	Gearbox ratio	Double	0.001	1.0e6
10	Turbine diameter in m	Double	-1.0e6	1.0e6
11	Stator resistance (Rs)	Double	0	1.0e6
12	Stator reactance (Xs)	Double	0	1.0e6
13	Rotor resistance (Rr)	Double	0	1.0e6
14	Rotor reactance (Xr)	Double	0	1.0e6
15	Magnetizing reactance (Xm)	Double	0	1.0e6
16	Turbine shaft inertia (Hw)	Double	0	1.0e6
17	Generator shaft inertia (Hg)	Double	0	1.0e6
18	Shaft stiffness constant (K)	Double	0	1.0e6
19	Turbine damping constant (Dw)	Double	0	1.0e6
20	Machine damping constant (Dg)	Double	0	1.0e6
21	Shaft damping constant (Ds)	Double	0	1.0e6
22	Wind Speed (m/s)	Double	0	50
23	Air Density (kg/m <sup>3</sup> )	Double	0	3
24	Pitch Angle	Double	0	180
25	Shaft Angle	Double	0	180
26	Operating slip	Double	0	2
27	Operating real power	Double	0	1.0e6
28	Tpe	Double	-1.0e6	1.0e6
29	Kw	Double	-1.0e6	1.0e6
30	Kdroop	Double	-1.0e6	1.0e6
31	Kp	Double	-1.0e6	1.0e6
32	Ki	Double	-1.0e6	1.0e6
33	Pimax	Double	-1.0e6	1.0e6
34	Pimin	Double	-1.0e6	1.0e6
35	T1	Double	-1.0e6	1.0e6
36	T2	Double	-1.0e6	1.0e6

Table 3.13 – Wind Generator Data for WT2

Col No.	Description	Type	Min	Max
1	Status	Int	0	3
2	WT Generator bus number	Int	1	9999
3	WT Generator model number	Int	1	4
4	No. of Turbines in the wind farm	Int	1	9999
5	MVA rating	Double	0.0	1.0e6
6	Drive Train model	Int	1	2
7	Shunt impedance of reactive power injection	Double	-1.0e6	1.0e6
8	No. of poles (only even numbers)	Int	2	9999
9	Gearbox ratio	Double	0.001	1.0e6
10	Turbine diameter in m	Double	-1.0e6	1.0e6
11	Optimum real power to operating slip curve	Int	1	9999
12	Stator resistance (Rs)	Double	0	1.0e6
13	Stator reactance (Xs)	Double	0	1.0e6
14	Rotor resistance (Rr)	Double	0	1.0e6
15	Rotor reactance (Xr)	Double	0	1.0e6
16	Magnetizing reactance (Xm)	Double	0	1.0e6
17	Turbine shaft inertia (Hw)	Double	0	1.0e6
18	Generator shaft inertia (Hg)	Double	0	1.0e6
19	Shaft stiffness constant (K)	Double	0	1.0e6
20	Turbine damping constant (Dw)	Double	0	1.0e6
21	Machine damping constant (Dg)	Double	0	1.0e6
22	Shaft damping constant (Ds)	Double	0	1.0e6
23	Wind Speed (m/s)	Double	0	50
24	Air Density (kg/m <sup>3</sup> )	Double	0	3
25	Pitch Angle	Double	0	180
26	Shaft Angle	Double	0	180
27	Operating slip	Double	0	2
28	Operating real power	Double	0	1.0e6
29	Tpe	Double	-1.0e6	1.0e6
30	Kw	Double	-1.0e6	1.0e6
31	Kdroop	Double	-1.0e6	1.0e6
32	Kp	Double	-1.0e6	1.0e6
33	Ki	Double	-1.0e6	1.0e6
34	Pimax	Double	-1.0e6	1.0e6
35	Pimin	Double	-1.0e6	1.0e6
36	T1	Double	-1.0e6	1.0e6
37	T2	Double	-1.0e6	1.0e6
38	Kp	Double	-1.0e6	1.0e6
39	Tp	Double	-1.0e6	1.0e6
40	Kw	Double	-1.0e6	1.0e6
41	Tw	Double	-1.0e6	1.0e6
42	Kpp	Double	-1.0e6	1.0e6

43	Kip	Double	-1.0e6	1.0e6
44	Rmin	Double	-1.0e6	1.0e6
45	Rmax	Double	-1.0e6	1.0e6

**Table 3.14 – Wind Generator Data for WT3**

Col No.	Description	Type	Min	Max
1	Status	Int	0	3
2	WT Generator bus number	Int	1	9999
3	WT Generator model number	Int	1	4
4	No. of Turbines in the wind farm	Int	1	9999
5	MVA rating	Double	0.0	1.0e6
6	Drive Train model	Int	1	2
7	Shunt impedance of reactive power injection	Double	-1.0e6	1.0e6
8	No. of poles (only even numbers)	Int	2	9999
9	Gearbox ratio	Double	0.001	1.0e6
10	Turbine diameter in m	Double	-1.0e6	1.0e6
11	Power curve	Int	1	9999
12	Operating mechanical power Vs operating slip	Int	1	9999
13	Power curve type	Int	1	9999
14	Stator resistance (Rs)	Double	0	1.0e6
15	Stator reactance (Xs)	Double	0	1.0e6
16	Rotor resistance (Rr)	Double	0	1.0e6
17	Rotor reactance (Xr)	Double	0	1.0e6
18	Magnetizing reactance (Xm)	Double	0	1.0e6
19	Turbine shaft inertia (Hw)	Double	0	1.0e6
20	Generator shaft inertia (Hg)	Double	0	1.0e6
21	Shaft stiffness constant (K)	Double	0	1.0e6
22	Turbine damping constant (Dw)	Double	0	1.0e6
23	Machine damping constant (Dg)	Double	0	1.0e6
24	Shaft damping constant (Ds)	Double	0	1.0e6
25	Wind Speed (m/s)	Double	0	50
26	Air Density (kg/m <sup>3</sup> )	Double	0	3
27	Pitch Angle	Double	0	180
28	Shaft Angle	Double	0	180
29	Operating slip	Double	0	2
30	Operating real power	Double	0	1.0e6
31	Operating reactive power	Double	0	1.0e6
32	varflg – VAR control flag	Int	0	1
33	pfaflg – Power factor control flag	Int	0	1
34	vltflg – Voltage control flag	Int	0	1
35	apcflg – Active power control flag	Int	0	1
36	wfflg – Turbine control flag	Int	0	1
37	fcflg – Frequency control flag	Int	0	1

38	Voltage control bus	Int	1	9999
39	Real power reference	Double	0	1.0e6
40	Reactive power reference	Double	0	1.0e6
41	kptrq	Double	0	1.0e6
42	kitrq	Double	0	1.0e6
43	Pwrat	Double	0	1.0e6
44	Pwmin	Double	0	1.0e6
45	Pwmax	Double	0	1.0e6
46	tp	Double	0	1.0e6
47	tpc	Double	0	1.0e6
48	kpp	Double	0	1.0e6
49	kip	Double	0	1.0e6
50	kpc	Double	0	1.0e6
51	kic	Double	0	1.0e6
52	Pimax	Double	0	1.0e6
53	Pimin	Double	0	1.0e6
54	Pirat	Double	0	1.0e6
55	tr	Double	0	1.0e6
56	Fn	Double	0	1.0e6
57	kiv	Double	0	1.0e6
58	tv	Double	0	1.0e6
59	kpv	Double	0	1.0e6
60	Qmin	Double	0	1.0e6
61	Qmax	Double	0	1.0e6
62	tc	Double	0	1.0e6
63	tpwr	Double	0	1.0e6
64	kqi	Double	0	1.0e6
65	Vmin	Double	0	1.0e6
66	Vmax	Double	0	1.0e6
67	kqv	Double	0	1.0e6
68	ipmax	Double	0	1.0e6
69	zerox	Double	0	1.0e6
70	brkpt	Double	0	1.0e6
71	Xdd	Double	0	1.0e6
72	XiQmax	Double	0	1.0e6
73	XiQmin	Double	0	1.0e6
74	VI1	Double	0	1.0e6
75	Vh1	Double	0	1.0e6
76	TI1	Double	0	1.0e6
77	TI2	Double	0	1.0e6
78	Th1	Double	0	1.0e6
79	Th2	Double	0	1.0e6
80	QI1	Double	0	1.0e6
81	QI2	Double	0	1.0e6
82	QI3	Double	0	1.0e6
83	Qh1	Double	0	1.0e6

84	Qh2	Double	0	1.0e6
85	Qh3	Double	0	1.0e6
86	dvtlp1	Double	0	1.0e6
87	dvtlp2	Double	0	1.0e6
88	dvtlp3	Double	0	1.0e6
89	dvtlp4	Double	0	1.0e6
90	dvtlp5	Double	0	1.0e6
91	dvtlp6	Double	0	1.0e6
92	dttrp1	Double	0	1.0e6
93	dttrp2	Double	0	1.0e6
94	dttrp3	Double	0	1.0e6
95	dttrp4	Double	0	1.0e6
96	dttrp5	Double	0	1.0e6
97	dttrp6	Double	0	1.0e6
98	Ipp	Double	0	1.0e6
99	rrpwr	Double	0	1.0e6
100	Xc	Double	0	1.0e6
101	kqd	Double	0	1.0e6
102	tlpqd	Double	0	1.0e6
103	Xqd	Double	0	1.0e6
104	vermn	Double	0	1.0e6
105	vermx	Double	0	1.0e6
106	vfrz	Double	0	1.0e6
107	tw	Double	0	1.0e6
108	tpav	Double	0	1.0e6
109	Pa	Double	0	1.0e6
110	Pbc	Double	0	1.0e6
111	Pd	Double	0	1.0e6
112	fa	Double	0	1.0e6
113	fb	Double	0	1.0e6
114	fc	Double	0	1.0e6
115	fd	Double	0	1.0e6
116	Pmax	Double	0	1.0e6
117	Pmin	Double	0	1.0e6
118	kwi	Double	0	1.0e6
119	dbwi	Double	0	1.0e6
120	tlpwi	Double	0	1.0e6
121	twowi	Double	0	1.0e6
122	urlwi	Double	0	1.0e6
123	drlwi	Double	0	1.0e6
124	pmxwi	Double	0	1.0e6
125	pmnwi	Double	0	1.0e6

Table 3.15 – Wind Generator Data for WT4

Col No.	Description	Type	Min	Max
1	Status	Int	0	3
2	WT Generator bus number	Int	1	9999
3	WT Generator model number	Int	1	4
4	No. of Turbines in the wind farm	Int	1	9999
5	MVA rating	Double	0.0	1.0e6
6	Drive Train model	Int	1	2
7	Shunt impedance of reactive power injection	Double	-1.0e6	1.0e6
8	No. of poles (only even numbers)	Int	2	9999
9	Gearbox ratio	Double	0.001	1.0e6
10	Turbine diameter in m	Double	-1.0e6	1.0e6
11	Power curve	Int	1	9999
12	Operating mechanical power Vs operating slip	Int	1	9999
13	Power curve type	Int	1	9999
14	Stator resistance (Rs)	Double	0	1.0e6
15	Stator reactance (Xs)	Double	0	1.0e6
16	Rotor resistance (Rr)	Double	0	1.0e6
17	Rotor reactance (Xr)	Double	0	1.0e6
18	Magnetizing reactance (Xm)	Double	0	1.0e6
19	Turbine shaft inertia (Hw)	Double	0	1.0e6
20	Generator shaft inertia (Hg)	Double	0	1.0e6
21	Shaft stiffness constant (K)	Double	0	1.0e6
22	Turbine damping constant (Dw)	Double	0	1.0e6
23	Machine damping constant (Dg)	Double	0	1.0e6
24	Shaft damping constant (Ds)	Double	0	1.0e6
25	Wind Speed (m/s)	Double	0	50
26	Air Density (kg/m <sup>3</sup> )	Double	0	3
27	Pitch Angle	Double	0	180
28	Shaft Angle	Double	0	180
29	Operating slip	Double	0	2
30	Operating real power	Double	0	1.0e6
31	Operating reactive power	Double	0	1.0e6
32	varflg – VAR control flag	Int	0	1
33	pfaflg – Power factor control flag	Int	0	1
34	vlflg – Voltage control flag	Int	0	1
35	apcflg – Active power control flag	Int	0	1
36	wfflg – Turbine control flag	Int	0	1
37	fccfg – Frequency control flag	Int	0	1
38	Voltage control bus	Int	1	9999
39	Real power reference	Double	0	1.0e6
40	Reactive power reference	Double	0	1.0e6
41	kptrq	Double	0	1.0e6
42	kitrq	Double	0	1.0e6
43	Pwrat	Double	0	1.0e6
44	Pwmmin	Double	0	1.0e6

45	Pwmax	Double	0	1.0e6
46	tp	Double	0	1.0e6
47	tpc	Double	0	1.0e6
48	kpp	Double	0	1.0e6
49	kip	Double	0	1.0e6
50	kpc	Double	0	1.0e6
51	kic	Double	0	1.0e6
52	Pimax	Double	0	1.0e6
53	Pimin	Double	0	1.0e6
54	Pirat	Double	0	1.0e6
55	tr	Double	0	1.0e6
56	Fn	Double	0	1.0e6
57	kiv	Double	0	1.0e6
58	tv	Double	0	1.0e6
59	kpv	Double	0	1.0e6
60	Qmin	Double	0	1.0e6
61	Qmax	Double	0	1.0e6
62	tc	Double	0	1.0e6
63	tpwr	Double	0	1.0e6
64	kqi	Double	0	1.0e6
65	Vmin	Double	0	1.0e6
66	Vmax	Double	0	1.0e6
67	kqv	Double	0	1.0e6
68	ipmax	Double	0	1.0e6
69	zerox	Double	0	1.0e6
70	brkpt	Double	0	1.0e6
71	dvtvp1	Double	0	1.0e6
72	dvtvp2	Double	0	1.0e6
73	dvtvp3	Double	0	1.0e6
74	dvtvp4	Double	0	1.0e6
75	dvtvp5	Double	0	1.0e6
76	dvtvp6	Double	0	1.0e6
77	dttrp1	Double	0	1.0e6
78	dttrp2	Double	0	1.0e6
79	dttrp3	Double	0	1.0e6
80	dttrp4	Double	0	1.0e6
81	dttrp5	Double	0	1.0e6
82	dttrp6	Double	0	1.0e6
83	lpp	Double	0	1.0e6
84	rrpwr	Double	0	1.0e6
85	Xc	Double	0	1.0e6
86	kqd	Double	0	1.0e6
87	tlpqd	Double	0	1.0e6
88	Xqd	Double	0	1.0e6
89	vermn	Double	0	1.0e6
90	vermx	Double	0	1.0e6

91	vfrz	Double	0	1.0e6
92	tw	Double	0	1.0e6
93	tpav	Double	0	1.0e6
94	Pa	Double	0	1.0e6
95	Pbc	Double	0	1.0e6
96	Pd	Double	0	1.0e6
97	fa	Double	0	1.0e6
98	fb	Double	0	1.0e6
99	fc	Double	0	1.0e6
100	fd	Double	0	1.0e6
101	Pmax	Double	0	1.0e6
102	Pmin	Double	0	1.0e6
103	kwi	Double	0	1.0e6
104	dbwi	Double	0	1.0e6
105	tlpwi	Double	0	1.0e6
106	twowi	Double	0	1.0e6
107	urlwi	Double	0	1.0e6
108	drlwi	Double	0	1.0e6
109	pmxwi	Double	0	1.0e6
110	pmnwi	Double	0	1.0e6
111	Iphl	Double	0	1.0e6
112	Iqhl	Double	0	1.0e6
113	Kbdr	Double	0	1.0e6
114	ebst	Double	0	1.0e6
115	spdw1	Double	0	1.0e6

Explanations to entries given in table 3.12 are as follows -

- Generator bus number refers to the bus number at which the generator is connected. The bus number should exist in the bus data stream.
- MVA rating will be specifying rating of one individual turbine. Number of units specifies the number of similar wind turbine available in the farm.
- Real power specified will be significant only in the case of WT4 model. Because this model can generate the power as specified by the operator, within the limit of available power generation.
- The wind farm/turbine tends to maintain the specified operating power factor within the reactive power limits. Negative operating power factor indicates lagging power factor and positive power factor indicates leading power factor.
- The reactive power compensation for WT1, WT2 will be through switchable capacitors at its terminal. So the compensation will be in terms of steps of capacitor bank.
- The No. of steps field is for WT1, WT2 models only. This field specifies No. of reactive power steps.
- The reactive power compensation for WT3, WT4 will be continuous control.
- In case of wind farm the reactive power limits are specified for the entire wind farm.

- System operating frequency should be less than the product of synchronous speed (rps), number of poles, gear box ratio/120. If this validation is not checked the program will give error.
- A general power curve can be represented as below.

$$P_m = \frac{1}{2} \cdot C_p(\lambda, \beta) \cdot \rho \cdot R^2 V_w^3$$

$$\lambda = \frac{\omega_R R}{V_w}$$

$$\omega_R = \frac{2\pi n}{60}$$

Where,  $P_m$  is the total power absorbed by the aerodynamic system

$\rho$  is air density ( $\text{kg/m}^3$ )

$R$  is radius of the turbine blade (m)

$V_m$  is wind speed (m/s)

$\lambda$  is tip speed ratio, i.e. ratio between speed of tip of the blade to the wind speed

$\beta$  is the pitch angle

$C_p$  is coefficient of power

$\omega_R$  is mechanical angular velocity of the turbine rotor (rad/s)

$n$  is rotational speed of wind turbine (RPM)

- Power curve can be represented in four ways. They are

1. Power curve is represented in formula 1
2. Power curve is represented in formula 2
3. Power curve is represented in power curve data
4. Power curve is represented in detailed power curve data

First three types of power curve representations will be in curve data library. Fourth type of representation will be in detailed curve data library.

The generalized formula 1 is as below:

$$C = C_p \left\{ \frac{C_1}{\lambda} + C_2 \lambda + C_3 \lambda^2 + C_4 \lambda^3 + C_5 \lambda^4 \right\} e^{-(\lambda_i + \frac{\lambda}{\lambda_i})}$$

$$\lambda = \frac{1}{\frac{1}{\lambda + a_0} - \frac{a_1}{\lambda^3 + 1}}$$

Where  $C_p$  is the coefficient of power

$\lambda$  is tip speed ratio

$\beta$  is pitch angle

All other coefficients in the equation are constant values and to be entered by the user.

The generalized formula 2 is as below:

$$P_w = \sum_{i=0}^4 \sum_{j=0}^4 (a_{ij} \lambda^j)$$

Where  $P_w$  is mechanical power generation

$a_{ij}$  coefficients for  $i = 0$  to  $4$  and  $j = 0$  to  $4$  need to be given in the input data

$\beta$  is the pitch angle

$\lambda$  is the tip speed ratio

- Variable number 20 specifies the format of powercurve.

Value of variable 20	Respective power curve format
1	Formula 1
2	Formula 2
3	Power curve
4	Detailed power curve

- Variable number 21, 22 and 23 specify the three curves reference numbers to curve libraries. First is Power curve(wind speed(m/s) vs mechanical power generation(p.u.)), second is operating mechanical power(p.u.) vs operating rotor speed(p.u.) and third is operating wind speed(m/s) vs operating rotor speed(p.u.).
- When the variable 20 is 1-3 the power curve represented is of curve library. When the variable 20 is 4 the power curve represented is of detailed curve library.

### Stream 21: Static Var Compensator Details

In this section Static var compensator details are given. Figure 3.20 gives the static VAR compensator model.

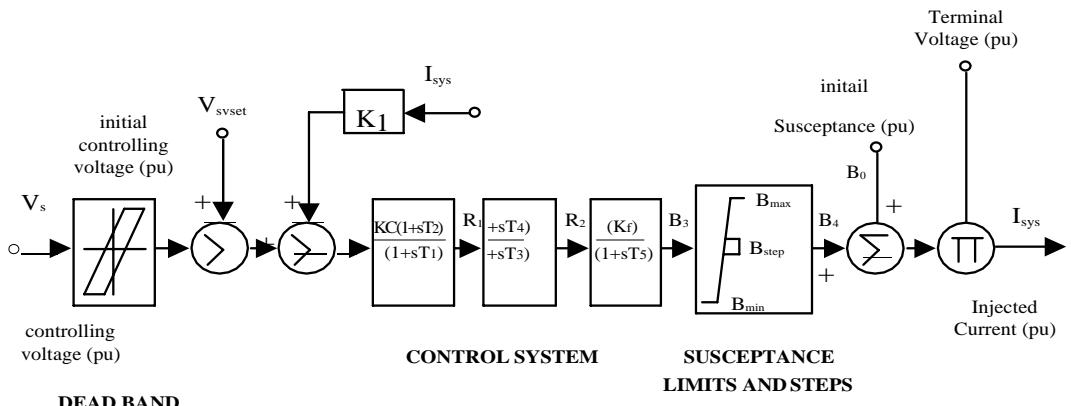


Figure 3.20: Composite Static Var Compensation System (SVS) Model

Number of lines of data is equal to number of static var compensators as given under system specification stream. Data that appear under different columns for each SVS is given in table 3.21

Explanations for the entries in table 3.21 are as follows –

- Bus number refers to the bus number to which the SVC is connected. This number should exist in the bus data stream.
- If the current stabilizer loop is open, then  $K_i$  value should be given as 0.0
- Initial control angled  $\alpha_0$  in radians is computed from the expression -  

$$B_0 = B_{\text{am}} (1 - 2\alpha_0/\Pi - \sin(2\alpha_0)) \quad (3.5)$$
- Minimum capacitance value is assumed as zero. For 50 Mvar capacitor bank control,  $B_{\text{max}}$  value is 0.5 pu on a 100 MVA base.

Table 3.21: SVC Details

Col No.	Description	Type	Min	Max
1.	Bus number	int	0	9999
2.	Current stabilizer gain $K_i$	float	0.0	10.0
3.	$K_c$ as per figure 3.20	float	1.0	10.0
4.	$K_f$ as per figure 3.20	float	1.0	100.0
5.	Time constant $T_1$	float	1.0e-3	100.0

6.	Time constant $T_2$	float	1.0e-3	100.0
7.	Time constant $T_3$	float	1.0e-3	100.0
8.	Time constant $T_4$	float	1.0e-3	100.0
9.	Time constant $T_5$	float	1.0e-3	100.0
10.	Initial control angle in radians	float	1.0e-3	100.0
11.	Maximum capacitance value $B_{max}$ in pu	float	0.0	100.0
12.	Initial value of capacitance $B_0$ in pu	float	0.0	100.0

- It is assumed that there is no other fixed compensation (Q-Mvar), specified along with the load data at the SVS bus.
- If the initial capacitance value is other than zero, then corresponding compensating Mvar should be provided at that bus in the load flow analysis data to establish the proper initial condition.

### Stream 22: HVDC Converters Data

In this stream of data, HVDC converter details are given. The schematic diagram of a 12 pulse converter station and its equivalent representation are given in figures 3.21 and 3.22 respectively.

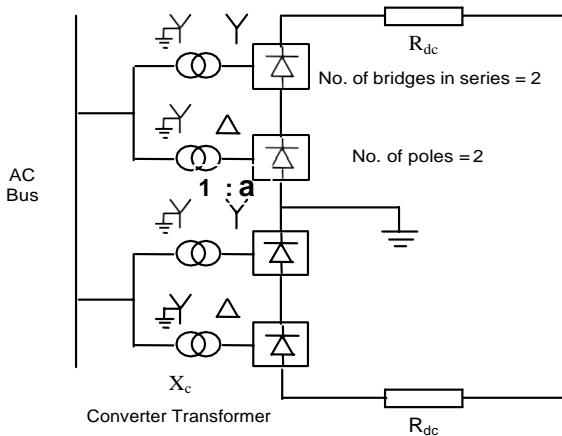


Figure 3.21: Schematic of 12 Pulse Bipolar Converter Station

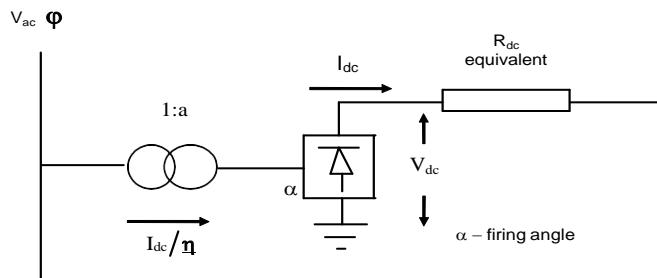


Figure 3.22: Equivalent representation

Total number of lines of data in this stream is equal to number of HVDC converters as given in specification stream. The data that appears in different columns of each line is given in table 3.22. Explanations to entries given in table 3.22 are as follows –

- Converter number is the serial number of the converter, which is also the dc bus number.
- AC bus number is the bus number to which the converter is connected. This number should exist in the "bus data stream".

Table 3.22 - HVDC Converter Data

Col No.	Description	Type	Min	Max
1.	Converter number	int	1	20
2.	AC bus number	int	1	9999
3.	Converter transformer X in pu	float	1.0e-5	1.0e2
4.	Control tag	int	1	3
5.	Voltage order in kV	float	-1.0e05	1.0e05
6.	Current order in Amps	float	-1.0e05	1.0e05
7.	Power order in MW	float	-1.0e05	1.0e05
8.	Current margin in Amps	float	-1.0e03	1.0e03
9.	Number of bridges in series	int	1	10
10.	Number of poles	int	1	2
11.	Converter transformer secondary kV	float	0.1	1.0e4
12.	Converter transformer MVA rating	float	0.1	1.0e4
13.	Minimum control angle in degrees	float	0.0	180.0
14.	Operating voltage in kV	float	-1.0e05	1.0e05
15.	Operating power in MW	float	-1.0e05	1.0e05
16.	Operating reactive power in Mvar	float	-1.0e05	1.0e05
17.	Control angle in degrees	float	0.0	180.0
18.	Transformer tap in pu	float	0.5	1.5
19.	Smoothening reactance in pu	float	0.0	1.0e05

- Converter transformer reactance is in p.u on transformer MVA rating. Commutation resistance  $R_c$  is related to the transformer reactance  $X_c$  by the expression -

$$R_c = \frac{3X_c}{\pi} \quad (3.6)$$

- Control tag is interpreted as -
  1. Constant voltage control
  2. Constant current control
  3. Constant power control.

In a two terminal or multi terminal converter group, at least one converter in the group should have control tag as 1.

- Depending on the control tag, voltage order or current order or power order is selected for the converter.
- Current margin is maintained between the rectifier and the inverter in order to avoid the mode changes.
- Number of bridges is interpreted as -
  1. Six pulse converter
  2. Twelve pulse converter.
- Number of poles is interpreted as -
  3. Monopolar
  4. Bipolar.

Minimum control angle in degrees is the minimum firing angle ( $\alpha_{min}$ ) for converter and minimum extinction angle ( $\alpha_{min} = 180.0 - \alpha - \mu$ ) for the inverter.  $\mu$  Is the overlap angle. Minimum firing angle ranges from 5 degrees to 7 degrees. Minimum extinction angle ranges from 15 degrees to 20 degrees.

Prior to transient stability study, load flow analysis is performed to establish the initial conditions. Columns 14 to 18 are obtained from the initial load flow study. During transient stability study converter transformer tap is held constant at the value given in column 18.

- In ac system, the base quantities are -

$P_{ac\ base}$  = 3 phase power

$V_{ac\ base}$  = line to line rms value.

$$I_{ac\ base} = P_{ac\ base} / \sqrt{3} V_{ac\ base}$$

- In dc system, the base quantities are -

$P_{dc\ base}$  =  $P_{ac\ base}$

$V_{dc\ base}$  =  $K_b V_{ac\ base}$ .

$$I_{dc\ base} = (3\sqrt{2}/\pi) I_{ac\ base}$$

where,

$$K_b = (3\sqrt{2}/\pi) n_b$$

$n_b$  number of series connected bridges in a hvdc terminal.

- The dc voltage and power at the converter are given by -

$$V_{dc} = a V_{ac} \cos \alpha - R_c I_{dc} \quad (3.7)$$

$$P_{dc} = V_{dc} I_{dc} \quad (3.8)$$

where,

a : transformer tap setting

$\alpha$  : firing angle.

Neglecting the losses in the converter and its transformer, the equation for power factor angle ( $\phi-\eta$ ) is given by  $V_{dc} = a V_{ac} \cos(\phi-\eta)$  (3.9)

Expression for reactive power flowing from the AC bus into the converter terminal is given by

$$Q_{dc} = P_{dc} \tan(\phi-\eta) \quad (3.10)$$

where,

$\phi$  : AC voltage angle.  $\eta$  : AC current angle.

### Stream 23: DC Link Data

In this stream of data, DC link details are given. Total number of lines of data in this stream is equal to number of DC links as given in specification stream. The data that appears in different columns of each line is given in table 3.23.

Table 3.23 - DC Link Data

Col No.	Description	Type	Min	Max
1.	From convertor number	int	1	20
2.	To convertor number	int	1	20
3.	DC link resistance in ohms	float	1.0e-5	1.0e2
4.	DC link inductance in henry	float	1.0e-5	1.0e2
5.	DC link shunt capacitance in farads	float	1.0e-08	1.0

Explanations to entries given in table 3.23 are as follows -

- From convertor number is the convertor number to which one end of dc link is connected. This number should exist in the convertor data stream.
- To convertor number is the convertor number to which the other end of dc link is connected. This number should exist in the convertor data stream.
- DC link resistance is in ohms for one pole. For bipolar operation, equivalent resistance is computed internally.
- DC link inductance is in henry for one pole. For bipolar operation, equivalent inductance is computed internally.

- DC link capacitance is in farads for one pole. For bipolar operation, equivalent capacitance is computed internally.
- 

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#### Stream 24: Free Programmable Block (FPB) Data

In this stream, data needed for the free programmable blocks are given. Number of data sets corresponds to number of FPBs as specified under system specification stream. For more details, chapter on Free programmable Block should be referred. For each FPB unit, following data are read.

- FPB bus, i.e., the bus to which the FPB is connected. In case of HVDC this is the convertor ac bus number. In case of ULTC this is transformer number
- FPB type which is interpreted as -
  1. Automatic voltage regulator
  2. Turbine governing system
  3. Static var system
  4. HVDC system
  5. Under Load Tap Changer
  6. Controller for load

In case of AVR and turbine governing system, FPB bus should be a generating bus. Also there should not be any standard AVR or turbine-governor control blocks associated with that generator, if the FPB type is for AVR or for turbine governing system respectively.

Total number of state variables (i.e., number of FPB nodes) in the FPB unit.

- Total number of basic free programmable blocks in the FPB unit.
- Total number of tables referred by the FPB.
- Initial value for nodes.
- Maximum number of iteration.
- Convergence tolerance
- Node data
- Block data

In **POWERTRS**, while establishing the initial condition and also while solving the system dynamic equations, node type field are used to establish the relation between the FPB state variable and the generator state variable. Node type field is explained in the chapter on Free Programmable Blocks.

### Stream 25: Frequency Relay Data

In this stream of data, frequency relay characteristic details are given. Total number of lines of data in this stream is equal to number of relay characteristics as given in specification stream. The data that appears in different columns of each line are given in table 3.24.

**Table 3.24: Frequency Relay Characteristic Data**

Col No.	Description	Type	Min	Max
1.	Frequency relay characteristic number	int	1	20
2.	Relay type	int	0	2
3.	Frequency setting 1 in Hz.	float	0.0	1.0
4.	Time setting 1 in seconds.	float	0.0	5.0
5.	Load shedding factor 1	float	0.0	1.0
6.	Frequency setting 2 in Hz.	float	0.0	1.0
7.	Time setting 2 in seconds.	float	0.0	5.0
8.	Load shedding factor 2	float	0.0	1.0
9.	Frequency setting 3 in Hz.	float	0.0	1.0
10.	Time setting 3 in seconds.	float	0.0	5.0
11.	Load shedding factor 3	float	0.0	1.0

Explanations to entries given in table 3.24 are as follows -

- The frequency relay number given here should match the one given under series element and shunt element data.
- Relay type is interpreted as -
  - 0: Under frequency relay.
  - 1: Over frequency relay.
  - 2: df/dt relay.
- In case of relay associated with a load, it is possible to shed the load partly or completely, depending on the load shedding factor. For elements other than loads, load shedding factor is not applicable.
- The relays are modeled to have 3 frequency settings. If the frequency (or df/dt) goes below the setting 3 (df/dt setting in case of rate of change of frequency relay), a timer is started. If the frequency deviation persists till the time setting 3, then the series or shunt element is disconnected from the system. In case of loads, load is curtailed by the amount given by factor 3. Thus if the specified load is 100 MW, frequency setting 3 is 47 Hz., time setting is 2 seconds, and the load shedding factor is 0.5, then if the bus frequency goes below 47 Hz, and persists for duration greater than 2 seconds, the actual load considered for the remaining duration is 50 MW. Same explanation holds for other two settings also.
- It is assumed that frequency setting 3 is less than frequency setting 2 and frequency setting 2 is less than frequency setting 1 for under frequency relay. In case of over frequency relay, frequency setting 3 is greater than frequency setting 2 and frequency setting 2 is greater than frequency setting 1.

- Load shedding factor is the amount of load to be shed from the specified value. At the end of each transient stability time step, the bus frequency at desired buses is computed. Frequency relay logic is introduced to determine the starting of the timer. A proper co-ordination of relays are required in terms of frequency settings and time delay to avoid the shedding (tripping) of loads (other series elements or shunt elements) at all the places simultaneously.

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### Stream 26: Voltage Relay Data

In this stream of data, voltage relay characteristic details are given. Total number of lines of data in this stream is equal to number of voltage characteristics as given in specification stream. The data that appears in different columns of each line are given in table 3.25.

Table 3.25: Voltage Relay Characteristic Data				
Col No.	Description	Type	Min	Max
1.	Voltage relay characteristic number	int	1	20
2.	Relay type	int	0	1
3.	Voltage setting 1 in pu.	float	0.0	1.0
4.	Time setting 1 in seconds.	float	0.0	5.0
5.	Load shedding factor 1	float	0.0	1.0
6.	Voltage setting 2 in pu.	float	0.0	1.0
7.	Time setting 2 in seconds.	float	0.0	5.0
8.	Load shedding factor 2	float	0.0	1.0
9.	Voltage setting 3 in pu.	float	0.0	1.0
10.	Time setting 3 in seconds.	float	0.0	5.0
11.	Load shedding factor 3	float	0.0	1.0

Explanations to entries given in table 3.25 are as follows -

- The voltage relay number given here should match the one given under series element and shunt element data.
- Relay type is interpreted as -
  - 0: Under voltage relay.
  - 1: Over voltage relay.
- In case of relay associated with a load, it is possible to shed the load partly or completely, depending on the load shedding factor.
- For elements other than loads, load shedding factor is not applicable.
- The relays are modeled to have 3 voltage settings. If the bus voltage goes below the setting 3, a timer is started. If the voltage deviation persists till the time setting 3, then the series or shunt element is disconnected from the system. In case of loads, load is curtailed by the amount given by factor 3. Thus if the specified load is 100 MW, under voltage setting 3 is 0.75 pu, time setting is 5 seconds, and the load shedding factor is 0.5, then if the bus voltage goes below 0.75 pu, and persists for duration greater than 5 seconds, the actual load considered for the remaining duration is 50 MW. Same explanation holds for other two settings also.

- It is assumed that voltage setting 3 is less than voltage setting 2 and voltage setting 2 is less than voltage setting 1 for under voltage relays. For over voltage relays, it is assumed that voltage setting 3 is greater than voltage setting 2 and voltage setting 2 is greater than voltage setting 1.
- Load shedding factor is the amount of load to be shed from the specified value. At the end of each transient stability time step, the bus frequency at desired buses is computed. Frequency relay logic is introduced to determine the starting of the timer. A proper co-ordination of relays are required in terms of frequency settings and time delay to avoid the shedding (tripping) of loads (other series elements or shunt elements) at all the places simultaneously.

### Stream 27: Over Current Relay Data

In this stream of data, over current relay characteristics data are given. Total number of lines of data under this stream is equal to number of **relays specified** under system size specification field. Data that appears under different columns of each line are given in table 3.26.

Table 3.26: Over current relay details				
Col No.	Description	Type	Min	Max
1.	Element number	int	1	1000
2.	Relay location	int	1	2
3.	Relay type	int	1	10
4.	Time dial setting (TDS or TMS)	float	0.05	10.0
5.	Relay plug setting	float	1.0	1.0e5
6.	Relay instantaneous setting	float	1.0	1.0e5

Explanations for the entries in table 3.26 are as follows -

- Element number refers to the series/shunt element number for which the relay is provided. Element number is assigned by counting the series elements in the system first and then the shunt elements as specified in the data. In series elements, transformers are counted first (2 winding transformers first and then 3 winding transformers, each 3 winding transformer results in 3 series elements), then the lines, followed by series reactors, capacitors, and bus couplers in the order the data is presented. For shunt elements, machines (generators and motors) are counted first, followed by shunt reactors and capacitors in admittance form and shunt reactors and capacitors in impedance form.
- Relay location is always 1 for shunt elements. For series elements, relay location is interpreted as -
  - 1: Relay is on the from bus side.
  - 2: Relay is on the to bus side.

But in the model, for series elements, tripping of any one side results in the isolation of other end also.

Relay type is interpreted as -

- 1 : 3 seconds relay i.e., relay operates in 3 seconds for 10 times the plug setting multiplier at unity time dial setting. The curve at unity TDS is implemented by  $t = 3.0/\log(M)$  where  $t$  is the operating time in seconds, and  $M$  is the multiple of plug setting.
  - 2 : 1.3 seconds relay i.e., relay operates in 1.3 seconds for 10 times the plug setting multiplier at unity time dial setting.
  - The curve at unity TDS is implemented by  $t = 1.3/\log(M)$  where  $t$  is the operating time in seconds, and  $M$  is the multiple of plug setting.
  - 3 - 10: User defined relay characteristics.  
Operating time at any other time dial setting is given by multiplying the above operating time by the time dial setting.
- Time dial setting (TDS) is sometimes referred to as time multiplier setting (TMS). The usual range is 0.05 - 1.0. But some manufacturers give the TDS value from 1 to 10 also. Relay TDS setting actually done after co-ordination is entered in column 4.
  - Plug setting is given in amperes referred to CT primary side. If the relay CT is 300/5 amps, and the relay plug setting is 150% (plug setting for phase fault relay is in the range 50% to 200%) then the value to be given in column 5 is 450 amperes.
  - Over current relays are provided with instantaneous elements to isolate the faulted line for close in faults. The instantaneous setting in amps, referred to CT primary side is given in column 6.
  - Whenever the current sensed by the relay exceeds the plug setting, a timer is started. If the timer count exceeds the actual relay operation time, the trip signal is given.

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### Stream 28: Distance Relay Data

In this stream, distance relay characteristics data are given. Total number of lines of data in this stream is equal to the number of distance relays as given under system size specification stream. Data fields that appear under different columns are given in table 3.27.

**Table 3.27: Distance relay data**

Col No.	Description	Type	Min	Max
1.	Line number	Int	1	1000
2.	Relay location	Int	1	2

For each relay the following data are considered as per table 3.28.

**Table 3.28: Distance relay data**

Col No.	Description	Type	Min	Max
1.	Relay number	Int	1	1000
2.	Relay name	char	1	10
3.	Relay type	Int	0	8
4.	Relay parameters for each zone (Zone1 Zone2, Zone3, PS1, PS2 and starter setting as per table 3.29)	-	-	-
5.	Power swing set time.	Float	0	1000
6.	Blocking time.	Float	0	1000

**Table 3.29: Distance relay parameter for each zone**

Relay type.	Relay type	Data required	Type	Min	Max
0	Mho	1.Impedance 2. Theta 3.Displacement 4.TimeSetting	Float Float Float Float	0 0 0 0	10 00 360 1000 1000
1	Ohm	1.Impedance 2. Theta 3.Phi 4.TimeSetting	Float Float Float Float	0 0 0 0	1000 360 360 1000
2	Quadrilateral	1.RF 2.RB 3.XT 4.XB 5.Theta 6.Phi 7.TimeSetting	Float Float Float Float Float Float Float	0 0 0 0 0 0 0	1000 1000 1000 1000 1000 1000 1000
3	Quadra Mho	1.Impedance 2. Theta 3.TimeSetting	Float Float Float	0 0 0	1000 360 1000
4	Elliptical	1.Impedance 2. Theta 3.Displacement 4.TimeSetting	Float Float Float Float	0 0 0 0	1000 360 1000 1000
5	Lential	1.Impedance 2. Theta 3.Displacement 4.TimeSetting	Float Float Float Float	0 0 0 0	1000 360 1000 1000

6	Circular	1.Impedance 2.TimeSetting	Float Float	0 0	1000 1000
7	Oval	1.Impedance 2. Theta 3.TimeSetting	Float Float Float	0 0 0	1000 360 1000

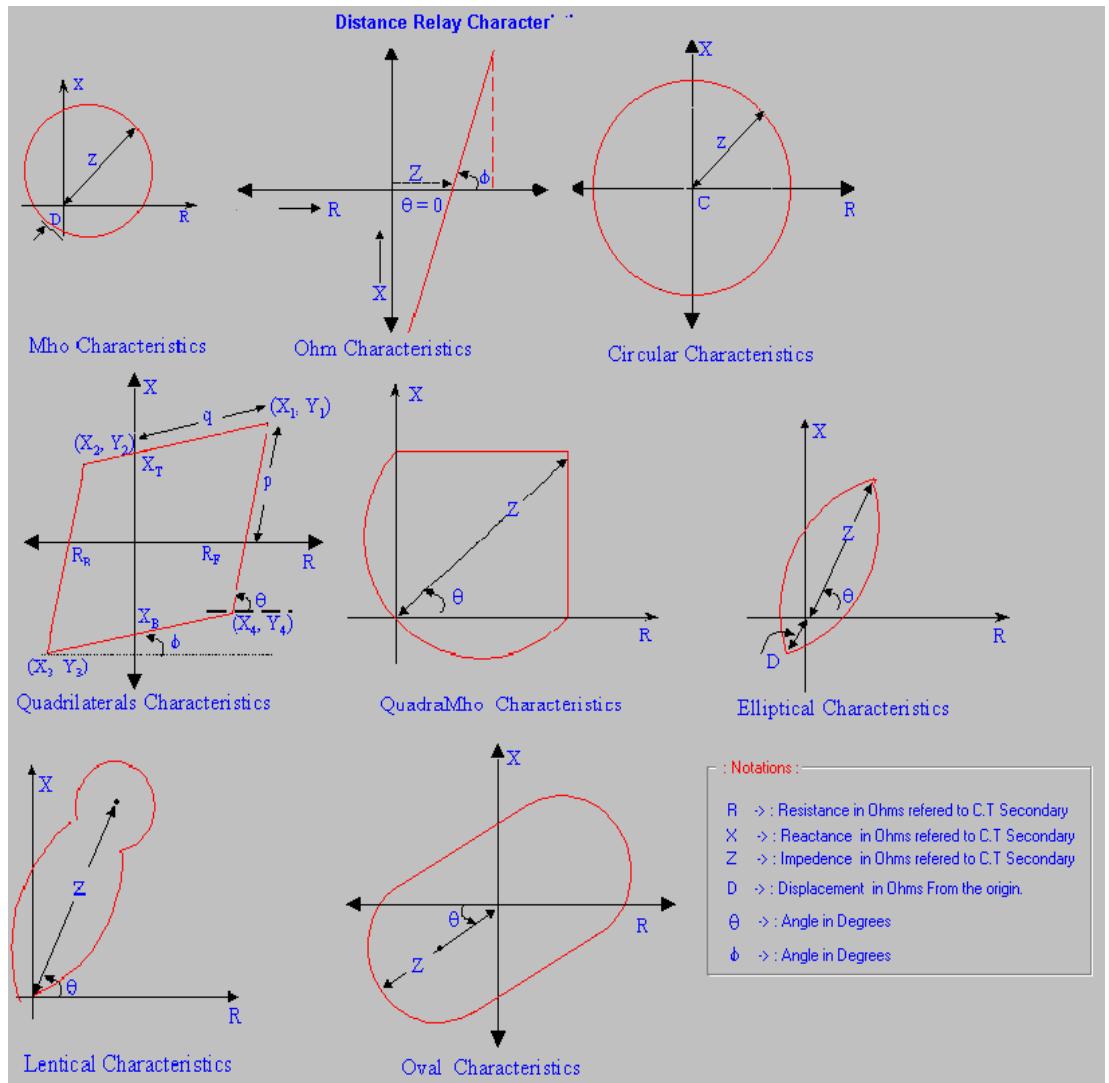
**Note:** Relay Type number 8 corresponds to that no relays settings are present for that zone.

Explanations for the entries in table 3.27 to 3.29 are as follows –

- Distance relays are provided for transmission lines. Line number refers to the transmission line number to which the relay should refer to. Since transmission line data follows the transformer data, number of transformer elements is subtracted from series element number to find the transmission line number.
- Relay location field is interpreted as -
  - 1: Relay is provided on from bus side of the line.
  - 2: Relay is provided on to bus side of the line.
 Even if anyone relay operates, the line is completely isolated from the system.
- Impedance, Displacement, RF, RB, XT, and XB referred in relay parameters are in ohms referred to primary (HT) side of instruments transformers (CT and PT).
- Theta and Phi referred in relay parameters are in angle indegrees.
- Power swing set time and blocking time referred in relay settings are time in sacs.
- At each simulation time step, the impedance seen by the distance relay is computed. If the impedance falls within zone 1 characteristic, line is tripped instantaneously (after a preset time interval corresponding to circuit breaker time delay). If the impedance falls within zone 2 or zone 3, respective timers are started. If the fault persists, the line is tripped after the zone 2 or zone 3-time delay.

Different set of characteristics are provided for phase and earth loop.

The ideal characteristic plots are as shown



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### Stream 29: Cyclic Load Data

1. Cyclic load bus number (int field): This is the bus number to which the cyclic load is connected.
2. Number of data points for cyclic load (int field): Total number of data points per cyclic load should not exceed 50.
3. Time period of cyclic load: Time period is in seconds, afterwhich the load pattern repeats.
4. For each data points following fields are read in order
  - (a) Serial number of the data point.
  - (b) Time in seconds for the sample from zero instant of time.
  - (c) Real power load in MW.
  - (d) Reactive power load in Mvar.

Load points need not be given in equal time intervals. Between two data points, the straight line relation is used to compute the load at intermediate points. Consider a cyclic load at bus say 15, which repeats after 10 seconds. The load remains constant at 10 MW in the interval 0.0-4.0 seconds. It remains constant at 20 MW in the interval 4.0-7.0 seconds. It is again 16 MW in the interval 7.0-10.0 seconds. Reactive power demand is 50% of real power demand. The cyclic variation of real power load is given in figure 3.23. For this case, the data is prepared as follows

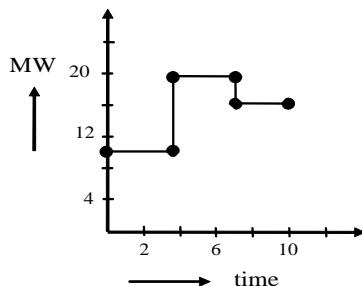


Figure 3.23 - Typical Cyclic Load Curve

15	6	10.0	
1	0.00	10.0	5.0
2	4.00	10.0	5.0
3	4.00	20.0	10.0
4	7.00	20.0	10.0
5	7.00	16.0	8.0
6	0.00	16.0	8.0

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### Stream 30: Wind Turbine Generator Curve Data

In this stream of data, wind turbine related curves details are given. For each curve, the data given are -

1. Curve number.
2. Curve type.
3. Number of curve points.
4. Real power in pu, corresponding minimum and maximum reactive powers in pu on its own rating for each data point.

Curve number is the generator capability curve number referred by the generator under "generator data stream". Minimum number of curve points required is two. Maximum number of curve points should not exceed ten. For a generator MVA rating 265, figure 3.8 shows a sample generator capability curve for minimum and maximum reactive power limits as shown in the table 3.17.

In this stream, Wind Turbine related curves library is printed. Basically there are five types of curves. They are

1. Power curve represented in formula 1 format.
2. Power curve represented in formula 2 format.
3. Power curve represented in curve data format.
4. Operating mechanical power(p.u.) vs operating rotor speed(p.u.)
5. Operating wind speed(m/s) vs operating rotor speed(p.u.)

Curve type 1-3 will represent for power curve. Curve type 4 represent for operating mechanical power vs operating rotor speed and curve type 5 for operating wind speed vs operating rotor speed. The format for the curve type 3-5 is same but for curve type 1 and 2 are different. Various streams present for each type of curve are listed in tables for each curve type separately.

Data streams for curve type 1

Table 3.12 – Curve data for curve type 1

Col No.	Description	Type	Min	Max
1	C0	Double	-1.0e6	1.0e6
2	C1	Double	-1.0e6	1.0e6
3	C2	Double	-1.0e6	1.0e6
4	C3	Double	-1.0e6	1.0e6
5	C4	Double	-1.0e6	1.0e6
6	C5	Double	-1.0e6	1.0e6
7	a	Double	-1.0e6	1.0e6
8	b	Double	-1.0e6	1.0e6
9	c	Double	-1.0e6	1.0e6
10	d	Double	-1.0e6	1.0e6
11	a0	Double	-1.0e6	1.0e6
12	a1	Double	-1.0e6	1.0e6

The generalized formula for curve type 1 is as below:

$$C = C_p \left\{ \frac{C_1}{\lambda} + C_2 \lambda + C_3 \lambda^2 + C_4 \lambda^3 + C_5 \right\} e^{(\lambda_i + \frac{\beta}{\lambda_i})}$$

$$\lambda = \frac{1 - a_1}{a_0 - \lambda^3 + 1}$$

Where  $C_p$  is the coefficient of power

$\lambda$  is tip speed ratio

$\beta$  is pitch angle

All other coefficients in the equation are constant values and to be entered by the user.

Data streams for curve type 2

Table 3.12 – Curve data for curve type 2

Col No.	Description	Type	Min	Max
1	$a_{00}$	Double	-1.0e6	1.0e6
2	$a_{01}$	Double	-1.0e6	1.0e6
3	$a_{02}$	Double	-1.0e6	1.0e6
4	$a_{03}$	Double	-1.0e6	1.0e6
5	$a_{04}$	Double	-1.0e6	1.0e6
6	$a_{10}$	Double	-1.0e6	1.0e6
7	$a_{11}$	Double	-1.0e6	1.0e6
8	$a_{12}$	Double	-1.0e6	1.0e6
9	$a_{13}$	Double	-1.0e6	1.0e6
10	$a_{14}$	Double	-1.0e6	1.0e6
11	$a_{20}$	Double	-1.0e6	1.0e6
12	$a_{21}$	Double	-1.0e6	1.0e6
13	$a_{22}$	Double	-1.0e6	1.0e6
14	$a_{23}$	Double	-1.0e6	1.0e6
15	$a_{24}$	Double	-1.0e6	1.0e6
16	$a_{30}$	Double	-1.0e6	1.0e6
17	$a_{31}$	Double	-1.0e6	1.0e6
18	$a_{32}$	Double	-1.0e6	1.0e6
19	$a_{33}$	Double	-1.0e6	1.0e6
20	$a_{34}$	Double	-1.0e6	1.0e6
21	$a_{40}$	Double	-1.0e6	1.0e6
22	$a_{41}$	Double	-1.0e6	1.0e6
23	$a_{42}$	Double	-1.0e6	1.0e6
24	$a_{43}$	Double	-1.0e6	1.0e6
25	$a_{44}$	Double	-1.0e6	1.0e6

The generalized formula for curve type 2 is as below:

$$P_w = \sum_{i=0}^4 \sum_{j=0}^4 (a_{ij} \lambda^j)$$

Where  $P_w$  is mechanical power generation

$a_{ij}$  coefficients for  $i = 0$  to 4 and  $j = 0$  to 4 need to be given in the input data

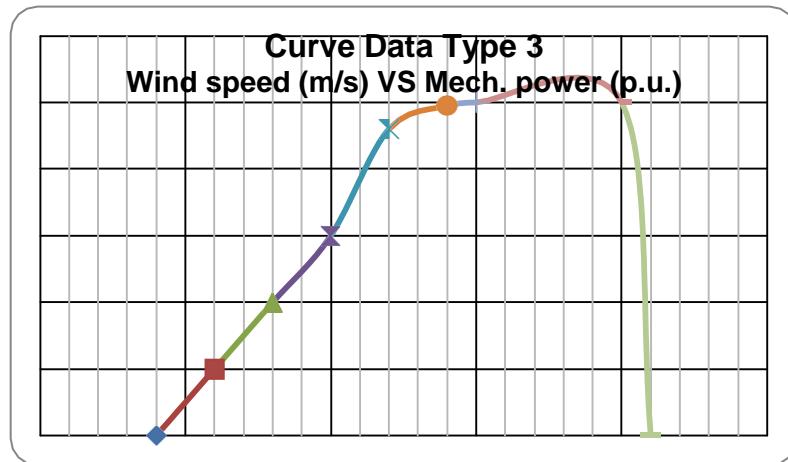
$\beta$  is the pitch angle

$\lambda$  is the tip speed ratio

Data streams for curve type 3

Table 3.12 – Curve data for curve type 3		
Col No.	Wind Speed (m/s)	Mechanical Power Generation (p.u.)
1	4	0
2	6	0.2
3	8	0.4
4	10	0.6
5	12	0.92
6	14	0.99
7	15	1.0
8	20	1.0
9	21	0.0

The maximum allowed number of points is 20. A typical power curve diagram is shown below.

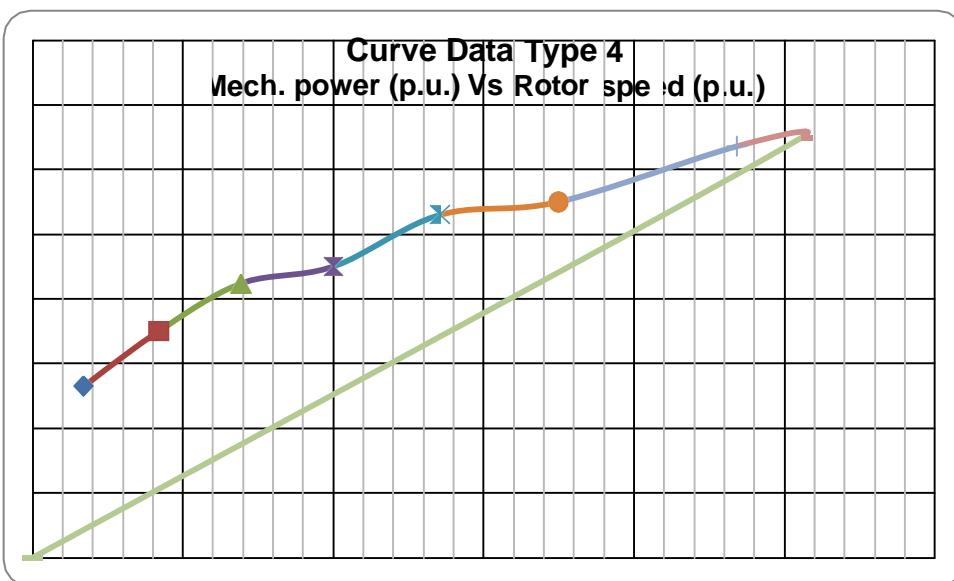


Data streams for curve type 4

Table 3.12 – Curve data for curve type 4

Col No.	Operating Mechanical Power Generation (p.u.)	Operating Rotor Speed (p.u.)
1	0.0678	0.53
2	0.1678	0.7
3	0.2775	0.848
4	0.4	0.9
5	0.5421	1.06
6	0.7	1.1
7	0.9367	1.272
8	1.0238	1.3

The maximum allowed number of points is 20. A typical operating mechanical power generation Vs Operating rotor speed curve diagram is shown below.

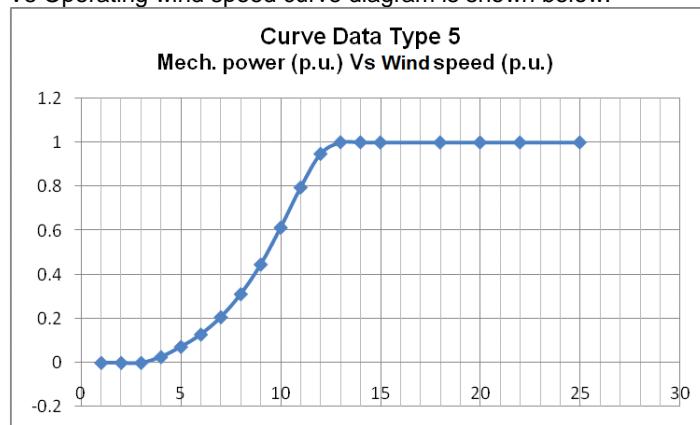


Data streams for curve type 5

**Table 3.12 – Curve data for curve type 5**

Col No.	Operating Wind Speed (m/s)	Mechanical Power Generation (p.u.)
1	1	0
2	2	0
3	3	0
4	4	0.026403
5	5	0.072607
6	6	0.128383
7	7	0.206931
8	8	0.311551
9	9	0.445875
10	10	0.613201
11	11	0.79538
12	12	0.948185
13	13	1.00066
14	14	1.00066
15	15	1
16	18	1
17	20	1
18	22	1
19	25	1

The maximum allowed number of points is 20. A typical operating mechanical power generation Vs Operating wind speed curve diagram is shown below.



## 4. INPUT/OUTPUT FILES

Table 4.1 gives extensions of different input and output files used by **POWERTRS**.

<b>Table 4.1: Input and Output Files of POWERTRS</b>			
<b>Sl. No.</b>	<b>File Extension</b>	<b>Mode</b>	<b>Description</b>
1.	".datX"	Input	Program input file
2.	".outX"	Output	Program output (general report) file
3.	"TM.BIN" Machine Binary file "TL.BIN" Line, Other Shunt Elements Binary file "TF.BIN" FPB Binary file and "TW.TXT" for Wind Turbine graph.	Output	Binary files having the information for plotting using MiP-PSCT graph module - MIGRAPH

".outX" file contains -

- Input data to the program, in the order the data is read.
- Computed values for machines, like terminal voltage, internal angle, frequency, mechanical power, electrical power etc.
- Flows, impedances in selected lines.
- Tripping information
- Negative and zero sequence flows for SLG fault.
- SVC output.

".BIN" files refer to graphic output files, whose format is compatible to MiP-PSCT's graphic utility. All the variables of the machines and the lines connected to the machine buses selected for plotting are written to two different binary files. For machines the binary plot file is "TM.BIN" and for lines it is "TL.BIN" where M of and L of TRSPLIT are distinct for machines and lines respectively. The variables written to the plot files are listed in table 4.2 and 4.3 for machines and lines respectively.

<b>Table 4.2 : Machine variables written to the binary ("TM.BIN") files</b>	
<b>Sl.No.</b>	<b>Description</b>
1.	Time in Seconds
2.	Machine terminal voltage in pu
3.	Machine terminal angle in degrees
4.	Machine internal angle for swing curve in degrees
5.	Machine frequency in Hz.
6.	Machine electrical power in MW
7.	Machine reactive power in Mvar
8.	Machine Mechanical power in MW

9	Machine field voltage in pu
10	Machine current magnitude in A
11	Machine Apparent Power in MVA
12	Motor slip in p.u *
13	Motor electrical torque in pu *
14	Motor mechanical torque in pu *

\* Plotted only for motors

In case of line flow plots, the variables written to the binary file (TRSPLTL.BIN) are given in table 4.3.

<b>Table 4.3: Machine variables written to the binary (“TL.BIN”) files</b>	
<b>Sl.No.</b>	<b>Description</b>
1.	Time in s
2.	Bus voltage in pu
3.	Bus frequency in Hz
4.	Current in A
5.	Real power in MW
6.	Reactive power in MVar
7.	Resistance in pu
8.	Reactance in pu

In case of line flow plots, the variables written to the binary file (TRSPLTL.BIN) are given in table 4.4.

<b>Table 4.4: Wind Turbine Generator variables written to the (“TW.TXT”) files</b>	
<b>Sl.No.</b>	<b>Description</b>
1.	Time in Seconds
2.	WTG terminal voltage in pu
3.	WTG terminal angle in degrees
4.	WTG wind speed in m/s
5.	WTG turbine shaft speed in pu
6.	WTG generator shaft speed in pu
7.	WTG electrical power in MW
8.	WTG reactive power in Mvar
9.	WTG mechanical power in MW
10.	WTG current magnitude in A
11.	Time in Seconds

For viewing the results by graph, graph module - Migraph has to be invoked. While importing the file, anyone of the binary file can be selected at a time. The variables list will be displayed in the screen which user can select according to the requirement.

## Error Messages

If the program while execution traces any error, an error message is written to the report file and further execution of the program is terminated. The error messages, which are traced by the program, are printed in the following format -

Error Number	Error Message	Error Description
--------------	---------------	-------------------

Error number is a number by which the error is identified. The nature of error is given in the error message. An error description specific to user/application is also given. The errors identified by the program are -

- [Error No. 0] Parameter passing error: If there is an error in passing parameters to the program, then an error is reported. In the description, the missing parameter is named.
- [Error No. 1] Input file opening error: If the input data file name specified by the user is not found or if an error occurs while the input file is opened, this message is generated. If there is more than one input file for the program then, the description specifies missing input file.
- [Error No. 2] Output file opening error: If an error occurs while opening the output file, this message is generated.
- [Error No. 3] Too less parameters to read: If the data provided is insufficient then, this error is displayed. The input data 'stream' for which data is insufficient is also described in the error message.
- [Error No. 4] Memory allocation error : If memory is not allocated for a variable for which dynamic memory allocation is done, this error message is given. The variable for which memory allocation is not successfully done is mentioned in the error description.
- [Error No. 5] Invalid character : If an invalid character data is present in the input data file then this message is generated. The data item for which invalid character is entered is also mentioned in the error message.
- [Error No. 6] Invalid number : If an invalid integer data is present in the input data file then this message is displayed. The data item for which invalid integer data is given is also mentioned in the error message.
- [Error No. 7] Invalid value : If the data given exceeds the limits mentioned for each item mentioned under different streams, an error message is given along with a description of the data item.

- [Error No. 8] Division by zero : During a mathematical operation, if division by zero occurs, then this error is generated. The variable, which may have caused this condition, is mentioned in the error description.
- [Error No. 9] Diverging error : This message is generated if no convergence is observed after a specified number of iterations.
- [Error No. 10] Error in data, Results not okay : If an erroneous input data is present which doesn't come under any of the above mentioned categories as a result of which wrong results are obtained, then this message is generated.

These errors are displayed in the output file mentioned by the user. Some of the common error messages and their probable reason for occurrence are -

ERROR [1] : Input file opening\_error - Input file not opened for reading. is written to the report file. If the program expects data to be read from input file, but has not provided data and end of file is reached, then this error message.

ERROR [3] : Too less parameters to read - Insufficient data provided for Stream is written to the report file. If the from/to bus of a transformer specified by the user doesn't exist in the bus data stream, then an error message

ERROR [6] : Invalid number - Invalid bus id specified is written to the report file.

## 5. Case Study

In this section, a sample IEEE power system network (Reference : J. Duncan Glover, "A Personal Computer Software package for Power Engineering Education, IEEE Transactions on Power System, Vol. 3, No. 4, November 1988, PP. 1864 - 1871) is considered to explain the execution and analysis of results of **POWERTRS**. The single line diagram of the sample network considered is given in figure 5.1. Tables 5.1 gives input data file and Table 5.2 gives output results file respectively.

A three phase fault is applied at the generating bus 1 at time  $t = 0.10$  seconds, and removed after 0.1second duration. A graphical representation of the swing curve for generator 1 is given in figure 5.2.

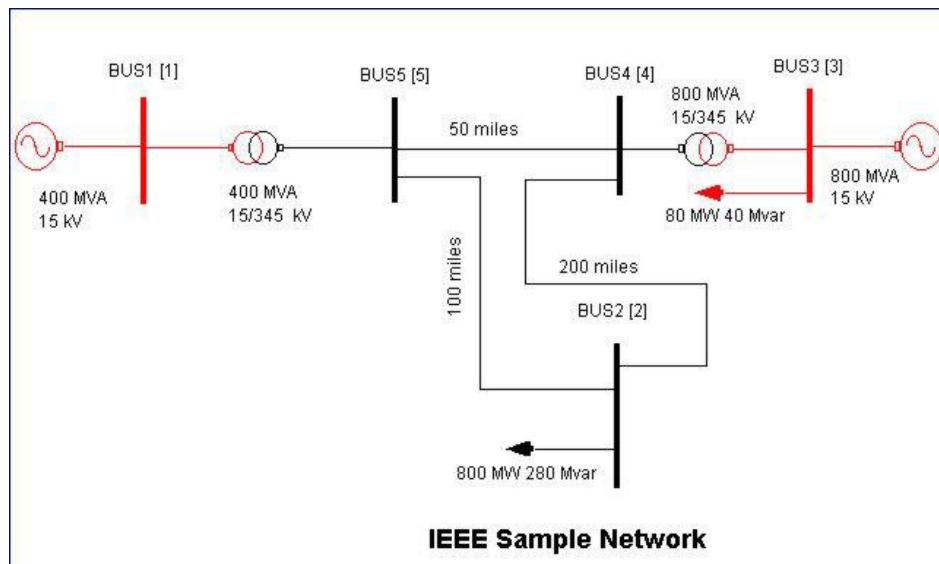


Figure 5.1

### Load Flow Results

#### BUS VOLTAGES AND POWERS

NODE NO.	FROM NAME	V-MAG P.U.	ANGLE DEGREE	MW GEN	MVAR GEN	MW LOAD	MVAR LOAD	MVAR COMP
1	Bus1	1.0000	0.00	388.983	295.503	0.000	0.000	0.000
>	2	Bus2	0.9227	-19.53	0.000	0.000	800.000	280.000
@	3	Bus3	1.0500	-0.29	520.000	55.566	80.000	40.000
	4	Bus4	1.0462	-2.57	0.000	0.000	0.000	0.000
#	5	Bus5	1.0505	-4.49	0.000	0.000	0.000	0.000

#### TRANSFORMER FLOWS AND TRANSFORMER LOSSES

SLNO	CS	FROM NODE	FROM NAME	TO NODE	TO NAME	FORWARD MW	LOSS MW	% MVAR
<b>LOADING</b>								
1	1	5	Bus5	1	Bus1	-385.403	-247.777	3.5794
81.4#								47.7255
2	1	4	Bus4	3	Bus3	-438.684	2.011	1.3183
41.9^								17.5768

#### LINE FLOWS AND LINE LOSSES

SLNO	CS	FROM NODE	FROM NAME	TO NODE	TO NAME	FORWARD MW	LOSS MW	% MVAR
<b>LOADING</b>								
--								
3	1	5	Bus5	4	Bus4	-143.670	9.088	0.4436
12.2&								-43.4296
4	1	4	Bus4	2	Bus2	294.554	50.506	8.8542
28.0^								-68.9760
5	1	5	Bus5	2	Bus2	529.045	238.689	14.7779
552.5!								78.1802

Table 5.1: Transient Stability Study Input file - 1Glove0t.dat0

```

TRANSIENT STABILITY STUDIES
CASE NO : 1      CONTINGENCY : 0      SCHEDULE NO : 0
CONTINGENCY NAME : Base Case
VERSION 8.1

```

```

%% First Power System Network
% COMMON SYSTEM SPECIFICATIONS

% (1)Maximum Bus Id (2) No of Buses (3) No of 2WdgTr
% (4) NUMBER OF 3 WIND. TRANSFORMERS (5) NUMBER OF TRANSMISSION LINES
% (6) NUMBER OF SERIES REACTORS (7) NUMBER OF SERIES CAPACITORS
% (8) NUMBER OF CIRCUIT BREAKERS (9) NUMBER OF SHUNT REACTORS
% (10) NUMBER OF SHUNT CAPACITORS (11) NUMBER OF SHUNT IMPEDANCES
% (12) NUMBER OF GENERATORS (13) NUMBER OF MOTORS
% (14) NUMBER OF LOADS(+WIND GENERATORS)(15) NUMBER OF LOAD CHARACTERISTICS
% (16) NUMBER OF UNDER FREQUENCY RELAYS (17) NUMBER OF VOLTAGE RELAYS
% (18) NUMBER OF OVER CURRENT RELAYS (19) NUMBER OF DISTANCE RELAYS
% (20) NUMBER OF FILTERS (21) NUMBER OF CYCLIC LOADS
% (22) NUMBER OF VOLTAGE REGULATORS (23) NUMBER OF GOVERNORS
% (24) NUMBER OF STATIC VAR COMPENSATORS(25) NUMBER OF HVDC CONV. TERMINALS
% (26) NUMBER OF HVDC LINKS
% (27) NUMBER OF FREE PROGRAMMABLE BLOCKS
% (28) NUMBER OF WIND TURBINES(DETAILED)% (29) NUMBER OF WT CURVES
% (30) NUMBER OF DETAILED WT CURVES
      5      5      2      0      3      0      0      0      0      0
      0      2      0      2      0      0      0      0      0      0
      0      0      0      0      0      0      0      0      0      0

% CONTROL INPUTS
% (1) No of Zones (2) No of Disturb (3) No of VIZS Out (4) No of LF iter
% (5) No of Time Steps
      1      2      5     10     10

% (6) Load Type during Post. Dist. (7) LF Print opt (8) VI print opt
% (9) Data Print opt (10) Swing Ref Bus
      0      1      1      1      0

% V_I_Z BUS DATA
      1      2      3      4      5

% MODEL SELECTION PARAMETERS
% (1) Base MVA (2)Base Frequency (3) R/X Ratio (4) CB R (5) CB X
4.0000e+002 50.0000 0.0500 0.0000e+000 1.0000e-004

% (5) Init P Tol (6) Init Q Tol (7) Post P Tol (8) Post Q Tol
1.0000e-004 1.0000e-004 1.0000e-004 1.0000e-004

% VARIABLE TIME STEP DATA
% End Time      TimeStep
5.0000e-001 2.0000e-003 1.0000e+000 2.0000e-002
2.0000e+000 2.0000e-002 3.0000e+000 2.0000e-002

```

---

```

%Zonal Multiplication Factors
% 1.Zone Numbers 2.PLoad 3.QLoad 4.PGen 5.QGen 6.ShRea 7.ShCap 8
Compensation
    0   1.0000   1.0000   1.0000   1.0000   1.0000   1.0000   1.0000
    1   1.0000   1.0000   1.0000   1.0000   1.0000   1.0000   1.0000

% DISTURBANCE DATA
% SlNo DistType DistTime FromBus ToBus
% New1F1 New1F2 New1F3 PoleRecType
% New2F1 New2F2 New2F3

    1   4   0.1000   1   1   0.000000e+000   1.000000e-005   0.000000e+000
0
0.000000e+000   0.000000e+000   0.000000e+000
    2   5   0.2000   1   1   0.000000e+000   1.000000e-005   0.000000e+000
0
0.000000e+000   0.000000e+000   0.000000e+000

% GENERATOR AND MOTOR BUS NUMBERS
    1   3

% BUS DATA
% BusId Islnd No Zone No Base Volt BusName
% VMag VAng PGen QGen PLd QLd QCmp

    1   1   1   15.000   Bus1
    1.000000000000e+000   0.000000000000e+000   3.889830e+002   2.955030e+002
0.000000e+000   0.000000e+000   0.00
    2   1   1   345.000   Bus2
    9.227341992785e-001   -1.952998891308e+001   0.000000e+000   0.000000e+000
8.000000e+002   2.800000e+002   0.00
    3   1   1   15.000   Bus3
    1.050000000000e+000   -2.854108260466e-001   5.200000e+002   5.556600e+001
8.000000e+001   4.000000e+001   0.00
    4   1   1   345.000   Bus4
    1.046210697168e+000   -2.574152239005e+000   0.000000e+000   0.000000e+000
0.000000e+000   0.000000e+000   0.00
    5   1   1   345.000   Bus5
    1.050491445376e+000   -4.486125141903e+000   0.000000e+000   0.000000e+000
0.000000e+000   0.000000e+000   0.00

% 2 WDG TRANSFORMER DATA
% Status Units FromBus ToBus +veR +veX ZeroR ZeroX
% NomTap PhShift FromFreq ToFreq FromVoltRel ToVoltRel

    3   1   5   1   5.999949e-003   7.999932e-002   5.999949e-003   7.999932e-002
    1.120000e+000   0.000000e+000   0   0   0
0.00000e+000   G   D

    3   1   4   3   2.999077e-003   3.998769e-002   2.999077e-003   3.998769e-002

```

---

```

1.000000e+000 0.000000e+000 0 0 0 0
0.000000e+000 G D

% Transmission Line Data
% Status Units FromBus ToBus +veR +veX +ve B/2 ZeroR ZeroX ZeroB/2
% FromFreq ToFreq FromVoltRel ToVoltRel

3 1 5 4 9.000000e-003 1.000000e-001 5.500000e-002 0.000000e+000
0.000000e+000 0.000000e+000
0 0 0 0
3 1 4 2 3.600000e-002 4.000000e-001 2.150000e-001 0.000000e+000
0.000000e+000 0.000000e+000
0 0 0 0
3 1 5 2 1.800000e-002 2.000000e-001 1.100000e-001 0.000000e+000
0.000000e+000 0.000000e+000
0 0 0 0

% LOAD DATA
% FromBus MWLoad MVARLoad CompMVAR LoadCharNo FreqRelId VoltRelId

2 8.000000e+002 2.800000e+002 0.000000e+000 0 0 0
3 8.000000e+001 4.000004e+001 0.000000e+000 0 0 0

% Island Information
1
50.000000

% GENERATOR DATA
%FromBus ModelType Units MVA H +veR xd` xq` Xn
% Ro Xo DampFact Xd Xq Xp Xd'' xq''
% Tdo' Tqo' Tdo'' Tqo'' FreqRel VoltRel

1 1 1 4.000000e+002 5.000000e+001 0.000000e+000 8.000000e-003 1.200000e-
002 4.000000e-002
0.000000e+000 4.000000e-002 1.500000e+000 4.000000e-001 4.000000e-002
2.000000e-002 4.000000e-003 4.000000e-002
1.000000e-003 2.000000e-003 0.000000e+000 1.000000e-004 0 0
3 1 1 4.000000e+002 5.000000e+001 0.000000e+000 8.000000e-003 1.200000e-
002 4.000000e-002
0.000000e+000 4.000000e-002 1.500000e+000 4.000000e-001 4.000000e-002
8.000000e-002 4.000000e-003 4.000000e-002
1.000000e-003 1.000000e-003 0.000000e+000 1.000000e-004 0 0

% Wind Turbine Data
-----
---
```

Table 5.2: Transient Stability Study Outut file - 1Glove0t.out0

Date and Time : Wed Apr 30 10:59:48 2014

TRANSIENT STABILITY STUDIES  
CASE NO : 1 CONTINGENCY : 0 SCHEDULE NO : 0  
CONTINGENCY NAME : Base Case

VERSION NUMBER : 8.1

% First Power System Network

LARGEST BUS NUMBER	:	5
ACTUAL NUMBER OF BUSES	:	5
NUMBER OF 2 WIND. TRANSFORMERS	:	2
NUMBER OF 3 WIND. TRANSFORMERS	:	0
NUMBER OF TRANSMISSION LINES	:	3
NUMBER OF SERIES REACTORS	:	0
NUMBER OF SERIES CAPACITORS	:	0
NUMBER OF CIRCUIT BREAKERS	:	0
NUMBER OF SHUNT REACTORS	:	0
NUMBER OF SHUNT CAPACITORS	:	0
NUMBER OF LINE REACTORS	:	0
NUMBER OF GENERATORS	:	2
NUMBER OF MOTORS	:	0
NUMBER OF LOADS	:	2
NUMBER OF LOAD CHARACTERISTICS	:	0
NUMBER OF UNDER FREQUENCY RELAYS	:	0
NUMBER OF VOLTAGE RELAYS	:	0
NUMBER OF OVER CURRENT RELAYS	:	0
NUMBER OF DISTANCE RELAYS	:	0
NUMBER OF FILTERS	:	0
NUMBER OF CYCLIC LOADS	:	0
NUMBER OF VOLTAGE REGULATORS	:	0
NUMBER OF GOVERNORS	:	0
NUMBER OF SHUNT FACT DEVICES	:	0
NUMBER OF HVDC CONV. TERMINALS	:	0
NUMBER OF HVDC LINKS	:	0
NUMBER OF FREE PROGRAMMABLE BLOCKS	:	0
NUMBER OF WIND TURBINES	:	0

No. of Zones	:	1
No. of Disturbances	:	2
No. of Nodes for V-I-Z-S output	:	5
No. of Iterations in Load Flow Analysis	:	10
No. of Time Steps for Print	:	10
Index for Load type during post-disturbance	:	0
Index for Load Flow Print	:	1
Index for Voltage Impedance Print	:	1
Index for Data details Print	:	1
Reference swing bus	:	0

---

Base MVA : 400.0000  
 Rated system frequency : 50.0000  
 Transformer R/X : 0.0500  
 Circuit breaker resistance : 0.0000  
 Circuit breaker reactance : 0.0001  
 Tolerance - Real Power (pu) - initial : 0.0001  
 Tolerance - Reactive Power (pu) - initial : 0.0001  
 Tolerance - Real Power (pu) - post-distb : 0.0001  
 Tolerance - Reactive Power (pu) - post-distb : 0.0001

---

Variable Time Step (Seconds)

From Time	To Time	Time Step
0.00000*	0.50000	0.00200
0.50000*	1.00000	0.02000
1.00000*	2.00000	0.02000
2.00000*	3.00000*	0.02000

---

Zonal Wise Demand Multiplication Factors :

Zone Number	P-DM	Q-DM	P-GM	Q-GM	SR_M	SC-M	C-DM
0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
1	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000

---

Disturbance Description

Dist. Type	Description
1.	Change in transformer/line parameters
2.	Change in shunt impedance load
3.	Change in load P and Q values
4.	Fault creation at a bus
5.	Fault clearing at a bus
6.	Change in number of generator sets at a bus
7.	Complete generation outage at a bus
8.	Simulation of single line to ground fault
9.	Clearing of single-line-to-ground fault and single pole opening
10.	SLG fault clearing or recloser of the line
11.	Loss of excitation at a generator
12.	Change in load model data
13.	Starting of the motor
14.	Stopping of the motor
15.	Change in motor torque T0
16.	Series faults
17.	Clearing of series faults
18.	Change in generation
19.	Asymmetrical faults like LL and LLG
20.	Clearing asymmetrical faults like LL and LLG

---

Dist. No.	Dist. Type	Time Sec.	From No.	To No.	New New Z.re New P.MW	New Z.im New MVAR	B/2 New Comp	Rec. Type
1	4	0.1000	1	1	0.00000 0.00000	0.00001 0.00000	0.00000 0.00000	0
2	5	0.2000	1	1	0.00000 0.00000	0.00001 0.00000	0.00000 0.00000	0

Generator Bus Numbers : 1 3

Bus No.	Island	Zone	Rated-Kv	Name	Vmag-pu	Vang-Deg	Pgen-MW	Qgen-MR
					P1-MW	Q1-MVAR	Comp-MR	
1	1	1	15.000	Bus1	1.00000 0.000	0.000 0.000	388.983 0.000	295.503 0.000
2	1	1	345.000	Bus2	0.92273 800.000	-19.530 280.000	0.000 0.000	0.000 0.000
3	1	1	15.000	Bus3	1.05000 80.000	-0.285 520.000	520.000 40.000	55.566 0.000
4	1	1	345.000	Bus4	1.04621 0.000	-2.574 0.000	0.000 0.000	0.000 0.000
5	1	1	345.000	Bus5	1.05049 0.000	-4.486 0.000	0.000 0.000	0.000 0.000

#### TRANSFORMER DATA ON 400.000 MVA BASE

SLNO*	STAT	#CKT	FROM	NAME	RP-PU	XP-PU	RZ-PU	XZ-PU		
					TAP	PHASE-SH	F-FREQ-V	T-FREQ-V		
1	3	1	5	Bus5	1	Bus1	0.00600 1.120	0.08000 0.00000	0.00600 0- 0	0.08000 0- 0
0 G D										
2	3	1	4	Bus4	3	Bus3	0.00300 1.000	0.03999 0.00000	0.00300 0- 0	0.03999 0- 0
0 G D										

TRANSMISSION LINE DATA ON 400.000 MVA BASE									
SLNO*	STAT	#CKT	FROMNAME	TO	NAME	RP-PU	XP-PU	BP/2-PU	
						R0-PU	X0-PU	B0/2-PU	F-FREQ-V
1	3	1	5	Bus5	4	Bus4	0.00900	0.10000	0.05500
						0.00000	0.00000	0.00000	0- 0
2	3	1	4	Bus4	2	Bus2	0.03600	0.40000	0.21500
						0.00000	0.00000	0.00000	0- 0
3	3	1	5	Bus5	2	Bus2	0.01800	0.20000	0.11000
						0.00000	0.00000	0.00000	0- 0

LOAD DATA							
SLNO	NODE	BUS	NAME	P-MW	Q-MVAR	COMPMVAR	LOADCHAR
1	2	Bus2		800.000	280.000	0.000	0 0- 0
2	3	Bus3		80.000	40.000	0.000	0 0- 0

Total islands in the system : 1

Frequency : 50.00

Machine Data on its own MVA rating

Notation used in the generator data print

H : Inertia constant in seconds.

Ra : Generator resistance in pu.

xd' : Direct axis transient reactance in pu.

xq' : Quadrature axis transient reactance in pu.

xn : Negative sequence reactance in pu.

R0 : Zero sequence resistance in pu.

x0 : Zero sequence reactance in pu.

df : Damping factor in pu.

xd : Direct axis reactance in pu.

xq : Quadrature axis reactance in pu.

xp : Potier reactance in pu.

xd" : Direct axis sub-transient reactance in pu.

xq" : Quadrature axis sub-transient reactance in pu.

tdo' : Direct axis transient open circuit time constant in seconds.

tqo' : Quadrature axis transient open circuit time constant in seconds.

tdo" : Direct axis sub-transient time constant in seconds.

tqo" : Quadrature axis sub-transient time constant in seconds.

Notation used in the motor data print

H : Inertia constant in seconds.

r1 : Stator resistance in pu.

x1 : Stator reactance in pu.

r2 : Rotor resistance in pu.

x2 : Rotor reactance in pu.

xm : Magnetizing reactance in pu.

Slip: Initial motor slip in pu.

pm : Motor rated power in in pu.

---

Generator bus no. : 1 Bus name : Bus1 Model type : 1 Units : 1  
MVA : 400.000 H : 50.00000, Ra : 0.00000 xd' : 0.00800 xq' :  
0.01200  
xn : 0.04000 Ro : 0.00000, x0 : 0.04000 df : 1.50000  
xd : 0.40000 xq : 0.04000 xp : 0.02000 xd" : 0.00400 xq" :  
0.04000  
tdo' : 0.00100 tgo' : 0.00200 tdo" : 0.00000 tgo" : 0.00010  
Frequency Relay No : 0 Voltage Relay NO : 0

Generator bus no. : 3 Bus name : Bus3 Model type : 1 Units : 1  
MVA : 400.000 H : 50.00000, Ra : 0.00000 xd' : 0.00800 xq' :  
0.01200  
xn : 0.04000 Ro : 0.00000, x0 : 0.04000 df : 1.50000  
xd : 0.40000 xq : 0.04000 xp : 0.08000 xd" : 0.00400 xq" :  
0.04000  
tdo' : 0.00100 tgo' : 0.00100 tdo" : 0.00000 tgo" : 0.00010  
Frequency Relay No : 0 Voltage Relay NO : 0

---



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---

kp 0 kq 0 Iterations 1 dpmx 0.000084 dqmx 0.000024

---

Iter #	Pmax	Pmax-bus	Qmax	Qmax-bus	Vmax	Vmax-bus
1	0.00008	2	0.00002	2	0.00000	0

---

#### Results of load flow study

No.	Name	Island	Zone	Rated KV	Vact-KV	V-mag	Ang-Deg	Pgen	Qgen	Pload	Qload	Q-comp
1	Bus1	1	1	15.000	15.000	1.00000	0.000	388.983	295.503	0.000	0.000	0.000
2	Bus2	1	1	345.000	318.343	0.92273	-19.530	0.000	0.000	800.000	280.000	0.000
3	Bus3	1	1	15.000	15.750	1.05000	-0.285	520.000	55.566	80.000	40.000	0.000
4	Bus4	1	1	345.000	360.943	1.04621	-2.574	0.000	0.000	0.000	0.000	0.000
5	Bus5	1	1	345.000	362.420	1.05049	-4.486	0.000	0.000	0.000	0.000	0.000

Line flow and line losses								
From Node Name	From Node Name	To Node Name	To Node Name	Ckts No.	Forward FlowMW	Forward FlowMVAR	MWLoss MW	MVARLoss
1 Bus1	5	Buss5		1	388.98	295.50	3.579	47.726
2 Bus2	4	Bus4		1	-285.70	-119.48	8.854	-68.976
2 Bus2	5	Buss5		1	-514.27	-160.51	14.778	78.180
3 Bus3	4	Bus4		1	440.00	15.57	1.318	17.577
4 Bus4	3	Buss3		1	-438.68	2.01	1.318	17.577
4 Bus4	5	Buss5		1	144.11	-52.52	0.444	-43.430
4 Bus4	2	Bus2		1	294.55	50.51	8.854	-68.976
5 Bus5	1	Bus1		1	-385.40	-247.78	3.579	47.726
5 Bus5	4	Bus4		1	-143.67	9.09	0.444	-43.430
5 Bus5	2	Bus2		1	529.04	238.69	14.778	78.180

Total power generation	:	908.98 MW	351.07 MVAR
Total reactive compensation	:		0.00 MVAR
Total capacitive compensation	:		0.00 MVAR
Total inductive compensation	:		0.00 MVAR
Total power losses	:	28.97 MW	31.08 MVAR
Over all P mismatch	:	0.010 MW	
Percentage P losses	:	3.188	

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

Notation used for generator graph files

Vbname.grp : Voltage Magnitude

Abname.grp : Voltage Angle

Dbname.grp : Swing curve

Fbname.grp : Frequency plot

Pbname.grp : Electrical Power P - MW

Qbname.grp : Electrical Power Q - MVAR

Mbname.grp : Mechanical Power - MW

Ebname.grp : Field Voltage - kV

Sbname.grp : Motor Slip - PU

Ibname.grp : Current Magnitude - Amps

Tbname.grp : Apparent power - MVA

wherein bname is the bus name.

Notation used for line flow graph files

LPxFV.grp : Voltage Magnitude From Bus

LPxTV.grp : Voltage Magnitude To Bus

LPxFI.grp : Forward flow current magnitude

LPxFF.grp : Frequency in Hz. From Bus

LPxFP.grp : Forward real power flow

LPxFR.grp : Forward reactive power flow  
 LPxFZ.grp : Forward impedance loci (r-x plot)  
 wherein x is the line number in the plot list as follows

1	Bus1	5	Bus5	x : 1
2	Bus2	4	Bus4	x : 2
		5	Bus5	x : 3
3	Bus3	4	Bus4	x : 4
4	Bus4	3	Bus3	x : 5
		5	Bus5	x : 6
		2	Bus2	x : 7
5	Bus5	1	Bus1	x : 8
		4	Bus4	x : 9
		2	Bus2	x : 10

-----  
 Time = 0.00000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/PU
1	Bus1	1	0	0.443	50	389	296	389	1.01
3	Bus3	1.05	-0.285	0.255	50	520	55.6	520	1.05

Maximum rotor angle difference : 0.18861 b/w buses : 1 and 3

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

Time = 0.02000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	0	0.443	50	389	296	389	1.01
3	Bus3	1.05	-0.285	0.255	50	520	55.6	520	1.05

Maximum rotor angle difference : 0.18861 b/w buses : 1 and 3

Island 1 Common system frequency 50.000

-----  
 Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name      Voltage Angle      To      Name      Voltage      Angle      Current      Angle  
                   Zl-real      Zl-im      P      Q

1	Bus1	1.000	0.00	5	Bus5	1.05	-4.5	1.9e+004	-37
						0.65	0.5	3.9e+002	3e+002
2	Bus2	0.923	-19.53	4	Bus4	1.05	-2.6	5.6e+002	1.4e+002
						-1	-0.42	-2.9e+002	-
1.2e+002				5	Bus5	1.05	-4.5	9.8e+002	1.4e+002
						-0.6	-0.19	-5.1e+002	-
1.6e+002									
3	Bus3	1.050	-0.29	4	Bus4	1.05	-2.6	1.6e+004	-2.3
						1	0.035	4.4e+002	16
4	Bus4	1.046	-2.57	3	Bus3	1.05	-0.29	7e+002	1.8e+002
						-1	0.0046	-4.4e+002	-
2				5	Bus5	1.05	-4.5	2.5e+002	17
						2.7	-0.98	1.4e+002	-53
				2	Bus2	0.923	-20	4.8e+002	-12
						1.4	0.25	2.9e+002	51
5	Bus5	1.050	-4.49	1	Bus1	1	0	7.3e+002	1.4e+002
						-0.81	-0.52	-3.9e+002	-
2.5e+002				4	Bus4	1.05	-2.6	2.3e+002	1.8e+002
						-3.1	0.19	-1.4e+002	-
9.1				2	Bus2	0.923	-20	9.2e+002	-29
						0.69	0.31	5.3e+002	2.4e+002

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024



Time = 0.06000 Seconds

## Intermediate results for Machines

GNO	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	0	0.443	50	389	296	389	1.01
3	Bus3	1.05	-0.285	0.255	50	520	55.6	520	1.05

Maximum rotor angle difference : 0.18861 b/w buses : 1 and 3

Island 1 Common system frequency 50.000

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To Name      Voltage Angle      Current Angle

	Zl-real	Zl-im	P	Q
--	---------	-------	---	---

1	Bus1	1.000	0.00	5	Buss5	1.05	-4.5	1.9e+004	-37
						0.65	0.5	3.9e+002	3e+002
2	Bus2	0.923	-19.53	4	Bus4	1.05	-2.6	5.6e+002	1.4e+002
						-1	-0.42	-2.9e+002	-
1.2e+002				5	Buss5	1.05	-4.5	9.8e+002	1.4e+002
						-0.6	-0.19	-5.1e+002	-
1.6e+002									
3	Bus3	1.050	-0.29	4	Bus4	1.05	-2.6	1.6e+004	-2.3
						1	0.035	4.4e+002	16
4	Bus4	1.046	-2.57	3	Bus3	1.05	-0.29	7e+002	1.8e+002
						-1	0.0046	-4.4e+002	
2				5	Buss5	1.05	-4.5	2.5e+002	17
						2.7	-0.98	1.4e+002	-53
				2	Bus2	0.923	-20	4.8e+002	-12
						1.4	0.25	2.9e+002	51

**MiP-PSCT****TRS**

5	Bus5	1.050	-4.49	1	Bus1	1	0	7.3e+002	1.4e+002	-
2.5e+002						-0.81		-0.52	-3.9e+002	-
9.1				4	Bus4	1.05	-2.6	2.3e+002	1.8e+002	
						-3.1	0.19	-1.4e+002		
				2	Bus2	0.923	-20	9.2e+002		-29
						0.69	0.31	5.3e+002	2.4e+002	

Time = 0.08000 Seconds

## Intermediate results for Machines

Generator		Bus 1		Bus 2		Bus 3		Bus 4	
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	0	0.443	50	389	296	389	1.01
3	Bus3	1.05	-0.285	0.255	50	520	55.6	520	1.05

Maximum rotor angle difference : 0.18861 b/w buses : 1 and 3  
Island 1 Common system frequency 50.000

Voltage (pu),		Current (AMPS),		impedance (PU)		and power (MW-MVAR) for lines			
From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	0.00	5	Bus5	1.05	-4.5	1.9e+004	-37
						0.65	0.5	3.9e+002	3e+002
2	Bus2	0.923	-19.53	4	Bus4	1.05	-2.6	5.6e+002	1.4e+002
						-1	-0.42	-2.9e+002	
1.2e+002				5	Bus5	1.05	-4.5	9.8e+002	1.4e+002
						-0.6	-0.19	-5.1e+002	
1.6e+002									
3	Bus3	1.050	-0.29	4	Bus4	1.05	-2.6	1.6e+004	-2.3
						1	0.035	4.4e+002	16
4	Bus4	1.046	-2.57	3	Bus3	1.05	-0.29	7e+002	1.8e+002
						-1	0.0046	-4.4e+002	
2				5	Bus5	1.05	-4.5	2.5e+002	17
						2.7	-0.98	1.4e+002	-53
				2	Bus2	0.923	-20	4.8e+002	-12
						1.4	0.25	2.9e+002	51
5	Bus5	1.050	-4.49	1	Bus1	1	0	7.3e+002	1.4e+002
						-0.81	-0.52	-3.9e+002	
2.5e+002				4	Bus4	1.05	-2.6	2.3e+002	1.8e+002
						-3.1	0.19	-1.4e+002	
9.1				2	Bus2	0.923	-20	9.2e+002	-29
						0.69	0.31	5.3e+002	2.4e+002

kp 0 kq 0 Iterations 1 dpmax 0.000084 dgmax 0.000024

```

kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024
kp 0 kq 0 Iterations 1 dpmax 0.000084 dqmax 0.000024

```

---

Time = 0.10000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	0	0.443	50	389	296	389	1.01
3	Bus3	1.05	-0.285	0.255	50	520	55.6	520	1.05

---

Maximum rotor angle difference : 0.18861 b/w buses : 1 and 3

Island 1 Common system frequency 50.000

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	0.00	5 Bus5	1.05	-4.5	1.9e+004	-37
				0.65	0.5	3.9e+002	3e+002
2 Bus2	0.923	-19.53	4 Bus4	1.05	-2.6	5.6e+002	1.4e+002
				-1	-0.42	-2.9e+002	-
1.2e+002			5 Bus5	1.05	-4.5	9.8e+002	1.4e+002
				-0.6	-0.19	-5.1e+002	-
1.6e+002							
3 Bus3	1.050	-0.29	4 Bus4	1.05	-2.6	1.6e+004	-2.3
				1	0.035	4.4e+002	16
4 Bus4	1.046	-2.57	3 Bus3	1.05	-0.29	7e+002	1.8e+002
				-1	0.0046	-4.4e+002	-
2			5 Bus5	1.05	-4.5	2.5e+002	17
				2.7	-0.98	1.4e+002	-53
			2 Bus2	0.923	-20	4.8e+002	-12
				1.4	0.25	2.9e+002	51
5 Bus5	1.050	-4.49	1 Bus1	1	0	7.3e+002	1.4e+002
				-0.81	-0.52	-3.9e+002	-
2.5e+002			4 Bus4	1.05	-2.6	2.3e+002	1.8e+002
				-3.1	0.19	-1.4e+002	-
9.1			2 Bus2	0.923	-20	9.2e+002	-29
				0.69	0.31	5.3e+002	2.4e+002

---

```

3 phase fault 0.10000    1      Bus1
kp 1 kq 0 Iterations 10 dpmax 0.002596 dqmax 0.000095
kp 1 kq 0 Iterations 10 dpmax 0.001096 dqmax 0.000096
kp 1 kq 0 Iterations 10 dpmax 0.001084 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001074 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001066 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001060 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001056 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001055 dqmax 0.000097
kp 1 kq 0 Iterations 10 dpmax 0.001055 dqmax 0.000003
kp 1 kq 0 Iterations 10 dpmax 0.001057 dqmax 0.000004
-----
Time = 0.12000 Seconds
Intermediate results for Machines
GNo Name          Voltage Angle   Delta     Freq   Pgen   Qgen   Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.   MW     MVAR   MW       pu/P.U.
-----
 1   Bus1  0.0013  0.0469  0.475    50  0.482   65.5   389   1.01
 3   Bus3  1.01   -0.235  0.259    50   459  1.9e+003  520
1.05
-----
Maximum rotor angle difference : 0.21526 b/w buses : 1 and 3
Island 1 Common system frequency 50.005
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name          Voltage Angle   To   Name          Voltage Angle   Current Angle
                           Zl-real   Zl-im   P       Q
-----
 1   Bus1  0.001  0.05      5   Bus5  0.43   -5.6  7.4e+004   89
                           6.6e-006 -0.00027   0.06   -2.5
 2   Bus2  0.495 -19.47     4   Bus4  0.828  -1.9  7e+002  1.1e+002
                           -0.31   -0.36  -1.4e+002  -
1.5e+002
                           5   Bus5  0.43   -5.6  4.1e+002  -
1.6e+002
                           -0.64   0.5   -94   74
 3   Bus3  1.014 -0.23      4   Bus4  0.828  -1.9  7.2e+004  -79
                           0.044   0.21  3.8e+002  1.9e+003
 4   Bus4  0.828 -1.91      3   Bus3  1.01   -0.23  3.1e+003  1e+002
                           -0.041  -0.17  -3.6e+002  -
1.5e+003
                           5   Bus5  0.43   -5.6  2.6e+003  -83
                           0.034   0.21  2.1e+002  1.3e+003
                           2   Bus2  0.495  -19  5.4e+002  -58
                           0.57   0.85  1.5e+002  2.2e+002
 5   Bus5  0.430 -5.61      1   Bus1  0.0013  0.047  2.9e+003  -91
                           0.0075  0.1   55  7.3e+002
                           4   Bus4  0.828  -1.9  2.7e+003  97
                           -0.024  -0.1  -1.5e+002  -
6.7e+002
                           2   Bus2  0.495  -19  4.4e+002  26
-----
```

0.55 -0.34 97 -60

---

```

kp 1 kq 0 Iterations 10 dpmax 0.001061 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001068 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001076 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001086 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001097 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001111 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001126 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001144 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001163 dqmax 0.000004
kp 1 kq 0 Iterations 10 dpmax 0.001183 dqmax 0.000005
-----
```

Time = 0.14000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	0.0013	0.0959	0.576	50	0.534	65.5	389	1.01
3	Bus3	1.01	-0.22	0.275	50		459	1.9e+003	520
		1.05							

---

Maximum rotor angle difference : 0.30068 b/w buses : 1 and 3

Island 1 Common system frequency 50.011

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
						Zl-real	Zl-im	P	Q
1	Bus1	0.001	0.10	5	Bus5	0.43	-5.6	7.4e+004	89
						6.8e-006	-0.00027	0.062	-2.5
2	Bus2	0.495	-19.46	4	Bus4	0.828	-1.9	7e+002	1.1e+002
						-0.31		-0.36	-1.4e+002
1.5e+002				5	Bus5	0.43		-5.6	4.1e+002
1.6e+002									-
3	Bus3	1.014	-0.22	4	Bus4	0.828	-1.9	7.2e+004	-79
						0.044		0.21	3.8e+002
4	Bus4	0.828	-1.89	3	Bus3	1.01	-0.22	3.1e+003	1e+002
						-0.041		-0.17	-3.6e+002
1.5e+003				5	Bus5	0.43	-5.6	2.6e+003	-83
						0.034		0.21	2.1e+002
5	Bus5	0.430	-5.59	1	Bus1	0.0013	0.096	2.9e+003	-91
						0.0075		0.1	55
				4	Bus4	0.828	-1.9	2.7e+003	7.3e+002
									97

---

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6.7e+002 2 Bus2 0.495 -19 4.4e+002 26

```

0.55   -0.34    97   -60
kp 1 kq 0 Iterations 10 dpmax 0.001206 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001230 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001256 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001283 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001312 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001343 dqmax 0.000005
kp 1 kq 0 Iterations 10 dpmax 0.001375 dqmax 0.000006
kp 1 kq 0 Iterations 10 dpmax 0.001409 dqmax 0.000006
kp 1 kq 0 Iterations 10 dpmax 0.001445 dqmax 0.000006
kp 1 kq 0 Iterations 10 dpmax 0.001482 dqmax 0.000006
-----
Time = 0.16000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle Delta     Freq Pgen Qgen Pmech Efd/Slip
      pu        Degree  Degree Hzs.  MW  MVAR  MW  pu/P.U.
-----
1 Bus1 0.0013  0.155  0.747  50  0.655  65.5 389  1.01
3 Bus3  1.01   -0.194  0.302  50   459  1.9e+003 520
1.05
-----
Maximum rotor angle difference : 0.44496 b/w buses : 1 and 3
Island 1 Common system frequency 50.017
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle To Name      Voltage Angle Current Angle
      pu        Degree   pu        Degree  Zl-real Zl-im   P       Q
-----
1 Bus1 0.001  0.15    5 Bus5  0.43   -5.6 7.4e+004 89
                           6.9e-006 -0.00027  0.063 -2.5
2 Bus2  0.495 -19.43   4 Bus4  0.828  -1.9 7e+002 1.1e+002
                           -0.31   -0.36 -1.4e+002 -
1.5e+002
                           5 Bus5  0.43   -5.6 4.1e+002 -
1.6e+002
                           -0.64   0.5   -94   74
3 Bus3  1.014 -0.19    4 Bus4  0.828  -1.9 7.2e+004 -79
                           0.044   0.21 3.8e+002 1.9e+003
4 Bus4  0.828 -1.87    3 Bus3  1.01  -0.19 3.1e+003 1e+002
                           -0.041  -0.17 -3.6e+002 -
1.5e+003
                           5 Bus5  0.43   -5.6 2.6e+003 -83
                           0.034   0.21 2.1e+002 1.3e+003
                           2 Bus2  0.495  -19 5.4e+002 -58
                           0.57   0.85 1.5e+002 2.2e+002
5 Bus5  0.430 -5.56    1 Bus1  0.0013  0.15 2.9e+003 -91
                           0.0075  0.1   55 7.3e+002
                           4 Bus4  0.828  -1.9 2.7e+003 97
                           -0.024  -0.1 -1.5e+002 -
6.7e+002
                           2 Bus2  0.495  -19 4.4e+002 26
-----
```

```

0.55      -0.34      97      -60
kp 1 kq 0 Iterations 10 dpmx 0.001520 dqmax 0.000006
kp 1 kq 0 Iterations 10 dpmx 0.001560 dqmax 0.000007
kp 1 kq 0 Iterations 10 dpmx 0.001601 dqmax 0.000007
kp 1 kq 0 Iterations 10 dpmx 0.001644 dqmax 0.000007
kp 1 kq 0 Iterations 10 dpmx 0.001688 dqmax 0.000007
kp 1 kq 0 Iterations 10 dpmx 0.001734 dqmax 0.000008
kp 1 kq 0 Iterations 10 dpmx 0.001781 dqmax 0.000008
kp 1 kq 0 Iterations 10 dpmx 0.001830 dqmax 0.000008
kp 1 kq 0 Iterations 10 dpmx 0.001880 dqmax 0.000009
kp 1 kq 0 Iterations 10 dpmx 0.001931 dqmax 0.000009
-----
Time = 0.18000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu       Degree   Degree   Hzs.    MW      MVAR    MW      pu/P.U.
----- -----
1     Bus1  0.0013    0.231    0.988      50    0.836    65.5    389    1.01
3     Bus3  1.01     -0.157      0.34      50    459  1.9e+003    520
1.05
-----
Maximum rotor angle difference : 0.64808 b/w buses : 1 and 3
Island 1 Common system frequency 50.022
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To Name      Voltage Angle   Current   Angle
                           Zl-real   Zl-im     P        Q
----- -----
1     Bus1  0.001    0.23      5     Bus5      0.43    -5.5  7.4e+004    89
                           7.1e-006 -0.00027    0.065    -2.5
2     Bus2  0.495   -19.39     4     Bus4      0.828    -1.8  7e+002  1.1e+002
                           -0.31      -0.36   -1.4e+002   -
1.5e+002
                           5     Bus5      0.43    -5.5  4.1e+002   -
1.6e+002
                           -0.64      0.5     -94     74
3     Bus3  1.014   -0.16      4     Bus4      0.828    -1.8  7.2e+004   -78
                           0.044      0.21  3.8e+002  1.9e+003
4     Bus4  0.828   -1.83      3     Bus3      1.01    -0.16  3.1e+003  1e+002
                           -0.041      -0.17  -3.6e+002   -
1.5e+003
                           5     Bus5      0.43    -5.5  2.6e+003   -83
                           0.034      0.21  2.1e+002  1.3e+003
                           2     Bus2      0.495    -19  5.4e+002   -58
                           0.57      0.85  1.5e+002  2.2e+002
5     Bus5  0.430   -5.53      1     Bus1      0.0013    0.23  2.9e+003   -91
                           0.0075      0.1     55  7.3e+002
                           4     Bus4      0.828    -1.8  2.7e+003   97
----- -----
Power Research and Development Consultants Pvt. Ltd.          -0.024    -0.1  -1.5e+002
6.7e+002
                           2     Bus2      0.495    -19  4.4e+002   26
----- -----

```

					0.55	-0.34	97	-60	
kp 1	kq 0	Iterations	10	dpmx 0.001983	dqmax 0.000010				
kp 1	kq 0	Iterations	10	dpmx 0.002037	dqmax 0.000011				
kp 1	kq 0	Iterations	10	dpmx 0.002092	dqmax 0.000011				
kp 1	kq 0	Iterations	10	dpmx 0.002148	dqmax 0.000012				
kp 1	kq 0	Iterations	10	dpmx 0.002206	dqmax 0.000013				
kp 1	kq 0	Iterations	10	dpmx 0.002265	dqmax 0.000014				
kp 1	kq 0	Iterations	10	dpmx 0.002325	dqmax 0.000015				
kp 1	kq 0	Iterations	10	dpmx 0.002386	dqmax 0.000016				
kp 1	kq 0	Iterations	10	dpmx 0.002449	dqmax 0.000017				
kp 1	kq 0	Iterations	10	dpmx 0.002512	dqmax 0.000018				
<hr/>									
Time = 0.20000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	0.0013	0.33	1.3	50	1.07	65.5	389	1.01
3	Bus3	1.01	-0.109	0.389		50	459	1.9e+003	520
1.05									
<hr/>									
Maximum rotor angle difference : 0.90999 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
<hr/>									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	0.001	0.33	5	Bus5	0.43	-5.5	7.4e+004	89
					7.3e-006	-0.00027	0.067		-2.5
2	Bus2	0.495	-19.35	4	Bus4	0.828	-1.8	7e+002	1.1e+002
					-0.31		-0.36	-1.4e+002	-
1.5e+002				5	Bus5	0.43	-5.5	4.1e+002	-
1.6e+002									
3	Bus3	1.014	-0.11	4	Bus4	0.828	-1.8	7.2e+004	-78
					0.044		0.21	3.8e+002	1.9e+003
4	Bus4	0.828	-1.78	3	Bus3	1.01	-0.11	3.1e+003	1e+002
					-0.041		-0.17	-3.6e+002	-
1.5e+003				5	Bus5	0.43	-5.5	2.6e+003	-83
					0.034		0.21	2.1e+002	1.3e+003
				2	Bus2	0.495	-19	5.4e+002	-58
					0.57		0.85	1.5e+002	2.2e+002
5	Bus5	0.430	-5.48	1	Bus1	0.0013	0.33	2.9e+003	-91
					0.0075		0.1	55	7.3e+002
				4	Bus4	0.828	-1.8	2.7e+003	97
					-0.024		-0.1	-1.5e+002	-
6.7e+002				2	Bus2	0.495	-19	4.4e+002	26

				0.55	-0.34	97	-60			
Fault removal	0.20000	1	Bus1							
kp 0 kq 0 Iterations	7	dpmx 0.000014	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000037	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000037	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000037	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000038	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000038	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000038	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000039	dqmax 0.000000							
kp 0 kq 0 Iterations	3	dpmx 0.000039	dqmax 0.000000							
Time =	0.22000 Seconds									
Intermediate results for Machines										
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.	
1	Bus1	1	1.13	1.65	50	421	296	389	1.01	
3	Bus3	1.05	-0.0666	0.446	50	488	55.4	520	1.05	
Maximum rotor angle difference : 1.19982 b/w buses : 1 and 3										
Island	1	Common system frequency		50.028						
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
		Zl-real	Zl-im			P	Q			
1	Bus1	1.000	1.13	5	Bus5	1.05 0.64	-3.7 0.45	2e+004 4.2e+002	-34 3e+002	
2	Bus2	0.923	-18.90	4	Bus4	1.05 -1	-2.2 -0.44	5.6e+002 -2.8e+002	1.4e+002 -	
1.2e+002				5	Bus5	1.05 -0.6	-3.7 -0.18	9.8e+002 -5.2e+002	1.4e+002 -	
1.6e+002	3	Bus3	1.050	-0.07	4	Bus4	1.05 1.1	-2.2 0.041	1.5e+004 4.1e+002	-2.2 15
4	Bus4	1.046	-2.19	3	Bus3	1.05 -1.1	-0.067 -0.00078	6.5e+002 -4.1e+002	1.8e+002 -	
0.29				5	Bus5	1.05 3.2	-3.7 -1.4	2e+002 1.2e+002	21 -50	
2.4e+002				2	Bus2	0.923 1.5	-19 0.25	4.7e+002 2.9e+002	-12 50	
5	Bus5	1.050	-3.74	1	Bus1	1 -0.79	1.1 -0.46	7.7e+002 -4.2e+002	1.5e+002 -	
				4	Bus4	1.05	-2.2	1.9e+002	1.8e+002	

---

-3.8                    0.15    -1.2e+002

4.5

2	Bus2	0.923	-19	9.3e+002	-28
		0.69	0.31	5.3e+002	2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000

---

Time = 0.24000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	1.46	1.99	50	430	297	389	1.01
3	Bus3	1.05	0.00485	0.509	50	479	55.5	520	1.05

---

Maximum rotor angle difference : 1.47838 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	1.46	5 Bus5	1.05	-3.5	2e+004	-33
2 Bus2	0.923	-18.72	4 Bus4	0.63	0.44	4.3e+002	3e+002
				1.05	-2.1	5.6e+002	1.4e+002
				-1	-0.44	-2.8e+002	-
1.2e+002			5 Bus5	1.05	-3.5	9.8e+002	1.4e+002
				-0.6	-0.18	-5.2e+002	-
1.6e+002							
3 Bus3	1.050	0.00	4 Bus4	1.05	-2.1	1.5e+004	-2.2
				1.1	0.043	4e+002	15
4 Bus4	1.046	-2.07	3 Bus3	1.05	0.0048	6.4e+002	1.8e+002
				-1.1	-0.0028	-4e+002	-1
			5 Bus5	1.05	-3.5	1.9e+002	22
				3.4	-1.5	1.1e+002	-49
			2 Bus2	0.923	-19	4.7e+002	-12
				1.5	0.25	2.9e+002	50
5 Bus5	1.050	-3.52	1 Bus1	1	1.5	7.8e+002	1.5e+002
				-0.78	-0.45	-4.3e+002	-
2.4e+002			4 Bus4	1.05	-2.1	1.7e+002	1.8e+002

---

3.1			-4.1		0.12	-1.1e+002			
	2	Bus2	0.923	-19	9.3e+002	-28			
			0.69	0.31	5.3e+002	2.4e+002			
kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000									
<hr/>									
Time = 0.26000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	1.79	2.32	50	438	297	389	1.01
3	Bus3	1.05	0.0829	0.579	50	471	55.6	520	1.05
<hr/>									
Maximum rotor angle difference : 1.74227 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
		Zl-real	Zl-im		P	Q			
---	---	---	---	---	---	---	---	---	---
1	Bus1	1.000	1.79	5	Bus5	1.05	-3.3	2e+004	-32
						0.63	0.42	4.4e+002	3e+002
2	Bus2	0.923	-18.53	4	Bus4	1.05	-1.9	5.5e+002	1.4e+002
						-1	-0.45	-2.8e+002	-
1.2e+002				5	Bus5	1.05	-3.3	9.9e+002	1.4e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	0.08	4	Bus4	1.05	-1.9	1.4e+004	-2.2
						1.1	0.045	3.9e+002	16
4	Bus4	1.046	-1.95	3	Bus3	1.05	0.083	6.2e+002	1.8e+002
						-1.1	-0.0049	-3.9e+002	-
1.7				5	Bus5	1.05	-3.3	1.8e+002	23
						3.5	-1.7	1e+002	-48
				2	Bus2	0.923	-19	4.7e+002	-12
						1.5	0.25	2.9e+002	50
5	Buss5	1.050	-3.30	1	Bus1	1	1.8	7.9e+002	1.5e+002
						-0.78	-0.43	-4.3e+002	-
2.4e+002				4	Bus4	1.05	-1.9	1.6e+002	1.8e+002

```

          -4.4      0.082   -1e+002    1.9
          2       Bus2      0.923   -19 9.3e+002   -27
                           0.69      0.31 5.4e+002  2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000
-----
Time = 0.28000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq   Pgen   Qgen   Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.   MW     MVAR   MW      pu/P.U.
-----
1   Bus1       1       2.11    2.65     50     446    298    389    1.01
3   Bus3      1.05    0.169   0.658     50     463    55.7   520    1.05
-----
Maximum rotor angle difference : 1.98843 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To      Name      Voltage Angle   Current Angle
                         Zl-real   Zl-im   P        Q
-----
1   Bus1       1.000    2.11    5       Bus5      1.05    -3.1 2.1e+004   -32
                               0.62     0.41 4.5e+002   3e+002
2   Bus2       0.923   -18.34   4       Bus4      1.05    -1.8 5.5e+002 1.4e+002
                               -1      -0.45 -2.8e+002   -
1.2e+002
                               5       Bus5      1.05    -3.1 9.9e+002 1.4e+002
                               -0.6     -0.18 -5.2e+002   -
1.6e+002
3   Bus3       1.050    0.17    4       Bus4      1.05    -1.8 1.4e+004   -2.2
                               1.1     0.047 3.8e+002   16
4   Bus4       1.046   -1.82    3       Bus3      1.05    0.17 6.1e+002 1.8e+002
                               -1.1    -0.0072 -3.8e+002   -
2.4
                               5       Bus5      1.05    -3.1 1.7e+002    25
                               3.7     -1.8     94    -47
                               2       Bus2      0.923    -18 4.7e+002   -12
                               1.5     0.25 2.9e+002   49
5   Bus5       1.050   -3.08    1       Bus1      1       2.1 8e+002 1.5e+002
                               -0.77    -0.42 -4.4e+002   -
2.4e+002
                               4       Bus4      1.05    -1.8 1.5e+002 1.8e+002
                               -4.7     0.038   -94    0.76
-----
```

2	Bus2	0.923	-18	9.4e+002	-27				
		0.69	0.31	5.4e+002	2.4e+002				
kp 0 kq 0 Iterations 3 dpmax 0.000054 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000056 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000060 dqmax 0.000000									
<hr/>									
Time = 0.30000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	2.41	2.96	50	453	298	389	1.01
3	Bus3	1.05	0.265	0.747	50	456	55.8	520	1.05
<hr/>									
Maximum rotor angle difference : 2.21399 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
<hr/>									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	1.000	2.41	5	Bus5	1.05	-2.9	2.1e+004	-31
						0.62	0.4	4.5e+002	3e+002
2	Bus2	0.923	-18.15	4	Bus4	1.05	-1.7	5.5e+002	1.4e+002
						-1	-0.45	-2.8e+002	-
1.2e+002				5	Bus5	1.05	-2.9	9.9e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	0.26	4	Bus4	1.05	-1.7	1.4e+004	-2.2
						1.2	0.049	3.8e+002	16
4	Bus4	1.046	-1.69	3	Bus3	1.05	0.26	6e+002	1.8e+002
						-1.2	-0.0095	-3.7e+002	-
3				5	Bus5	1.05	-2.9	1.6e+002	26
						3.9	-2	88	-46
				2	Bus2	0.923	-18	4.6e+002	-11
						1.5	0.26	2.9e+002	49
5	Bus5	1.050	-2.86	1	Bus1	1	2.4	8.1e+002	1.5e+002
						-0.77	-0.41	-4.5e+002	-
2.4e+002				4	Bus4	1.05	-1.7	1.4e+002	1.8e+002
						-5	-0.017	-88	-0.29
2	Bus2	0.923	-18	9	4e+002				-27

```

0.69      0.31 5.4e+002 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000062 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000065 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000
-----
Time = 0.32000 Seconds
Intermediate results for Machines
GNo Name          Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.    MW      MVAR    MW      pu/P.U.
----- -----
 1   Bus1           1       2.71    3.26     50      460     298     389     1.01
 3   Bus3          1.05    0.371   0.848    50      449      56     520     1.05
-----
Maximum rotor angle difference : 2.41634 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name          Voltage Angle   To     Name          Voltage Angle   Current Angle
                           pu        Degree   pu        pu        Zl-real  Zl-im    P        Q
----- -----
 1   Bus1          1.000    2.71    5   Bus5          1.05    -2.6 2.1e+004   -30
                               0.61      0.4 4.6e+002 3e+002
 2   Bus2          0.923   -17.96   4   Bus4          1.05    -1.5 5.5e+002 1.4e+002
                               -1      -0.46 -2.8e+002 -
 1.2e+002
                               5   Bus5          1.05    -2.6 9.9e+002 1.5e+002
                               -0.6      -0.18 -5.2e+002 -
 1.6e+002
 3   Bus3          1.050    0.37    4   Bus4          1.05    -1.5 1.4e+004   -2.1
                               1.2      0.052 3.7e+002 16
 4   Bus4          1.046   -1.55    3   Bus3          1.05    0.37 5.9e+002 1.8e+002
                               -1.2      -0.012 -3.7e+002 -
 3.6
                               5   Bus5          1.05    -2.6 1.5e+002    27
                               4.1      -2.2      82     -45
                               2   Bus2          0.923   -18 4.6e+002  -11
                               1.5      0.26 2.9e+002  49
 5   Bus5          1.050   -2.65    1   Bus1          1      2.7 8.2e+002 1.5e+002
                               -0.76      -0.4 -4.6e+002 -
 2.4e+002
                               4   Bus4          1.05    -1.5 1.3e+002 1.8e+002
                               -5.4      -0.08     -82     -1.2
                               2   Bus2          0.923   -18 9.4e+002  -27
                               0.68      0.3 5.4e+002 2.4e+002
-----
```

```

kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000072 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000073 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000075 dqmax 0.000000
-----
```

Time = 0.34000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	3	3.55	50	466	299	389	1.01
3	Bus3	1.05	0.489	0.961	50	443	56.1	520	1.05

Maximum rotor angle difference : 2.59312 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	To Name	Voltage zl-real	Angle zl-im	Current P	Angle Q
1 Bus1	5 Bus5	1.05	-2.4	2.1e+004	-30
		0.61	0.39	4.7e+002	3e+002
2 Bus2	4 Bus4	1.05	-1.4	5.5e+002	1.4e+002
		-1	-0.46	-2.8e+002	-
1.2e+002					
	5 Bus5	1.05	-2.4	9.9e+002	1.5e+002
		-0.6	-0.18	-5.2e+002	-
1.6e+002					
3 Bus3	4 Bus4	1.05	-1.4	1.3e+004	-2.1
		1.2	0.054	3.6e+002	16
4 Bus4	3 Bus3	1.05	0.49	5.8e+002	1.8e+002
		-1.2	-0.014	-3.6e+002	-
4.2					
	5 Bus5	1.05	-2.4	1.4e+002	29
		4.2	-2.5	77	-45
	2 Bus2	0.923	-18	4.6e+002	-11
		1.5	0.26	2.8e+002	49
5 Bus5	1 Bus1	1	3	8.3e+002	1.5e+002
		-0.76	-0.39	-4.6e+002	-
2.4e+002					
	4 Bus4	1.05	-1.4	1.2e+002	1.8e+002
		-5.7	-0.15	-77	-2.1
	2 Bus2	0.923	-18	9.4e+002	-26
		0.68	0.3	5.4e+002	2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000076 dqmax 0.000000

```

kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000078 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000079 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000080 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000080 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000081 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000082 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000083 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000084 dqmax 0.000000
-----
```

Time = 0.36000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	3.27	3.83	50	471	299	389	1.01
3	Bus3	1.05	0.62	1.09	50	438	56.3	520	1.05

Maximum rotor angle difference : 2.74226 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	3.27	5 Bus5	1.05 0.61	-2.2 0.38	2.1e+004 4.7e+002	-29 3e+002
2 Bus2	0.923	-17.57	4 Bus4	1.05 -1	-1.2 -0.46	5.5e+002 -2.8e+002	1.4e+002 -
1.2e+002			5 Bus5	1.05 -0.6	-2.2 -0.18	9.9e+002 -5.2e+002	1.5e+002 -
1.6e+002							
3 Bus3	1.050	0.62	4 Bus4	1.05 1.2	-1.2 0.056	1.3e+004 3.6e+002	-2 16
4 Bus4	1.046	-1.24	3 Bus3	1.05 -1.2	0.62 -0.016	5.7e+002 -3.6e+002	1.8e+002 -
4.6			5 Bus5	1.05 4.4	-2.2 -2.7	1.4e+002 73	30 -44
			2 Bus2	0.923 1.5	-18 0.26	4.6e+002 2.8e+002	-11 49
5 Bus5	1.050	-2.22	1 Bus1	1 -0.75	3.3 -0.38	8.3e+002 -4.7e+002	1.5e+002 -
2.4e+002			4 Bus4	1.05 -6	-1.2 -0.23	1.2e+002 -73	1.8e+002 -2.8
			2 Bus2	0.923 0.68	-18 0.3	9.4e+002 5.4e+002	-26 2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000085 dqmax 0.000000

kp 0 kq 0 Iterations 3 dpmax 0.000086 dqmax 0.000000

```

kp 0 kq 0 Iterations 3 dpmax 0.000087 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000087 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000089 dqmax 0.000002
kp 0 kq 0 Iterations 3 dpmax 0.000089 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000090 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000092 dqmax 0.000001
kp 0 kq 0 Iterations 3 dpmax 0.000092 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000093 dqmax 0.000000

```

---

Time = 0.38000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	3.53	4.09	50	474	299	389	1.01
3	Bus3	1.05	0.764	1.23	50	434	56.4	520	1.05

---

Maximum rotor angle difference : 2.86201 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	3.53	5	Bus5	1.05	-2	2.2e+004	-29
						0.6	0.38	4.7e+002	3e+002
2	Bus2	0.922	-17.38	4	Bus4	1.05	-1.1	5.5e+002	1.4e+002
						-1	-0.46	-2.8e+002	-
1.2e+002				5	Bus5	1.05	-2	9.9e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	0.76	4	Bus4	1.05	-1.1	1.3e+004	-1.9
						1.2	0.057	3.5e+002	16
4	Bus4	1.046	-1.08	3	Bus3	1.05	0.76	5.7e+002	1.8e+002
						-1.2	-0.017	-3.5e+002	-
5				5	Bus5	1.05	-2	1.3e+002	31
						4.5	-2.8	70	-44
				2	Bus2	0.922	-17	4.6e+002	-11
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	-2.01	1	Bus1	1	3.5	8.4e+002	1.5e+002
						-0.75	-0.38	-4.7e+002	-
2.4e+002				4	Bus4	1.05	-1.1	1.1e+002	1.8e+002
						-6.3	-0.3	-70	-3.3
				2	Bus2	0.922	-17	9.4e+002	-26
						0.68	0.3	5.4e+002	2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000094 dqmax 0.000001

kp 0 kq 0 Iterations 3 dpmax 0.000095 dqmax 0.000000

kp 0 kq 0 Iterations 3 dpmax 0.000096 dqmax 0.000000

```

kp 0 kq 0 Iterations 3 dpmax 0.000097 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000098 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000099 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000100 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000

```

---

Time = 0.40000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	3.77	4.34	50	477	299	389	1.01
3	Bus3	1.05	0.923	1.39	50	431	56.5	520	1.05

---

Maximum rotor angle difference : 2.95098 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
		Zl-real	Zl-im			P	Q		
1	Bus1	1.000	3.77	5	Bus5	1.05	-1.8	2.2e+004	-28
						0.6	0.38	4.8e+002	3e+002
2	Bus2	0.922	-17.18	4	Bus4	1.05	-0.9	5.5e+002	1.4e+002
						-1	-0.46	-2.8e+002	-
1.2e+002				5	Bus5	1.05	-1.8	9.9e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	0.92	4	Bus4	1.05	-0.9	1.3e+004	-1.8
						1.3	0.059	3.5e+002	16
4	Bus4	1.046	-0.90	3	Bus3	1.05	0.92	5.6e+002	1.8e+002
						-1.2	-0.019	-3.5e+002	-
5.3				5	Bus5	1.05	-1.8	1.3e+002	32
						4.6	-3	67	-43
				2	Bus2	0.922	-17	4.6e+002	-11
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	-1.80	1	Bus1	1	3.8	8.4e+002	1.5e+002
						-0.75	-0.37	-4.7e+002	-
2.4e+002				4	Bus4	1.05	-0.9	1.1e+002	1.8e+002
						-6.6	-0.36	-67	-3.7
				2	Bus2	0.922	-17	9.4e+002	-26
						0.68	0.3	5.4e+002	2.4e+002

```

kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000

```

---

```

kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000

```

-----  
Time = 0.42000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	4	4.57	50	479	300	389	1.01
3	Bus3	1.05	1.1	1.56	50	429	56.6	520	1.05

Maximum rotor angle difference : 3.00809 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

-----  
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To		Voltage	Angle	Current	Angle	Zl-real	Zl-im	P	Q
1	Bus1	1.000	5		Bus5	1.05	-1.6	2.2e+004	0.6		3e+002	
2	Bus2	0.922	-16.98		Bus4	1.05	-0.72	5.5e+002	-1		1.4e+002	
1.2e+002			5		Bus5	1.05	-1.6	9.9e+002	-0.6		1.5e+002	
1.6e+002			-0.18						-0.18		-5.2e+002	
3	Bus3	1.050	1.10		Bus4	1.05	-0.72	1.3e+004	1.1		-1.6	
4	Bus4	1.046	-0.72		Bus3	1.05	0.06	3.5e+002	1.3		17	
5.5			-0.02						-0.02		-3.5e+002	
5	Bus5	1.050	-1.59		1	Bus1	1	4	-0.75		8.4e+002	
2.4e+002			1.3e+002						-0.37		1.5e+002	
			33						-4.7e+002		-43	
			-3.1						-17		65	
			65						0.26		-10	
			-43						2.8e+002		49	
			-10						4		1.7e+002	
			49						8.4e+002		1.5e+002	
			-0.41						-0.37		-4.7e+002	
			-65						-17		-4	
			-4						0.3		-26	
			-26						5.4e+002		2.4e+002	

```

kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000

```

```

kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
-----
Time = 0.44000 Seconds
Intermediate results for Machines
GNo Name Voltage Angle Delta Freq Pgen Qgen Pmech Efd/Slip
pu Degree Degree Hzs. MW MVAR MW pu/P.U.
-----
1 Bus1 1 4.21 4.78 50 480 300 389 1.01
3 Bus3 1.05 1.28 1.75 50 429 56.6 520 1.05
-----
Maximum rotor angle difference : 3.03267 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name Voltage Angle To Name Voltage Angle Current Angle
Zl-real Zl-im P Q
-----
1 Bus1 1.000 4.21 5 Bus5 1.05 -1.4 2.2e+004 -28
0.6 0.37 4.8e+002 3e+002
2 Bus2 0.922 -16.78 4 Bus4 1.05 -0.53 5.5e+002 1.4e+002
-1 -0.46 -2.7e+002 -
1.2e+002
5 Bus5 1.05 -1.4 9.9e+002 1.5e+002
-0.6 -0.18 -5.2e+002 -
1.6e+002
3 Bus3 1.050 1.28 4 Bus4 1.05 -0.53 1.3e+004 -1.4
1.3 0.06 3.5e+002 17
4 Bus4 1.046 -0.53 3 Bus3 1.05 1.3 5.6e+002 1.8e+002
-1.3 -0.02 -3.5e+002 -
5.6
5 Bus5 1.05 -1.4 1.2e+002 33
4.7 -3.1 65 -43
2 Bus2 0.922 -17 4.6e+002 -10
1.5 0.26 2.8e+002 49
5 Bus5 1.05 4.2 8.5e+002 1.5e+002
-0.74 -0.37 -4.8e+002 -
2.4e+002
4 Bus4 1.05 -0.53 1e+002 1.7e+002
-6.8 -0.44 -65 -4.1
2 Bus2 0.922 -17 9.4e+002 -25
0.68 0.3 5.4e+002 2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000

```

```

kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
-----
```

Time = 0.46000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	4.41	4.98	50	480	300	389	1.01
3	Bus3	1.05	1.49	1.96	50	429	56.6	520	1.05

Maximum rotor angle difference : 3.02440 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	4.41	5 Bus5	1.05	-1.2	2.2e+004	-28
				0.6	0.37	4.8e+002	3e+002
2 Bus2	0.922	-16.58	4 Bus4	1.05	-0.32	5.5e+002	1.4e+002
				-1	-0.46	-2.7e+002	-
1.2e+002			5 Bus5	1.05	-1.2	9.9e+002	1.5e+002
				-0.6	-0.18	-5.2e+002	-
1.6e+002							
3 Bus3	1.050	1.49	4 Bus4	1.05	-0.32	1.3e+004	-1.2
				1.3	0.06	3.5e+002	17
4 Bus4	1.046	-0.32	3 Bus3	1.05	1.5	5.6e+002	1.8e+002
				-1.3	-0.02	-3.5e+002	-
5.5			5 Bus5	1.05	-1.2	1.2e+002	33
				4.7	-3.1	65	-43
			2 Bus2	0.922	-17	4.6e+002	-10
				1.5	0.26	2.8e+002	49
5 Bus5	1.050	-1.19	1 Bus1	1	4.4	8.5e+002	1.5e+002
				-0.74	-0.37	-4.8e+002	-
2.4e+002			4 Bus4	1.05	-0.32	1e+002	1.8e+002
				-6.8	-0.43	-65	-4.1
			2 Bus2	0.922	-17	9.4e+002	-25
				0.68	0.3	5.4e+002	2.4e+002

```

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

```

```

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
-----
```

Time = 0.48000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	4.6	5.16	50	479	299	389	1.01
3	Bus3	1.05	1.71	2.18	50	430	56.5	520	1.05

Maximum rotor angle difference : 2.98335 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	To Name	Voltage Zl-real	Angle Zl-im	Current P	Angle Q
1 Bus1	5 Bus5	1.05 0.6	-0.99 0.38	2.2e+004 4.8e+002	-27 3e+002
2 Bus2	4 Bus4	1.05 -1	-0.11 -0.46	5.5e+002 -2.7e+002	1.4e+002 -
1.2e+002	5 Bus5	1.05 -0.6	-0.99 -0.18	9.9e+002 -5.2e+002	1.5e+002 -
1.6e+002	5 Bus5	1.05 -0.6	-0.99 -0.18	1.3e+004 -5.2e+002	-1 -
3 Bus3	4 Bus4	1.05 1.3	-0.11 0.059	1.3e+004 3.5e+002	-1 17
4 Bus4	3 Bus3	1.05 -1.3	1.7 -0.019	5.6e+002 -3.5e+002	1.8e+002 -
5.4	5 Bus5	1.05 4.6	-0.99 -3.1	1.3e+002 66	33 -43
	2 Bus2	0.922 1.5	-16 0.26	4.6e+002 2.8e+002	-9.9 49
2.4e+002	1 Bus1	1 -0.75	4.6 -0.37	8.4e+002 -4.7e+002	1.5e+002 -
	4 Bus4	1.05 -6.7	-0.11 -0.4	1e+002 -66	1.8e+002 -4
	2 Bus2	0.922 0.68	-16 0.3	9.4e+002 5.4e+002	-25 2.4e+002

```

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000
-----
```



kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

Time = 0.52000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	4.92	5.47	50	473	299	389	1.01
3	Bus3	1.05	2.19	2.67	50	435	56.4	520	1.05

Maximum rotor angle difference : 2.80507 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

Voltage (pu), Current (AHLB), Impedance (Ω) and power (MW MVA) for lines

From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	4.92	5	Bus5	1.05	-0.6	2.2e+004	-27
						0.6	0.38	4.7e+002	3e+002
2	Bus2	0.922	-15.97	4	Bus4	1.05	0.34	5.5e+002	1.4e+002
						-1	-0.46	-2.8e+002	
1.2e+002				5	Bus5	1.05	-0.6	9.9e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	
1.6e+002									
3	Bus3	1.050	2.19	4	Bus4	1.05	0.34	1.3e+004	-0.45
						1.2	0.057	3.6e+002	16
4	Bus4	1.046	0.34	3	Bus3	1.05	2.2	5.7e+002	1.8e+002
						-1.2	-0.017	-3.5e+002	
4.9				5	Bus5	1.05	-0.6	1.3e+002	32
						4.5	-2.8	71	-44
				2	Bus2	0.922	-16	4.6e+002	-9.4
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	-0.60	1	Bus1	1	4.9	8.4e+002	1.5e+002
						-0.75	-0.38	-4.7e+002	
2.4e+002				4	Bus4	1.05	0.34	1.1e+002	1.8e+002
						-6.2	-0.28	-71	-3.2
				2	Bus2	0.922	-16	9.4e+002	-25
						0.68	0.35	5.4e+002	2.4e+002

kp 0 kg 0 Iterations 4 dpmax 0.000008 dgmax 0.000000

kp 0 kg 0 Iterations 4 dpmax 0.000008 dgmax 0.000000

kp 0 kg 0 Iterations 4 dpmax 0.000008 dgmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000008 dgmax 0.000000

kp 0 kq 0 Iterations 4 upmax 0.000008 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000008 dcmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000008 dgmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4 dpmax 0.000008 dqmax 0.000000  
 $k_p = 0$   $k_q = 0$  Iterations 4 dpmax 0.000008 dqmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4 dpmax 0.000008 dqmax 0.000000  
 $k_p = 0$   $k_q = 0$  Iterations 4 dpmax 0.000008 dqmax 0.000000

k<sub>p</sub> 0 k<sub>q</sub> 0 Iterations 4 dpmax 0.000008 dqmax 0.000000  
1 2 1 2 Iterations 4 1 2 0.000000 1 2 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2

kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000

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Time = 0.54000 Seconds

### Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	5.06	5.61	50	469	299	389	1.01
3	Bus3	1.05	2.45	2.94	50	440	56.2	520	1.05

Maximum rotor angle difference : 2.66984 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage Angle	To Name	Voltage Angle	Current Angle
	Zl-real	Zl-im	P	Q

1	Bus1	1.000	5.06	5	Bus5	1.05	-0.41	2.1e+004	-27
2	Bus2	0.923	-15.76	4	Bus4	1.05	0.58	4.7e+002	3e+002
						-1	-0.46	-2.8e+002	-
1.2e+002				5	Bus5	1.05	-0.41	9.9e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	2.45	4	Bus4	1.05	0.58	1.3e+004	-0.13
						1.2	0.055	3.6e+002	16
4	Bus4	1.046	0.58	3	Bus3	1.05	2.5	5.7e+002	1.8e+002
						-1.2	-0.015	-3.6e+002	-
4.5				5	Bus5	1.05	-0.41	1.4e+002	31
						4.3	-2.6	74	-44
				2	Bus2	0.923	-16	4.6e+002	-9.2
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	-0.41	1	Bus1	1	5.1	8.3e+002	1.5e+002
						-0.75	-0.38	-4.6e+002	-
2.4e+002				4	Bus4	1.05	0.58	1.2e+002	1.8e+002
						-5.9	-0.2	-74	-2.6
				2	Bus2	0.923	-16	9.4e+002	-24
						0.68	0.3	5.4e+002	2.4e+002

Time = 0.56000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	5.19	5.73	50	464	299	389	1.01
3	Bus3	1.05	2.73	3.22	50	445	56.1	520	1.05

Maximum rotor angle difference : 2.50581 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im			P	Q		
1 Bus1	1.000	5.19	5	Bus5	1.05	-0.22	2.1e+004	-28
					0.61	0.39	4.6e+002	3e+002
2 Bus2	0.923	-15.55	4	Bus4	1.05	0.83	5.5e+002	1.4e+002
					-1	-0.46	-2.8e+002	-
1.2e+002			5	Bus5	1.05	-0.22	9.9e+002	1.5e+002
					-0.6	-0.18	-5.2e+002	-
1.6e+002								
3 Bus3	1.050	2.73	4	Bus4	1.05	0.83	1.3e+004	0.2
					1.2	0.053	3.6e+002	16
4 Bus4	1.046	0.83	3	Bus3	1.05	2.7	5.8e+002	-
1.8e+002					-1.2	-0.013	-3.6e+002	-
4			5	Bus5	1.05	-0.22	1.5e+002	31
					4.2	-2.4	79	-45
			2	Bus2	0.923	-16	4.6e+002	-8.9
					1.5	0.26	2.9e+002	49
5 Bus5	1.050	-0.22	1	Bus1	1	5.2	8.2e+002	1.5e+002
					-0.76	-0.39	-4.6e+002	-
2.4e+002			4	Bus4	1.05	0.83	1.3e+002	1.8e+002
					-5.6	-0.13	-79	-1.8
			2	Bus2	0.923	-16	9.4e+002	-24
					0.68	0.3	5.4e+002	2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000

Time = 0.58000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	5.3	5.83	50	458	298	389	1.01
3	Bus3	1.05	3.02	3.52	50	451	55.9	520	1.05

Maximum rotor angle difference : 2.31486 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im			P	Q		
1 Bus1	1.000	5.30	5	Bus5	1.05	-0.03	2.1e+004	-28
					0.61	0.4	4.6e+002	3e+002
2 Bus2	0.923	-15.34	4	Bus4	1.05	1.1	5.5e+002	1.4e+002
					-1	-0.45	-2.8e+002	-
1.2e+002								
			5	Bus5	1.05	-0.03	9.9e+002	1.5e+002
					-0.6	-0.18	-5.2e+002	-
1.6e+002								
3 Bus3	1.050	3.02	4	Bus4	1.05	1.1	1.4e+004	0.56
					1.2	0.051	3.7e+002	16
4 Bus4	1.046	1.09	3	Bus3	1.05		3 5.9e+002	-
1.8e+002								
					-1.2	-0.011	-3.7e+002	-
3.5								
			5	Bus5	1.05	-0.03	1.5e+002	30
					4	-2.2	84	-46
			2	Bus2	0.923	-15	4.6e+002	-8.7
					1.5	0.26	2.9e+002	49
5 Bus5	1.050	-0.03	1	Bus1	1	5.3	8.2e+002	1.5e+002
					-0.76	-0.4	-4.5e+002	-
2.4e+002								
			4	Bus4	1.05	1.1	1.3e+002	1.8e+002
					-5.3	-0.06	-84	-0.95
			2	Bus2	0.923	-15	9.4e+002	-24
					0.68	0.31	5.4e+002	2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000

Time = 0.60000 Seconds

## Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	5.4	5.93	50	451	298	389	1.01
3	Bus3	1.05	3.32	3.83	50	458	55.8	520	1.05

Maximum rotor angle difference : 2.09916 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	Zl-real	Zl-im	P	Q
1	Bus1	1.000	5.40	5	Buss5	1.05	0.16	2.1e+004	-28			
						0.62	0.41	4.5e+002	3e+002			
2	Bus2	0.923	-15.12	4	Bus4	1.05	1.4	5.5e+002	1.4e+002			
						-1	-0.45	-2.8e+002	-			
1.2e+002												
						5	Buss5	1.05	0.16	9.9e+002	1.5e+002	
								-0.6	-0.18	-5.2e+002	-	
1.6e+002												
3	Bus3	1.050	3.32	4	Bus4	1.05	1.4	1.4e+004	0.92			
						1.2	0.049	3.8e+002	16			
4	Bus4	1.046	1.36	3	Bus3	1.05	3.3	6e+002	-			
1.8e+002												
							-1.2	-0.0088	-3.8e+002	-		
2.9												
						5	Buss5	1.05	0.16	1.6e+002	29	
								3.8	-2	90	-46	
						2	Bus2	0.923	-15	4.7e+002	-8.4	
								1.5	0.25	2.9e+002	49	
5	Bus5	1.050	0.16	1	Bus1	1	5.4	8.1e+002	1.5e+002			
							-0.77	-0.41	-4.5e+002	-		
2.4e+002												
						4	Bus4	1.05	1.4	1.4e+002	-	
1.8e+002												
								-4.9	0.0016	-90	0.03	
						2	Bus2	0.923	-15	9.4e+002	-24	
								0.69	0.31	5.4e+002	2.4e+002	

kp 0 kg 0 Iterations 4 dpmax 0.000010 dmmax 0.000000

kp 0 kg 0 Iterations 4 dpmax 0.000010 dcmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000010 dcmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dqm_{max} = 0.000000$

$k_p = 0$   $k_q = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dqm_{max} = 0.000000$

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
lm 0 lm 0 Iterations 4 dmmax 0.000010 dmav 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dqm_{max} = 0.000000$   
 $lpm = 0$   $lqm = 0$  Iterations 4  $dmu_{max} = 0.000010$   $dmu_{min} = 0.000000$

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
km 0 km 0 Iterations 4 dmmax 0.000010 dmmin 0.000000

kp 0 kq 0 iterations 4 dpmax 0.000010 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
1 2 1 2 5 1 4 1 2 0.000010 1 2 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000

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Time = 0.62000 Seconds

## Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	5.5	6.01	50	443	297	389	1.01
3	Bus3	1.05	3.63	4.15	50	465	55.7	520	1.05

Maximum rotor angle difference : 1.86120 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im	P	Q				

1	Bus1	1.000	5.50	5	Bus5	1.05	0.34	2.1e+004	-28
2	Bus2	0.923	-14.91	4	Bus4	1.05	1.6	5.5e+002	1.4e+002
						-1	-0.45	-2.8e+002	-
1.2e+002				5	Bus5	1.05	0.34	9.9e+002	1.5e+002
1.6e+002						-0.6	-0.18	-5.2e+002	-
3	Bus3	1.050	3.63	4	Bus4	1.05	1.6	1.4e+004	1.3
4	Bus4	1.046	1.63	3	Bus3	1.1	0.046	3.9e+002	16
1.8e+002						1.05	3.6	6.1e+002	-
2.2						-1.1	-0.0065	-3.8e+002	-
				5	Bus5	1.05	0.34	1.7e+002	28
						3.7	-1.8	97	-47
				2	Bus2	0.923	-15	4.7e+002	-8.1
						1.5	0.25	2.9e+002	49
5	Bus5	1.050	0.34	1	Bus1	1	5.5	8e+002	1.5e+002
2.4e+002						-0.77	-0.42	-4.4e+002	-
1.8e+002				4	Bus4	1.05	1.6	1.5e+002	-
						-4.6	0.053	-96	1.1
				2	Bus2	0.923	-15	9.3e+002	-24
						0.69	0.31	5.4e+002	2.4e+002

kp 0 kg 0 Iterations 4 dpmax 0.000010 dgmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dq_{max} = 0.000000$

kp 0 kq 0 Iterations 4 dpmmax 0.000010 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000010 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmmax 0.000010 dpmax 0.000000  
kp 0 kg 0 Iterations 4 dmmax 0.000010 dmmax 0.000000

kp 0 kq 0 Iterations 4 dpmmax 0.000010 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000010 dcmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
kp 0 kg 0 Iterations 4 dpmax 0.000010 dgmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dqm_{max} = 0.000000$   
 $k_m = 0$   $k_{lg} = 0$  Iterations 4  $dpm_{max} = 0.000010$   $dqm_{max} = 0.000000$

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
lm 0 lm 0 Iterations 4 dmav 0.000010 dmav 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
lm 0 lq 0 Iterations 4 dmmax 0.000010 dqmax 0.000000

**kp** 0 **kq** 0 Iterations 4 **dpmx** 0.000010 **dqmx** 0.000000

Power Research and Development Consultants Pvt. Ltd.

kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000

Time = 0.64000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	5.58	6.08	50	435	297	389	1.01
3	Bus3	1.05	3.95	4.48	50	474	55.6	520	1.05

Maximum rotor angle difference : 1.60369 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To      Name      Voltage      Angle      Current      Angle

```

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
-----
Time = 0.66000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.    MW      MVAR    MW      pu/P.U.
-----
 1   Bus1       1       5.65    6.14    50      427     297     389     1.01
 3   Bus3      1.05    4.28    4.82    50      482     55.5    520     1.05
-----
Maximum rotor angle difference : 1.32961 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To   Name      Voltage Angle   Current Angle
                           Zl-real   Zl-im    P      Q
-----
 1   Bus1      1.000    5.65   5   Bus5      1.05     0.71  2e+004   -29
                               0.63     0.44  4.3e+002  3e+002
 2   Bus2      0.923   -14.48  4   Bus4      1.05     2.2   5.6e+002  1.4e+002
                               -1      -0.44  -2.8e+002  -
1.2e+002
                               5   Bus5      1.05     0.71  9.8e+002  1.5e+002
                               -0.6     -0.18  -5.2e+002  -
1.6e+002
 3   Bus3      1.050    4.28   4   Bus4      1.05     2.2   1.5e+004  2.1
                               1.1     0.042  4e+002   15
 4   Bus4      1.046    2.19   3   Bus3      1.05     4.3   6.4e+002  -
1.8e+002
                               5   Bus5      -1.1    -0.0022 -4e+002   -0.79
                               1.05     0.71  1.9e+002   26
                               3.3     -1.4   1.1e+002   -49
 2   Bus2      0.923    1.5     1   Bus1      0.25    5.7   7.8e+002  1.5e+002
                               1      -0.79   -0.45  -4.2e+002  -
2.4e+002
                               4   Bus4      1.05     2.2   1.8e+002  -
1.8e+002
                               5   Bus5      -4      0.13  -1.1e+002
                               0.923   -14  9.3e+002   -23
                               0.69   0.31  5.3e+002  2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

```

```
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
```

Time = 0.68000 Seconds

### Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	5.72	6.2	50	417	296	389	1.01
3	Bus3	1.05	4.61	5.16	50	492	55.4	520	1.05

Maximum rotor angle difference : 1.04209 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle

						Zl-real	Zl-im	P	Q
1	Bus1	1.000	5.72	5	Buss5	1.05	0.89	2e+004	-30
2	Bus2	0.923	-14.27	4	Bus4	1.05	2.5	4.2e+002	3e+002
						-1	-0.44	5.6e+002	1.4e+002
1.2e+002				5	Buss5	1.05	0.89	9.8e+002	1.5e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	4.61	4	Bus4	1.05	2.5	1.5e+004	2.5
						1.1	0.04	4.1e+002	15
4	Bus4	1.046	2.47	3	Bus3	1.05	4.6	6.6e+002	-
1.8e+002							-1.1	-0.00019	-4.1e+002
0.072				5	Buss5	1.05	0.89	2.1e+002	25
						3.1	-1.3	1.2e+002	-50
				2	Bus2	0.923	-14	4.7e+002	-7.3
						1.5	0.25	2.9e+002	50
5	Bus5	1.050	0.89	1	Bus1	1	5.7	7.6e+002	1.5e+002
						-0.79	-0.47	-4.1e+002	-
2.4e+002				4	Bus4	1.05	2.5	1.9e+002	-
1.8e+002							-3.7	0.15	-1.2e+002
4.9									
				2	Bus2	0.923	-14	9.3e+002	-23
						0.69	0.31	5.3e+002	2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

kp 0 kg 0 Iterations 4 dpmax 0.000011 dgmax 0.000000

~~kp 0 kg 0 Iterations 4 dmax 0.000011 dgmax 0.000000~~

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kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
-----
Time = 0.70000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.    MW     MVAR    MW     pu/P.U.
-----
 1   Bus1       1       5.78    6.25     50     408     296     389    1.01
 3   Bus3      1.05    4.95    5.51     50     501     55.4    520    1.05
-----
Maximum rotor angle difference : 0.74446 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To Name      Voltage Angle   Current Angle
                         Zl-real   Zl-im     P         Q
-----
 1   Bus1      1.000    5.78     5   Bus5      1.05     1.1 1.9e+004   -30
                           0.64     0.47 4.1e+002  3e+002
 2   Bus2      0.923   -14.05    4   Bus4      1.05     2.8 5.6e+002 1.4e+002
                           -1      -0.43 -2.8e+002   -
1.2e+002
                           5   Bus5      1.05     1.1 9.8e+002 1.5e+002
                           -0.6     -0.19 -5.2e+002   -
1.6e+002
 3   Bus3      1.050    4.95     4   Bus4      1.05     2.8 1.5e+004   2.9
                           1     0.038 4.2e+002  15
 4   Bus4      1.046    2.76     3   Bus3      1.05     5  6.7e+002   -
1.8e+002
                           0.65
                           5   Bus5      1.05     1.1 2.2e+002   24
                           3     -1.2 1.3e+002  -51
                           2   Bus2      0.923    -14 4.7e+002  -7
                           1.5     0.25 2.9e+002  50
 5   Bus5      1.050    1.07     1   Bus1      1     5.8 7.5e+002 1.5e+002
                           -0.8     -0.48 -4e+002   -
2.5e+002
                           4   Bus4      1.05     2.8  2e+002   -
1.8e+002
                           6.3
                           2   Bus2      0.923    -14 9.3e+002  -23
                           0.69     0.31 5.3e+002  2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

```

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kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

```

---

Time = 0.72000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	5.84	6.3	50	398	296	389	1.01
3	Bus3	1.05	5.3	5.86	50	511	55.5	520	1.05

---

Maximum rotor angle difference : 0.44015 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im			P	Q		
1 Bus1	1.000	5.84	5	Bus5	1.05	1.2	1.9e+004	-31
					0.65	0.48	4e+002	3e+002
2 Bus2	0.923	-13.83	4	Bus4	1.05	3.1	5.6e+002	1.4e+002
					-1	-0.43	-2.8e+002	-
1.2e+002								
			5	Bus5	1.05	1.2	9.8e+002	1.5e+002
					-0.6	-0.19	-5.2e+002	-
1.6e+002								
3 Bus3	1.050	5.30	4	Bus4	1.05	3.1	1.6e+004	3.2
					1	0.037	4.3e+002	16
4 Bus4	1.046	3.06	3	Bus3	1.05	5.3	6.9e+002	-
1.8e+002					-1		0.0032	-4.3e+002
1.4								
			5	Bus5	1.05	1.2	2.3e+002	24
					2.8	-1.1	1.4e+002	-52
			2	Bus2	0.923	-14	4.8e+002	-6.7
					1.4	0.25	2.9e+002	50
5 Bus5	1.050	1.25	1	Bus1	1	5.8	7.4e+002	1.5e+002
					-0.8	-0.5	-3.9e+002	-
2.5e+002								
			4	Bus4	1.05	3.1	2.2e+002	-
1.8e+002						-3.2	0.18	-1.4e+002
7.7								
			2	Bus2	0.923	-14	9.3e+002	-23
					0.69	0.31	5.3e+002	2.4e+002

---

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

Time = 0.74000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	5.9	6.35	50	388	296	389	1.01
3	Bus3	1.05	5.64	6.22	50	521	55.6	520	1.05

Maximum rotor angle difference : 0.13267 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
		Zl-real	Zl-im			P	Q		
1	Bus1	1.000	5.90	5	Bus5	1.05	1.4	1.9e+004	-31
2	Bus2	0.923	-13.61	4	Bus4	0.65	0.5	3.9e+002	3e+002
1.2e+002				5	Bus5	1.05	3.3	5.6e+002	1.4e+002
1.6e+002						-0.6	-0.19	-5.1e+002	-
3	Bus3	1.050	5.64	4	Bus4	1.05	3.3	1.6e+004	3.6
1.8e+002						1	0.035	4.4e+002	16
4	Bus4	1.046	3.35	3	Bus3	1.05	5.6	7e+002	-
2						-1		0.0046	-4.4e+002
				5	Bus5	1.05	1.4	2.5e+002	23
						2.7	-0.97	1.4e+002	-53
				2	Bus2	0.923	-14	4.8e+002	-6.4
						1.4	0.25	2.9e+002	51
5	Bus5	1.050	1.43	1	Bus1	1	5.9	7.3e+002	1.5e+002
2.5e+002						-0.81	-0.52	-3.8e+002	-
1.7e+002				4	Bus4	1.05		3.3	2.3e+002
9.2						-3		0.19	-1.4e+002
				2	Bus2	0.923	-14	9.2e+002	-23





4              Bus4              1.05              3.9 2.6e+002 -

1.7e+002              -2.7              0.2 -1.6e+002

12              2              Bus2              0.923              -13 9.2e+002 -23

0.7              0.32 5.3e+002 2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

---

Time = 0.80000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	6.08	6.5	50	359	295	389	1.01
3	Bus3	1.05	6.67	7.27	50	550	56.2	520	1.05

---

Maximum rotor angle difference : 0.77333 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
				Zl-real	Zl-im	P	Q	
1	Bus1	1.000	6.08	5	Bus5	1.05	2 1.8e+004	-33
						0.66	0.55 3.6e+002	3e+002
2	Bus2	0.923	-12.96	4	Bus4	1.05	4.2 5.7e+002	1.4e+002
						-1	-0.41	-2.9e+002
1.2e+002				5	Bus5	1.05	2 9.7e+002	1.5e+002
						-0.61	-0.19	-5.1e+002
1.6e+002								
3	Bus3	1.050	6.67	4	Bus4	1.05	4.2 1.7e+004	4.7
						0.94	0.032 4.7e+002	16
4	Bus4	1.046	4.22	3	Bus3	1.05	6.7 7.5e+002	-
1.8e+002								
3.9								
				5	Bus5	1.05	2 2.9e+002	22
						2.3	-0.75 1.7e+002	-55
				2	Bus2	0.923	-13 4.8e+002	-5.5

---

Power Research and Development Consultants Pvt. Ltd. Bus1              1.4 0.24 3e+002 51

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5	Bus5	1.051	2.15	1	Bus1	1.4	0.24	3e+002	51
						1	6.2	6.8e+002	1.5e+002
						-0.83	-0.61	-3.5e+002	-
2.5e+002				4	Bus4	1.05		4.5	2.8e+002
1.7e+002						-2.5		0.21	-1.8e+002
15				2	Bus2	0.923		-13	9.2e+002
						0.7	0.32	5.2e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
Time = 0.84000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	6.23	6.62	50	341	295	389	1.01
3	Bus3	1.05	7.33	7.95	50	568	56.7	520	1.05
Maximum rotor angle difference : 1.32887 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
				Zl-real	Zl-im	P	Q		
1	Bus1	1.000	6.23	5	Bus5	1.05	2.3	1.7e+004	-35
						0.67	0.58	3.4e+002	3e+002
2	Bus2	0.923	-12.53	4	Bus4	1.05	4.8	5.7e+002	1.5e+002
						-1	-0.4	-2.9e+002	-
1.2e+002				5	Bus5	1.05	2.3	9.7e+002	1.5e+002
						-0.61	-0.19	-5.1e+002	-
1.6e+002									
3	Bus3	1.050	7.33	4	Bus4	1.05	4.8	1.8e+004	5.4
						0.9	0.031	4.9e+002	17
4	Bus4	1.046	4.79	3	Bus3	1.05	7.3	7.8e+002	-
1.7e+002							-0.9	0.009	-4.9e+002
4.9				5	Bus5	1.05	2.3	3.1e+002	22



					-0.88	0.0094	-4.9e+002		
5.3		5	Bus5	1.05	2.5 3.2e+002	22			
				2.1	-0.62 1.9e+002	-57			
		2	Bus2	0.923	-12 4.9e+002	-4.7			
				1.4	0.24 3e+002	52			
5	Bus5	1.051	2.51	1	Bus1	1	6.3 6.6e+002 1.4e+002		
						-0.84	-0.65 -3.3e+002 -		
2.6e+002				4	Bus4	1.05	5.1 3.1e+002 -		
1.7e+002						-2.3	0.21 -1.9e+002		
17		2	Bus2	0.923	-12 9.1e+002	-22			
				0.7	0.32 5.2e+002 2.4e+002				
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
Time = 0.88000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	6.4	6.78	50	325	295	389	1.01
3	Bus3	1.05	7.96	8.6	50	584	57.4	520	1.05
---	---	---	---	---	---	---	---	---	---
Maximum rotor angle difference : 1.81537 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
				Zl-real	Zl-im	P	Q		
---	---	---	---	---	---	---	---	---	
1	Bus1	1.000	6.40	5	Bus5	1.05	2.7 1.7e+004	-36	
						0.67	0.61 3.3e+002	3e+002	
2	Bus2	0.923	-12.11	4	Bus4	1.05	5.3 5.7e+002 1.5e+002	-	
						-1	-0.4	-2.9e+002	-
1.2e+002				5	Bus5	1.05	2.7 9.7e+002 1.5e+002	-	
						-0.61	-0.2	-5.1e+002	-
1.6e+002				4	Bus4	1.05	5.3 1.8e+004	6	
3	Bus3	1.050	7.96	4	Bus4	0.87	0.03 5e+002	17	

4	Bus4	1.046	5.34	3	Bus3	1.05	8	8e+002	-
1.7e+002									
						-0.87	0.0098	-5e+002	5.6
				5	Bus5	1.05	2.7	3.3e+002	21
						2	-0.58	2e+002	-58
				2	Bus2	0.923	-12	4.9e+002	-4.4
						1.4	0.24	3e+002	52
5	Bus5	1.051	2.69	1	Bus1	1	6.4	6.6e+002	1.4e+002
2.6e+002						-0.84	-0.67	-3.2e+002	-
1.7e+002				4	Bus4	1.05	5.3	3.2e+002	-
						-2.2	0.21	-2e+002	19
				2	Bus2	0.923	-12	9.1e+002	-22
						0.7	0.32	5.2e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
-----									
Time = 0.90000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	6.5	6.88	50	318	295	389	1.01
3	Bus3	1.05	8.26	8.9	50	590	57.7	520	1.05
-----									
Maximum rotor angle difference : 2.02552 b/w buses : 1 and 3									
Island	1	Common system frequency 50.028							
-----									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
---	---	---	---	---	---	---	---	---	---
1	Bus1	1.000	6.50	5	Bus5	1.05	2.9	1.7e+004	-36
						0.68	0.63	3.2e+002	3e+002
2	Bus2	0.923	-11.90	4	Bus4	1.05	5.6	5.7e+002	1.5e+002
						-1	-0.4	-2.9e+002	-
1.2e+002				5	Bus5	1.05	2.9	9.6e+002	1.5e+002
						-0.61	-0.2	-5.1e+002	-
-----									







Time = 0.98000 Seconds

Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	7.04	7.39	50	300	296	389	1.01
3	Bus3	1.05	9.33	9.98	50	609	58.6	520	1.05

Maximum rotor angle difference : 2.59202 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle  
                     Zl-real      Zl-im      P      Q

2	Bus2	0.922	-11.06	4	Bus4	0.68	0.67	3e+002	3e+002
						1.05	6.6	5.8e+002	1.5e+002
						-1	-0.39	-3e+002	-
1.1e+002				5	Bus5	1.05	3.6	9.6e+002	1.5e+002
						-0.61	-0.2	-5e+002	-
1.7e+002				4	Bus4	1.05	6.6	1.9e+004	7.3
3	Bus3	1.050	9.33	4	Bus4	0.83	0.029	5.3e+002	19
4	Bus4	1.046	6.57	3	Bus3	1.05	9.3	8.4e+002	-
1.7e+002						-0.83	0.011	-5.3e+002	
6.7				5	Bus5	1.05	3.6	3.7e+002	22
						1.8	-0.49	2.2e+002	-59
				2	Bus2	0.922	-11	5e+002	-3.2
						1.4	0.24	3.1e+002	53
5	Bus5	1.051	3.64	1	Bus1	1	7	6.3e+002	1.4e+002
						-0.84	-0.74	-3e+002	-
2.6e+002				4	Bus4	1.05	6.6	3.5e+002	-
1.7e+002						-2	0.2	-2.2e+002	
22				2	Bus2	0.922	-11	9.1e+002	-21
						0.7	0.32	5.2e+002	2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

---

Time = 1.00000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	7.2	7.56	50	298	296	389	1.01
3	Bus3	1.05	9.56	10.2	50	611	58.8	520	1.05

---

Maximum rotor angle difference : 2.65680 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	to Name	Voltage	Angle	Current	Angle
Zl-real	Zl-im	P	Q	Page 169			

Time = 1.02000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	7.39	7.74	50	297	296	389	1.01
3	Bus3	1.05	9.78	10.4	50	612	58.8	520	1.05

Maximum rotor angle difference : 2.68875 b/w buses : 1 and 3

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
		Zl-real	Zl-im			P	Q			
1	Bus1	1.000	7.39	5	Bus5	1.05		4	1.6e+004	-38
2	Bus2	0.922	-10.66	4	Bus4	0.68	0.67	3e+002	3e+002	-
						1.05		7 5.8e+002	1.5e+002	-
						-1		-0.39	-3e+002	-
1.1e+002				5	Bus5	1.05		4 9.6e+002	1.5e+002	-
						-0.61		-0.2	-5e+002	-
1.7e+002										-
3	Bus3	1.050	9.78	4	Bus4	1.05		7 2e+004	7.8	-
						0.83	0.029	5.3e+002	19	-
4	Bus4	1.046	7.01	3	Bus3	1.05		9.8 8.5e+002	-	-
1.7e+002						-0.82		0.011	-5.3e+002	-
6.9				5	Bus5	1.05		4 3.7e+002	22	-
						1.8	-0.48	2.2e+002	-60	-
				2	Bus2	0.922		-11 5e+002	-2.8	-
						1.4	0.24	3.1e+002	53	-
5	Bus5	1.051	4.03	1	Bus1	1		7.4 6.3e+002	1.4e+002	-
						-0.84		-0.75	-2.9e+002	-
2.6e+002				4	Bus4	1.05		7 3.6e+002	-	-
1.7e+002						-2		0.2	-2.2e+002	-
23				2	Bus2	0.922		-11 9.1e+002	-21	-
						0.7	0.32	5.2e+002	2.4e+002	-
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000										-
Time = 1.04000 Seconds										-
Intermediate results for Machines										
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip	
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.	
1	Bus1	1	7.59	7.95	50	296	296	389	1.01	
3	Bus3	1.05	9.98	10.6	50	612	58.8	520	1.05	

Time = 1.06000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	7.8	8.16	50	297	296	389	1.01
3	Bus3	1.05	10.2	10.8	50	611	58.8	520	1.05

Maximum rotor angle difference : 2.65295 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Time = 1.08000 Seconds

## Intermediate results for Machines

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3 Bus3 1.05 10.3 11 50 609 58.7 520 1.05

---

Maximum rotor angle difference : 2.58555 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
	Zl-real	Zl-im		P	Q				
1 Bus1	1.000	8.03	5 Bus5	1.05	4.6	1.6e+004	-37		
				0.68	0.67	3e+002	3e+002		
2 Bus2	0.922	-10.06	4 Bus4	1.05	7.6	5.8e+002	1.5e+002		
				-1	-0.39	-3e+002	-		
1.1e+002			5 Bus5	1.05	4.6	9.6e+002	1.5e+002		
				-0.61	-0.2	-5e+002	-		
1.7e+002									
3 Bus3	1.050	10.33	4 Bus4	1.05	7.6	1.9e+004	8.3		
				0.83	0.029	5.3e+002	19		
4 Bus4	1.046	7.58	3 Bus3	1.05	10	8.4e+002	-		
1.7e+002					-0.83	0.011	-5.3e+002		
6.7			5 Bus5	1.05	4.6	3.7e+002	23		
				1.8	-0.49	2.2e+002	-59		
			2 Bus2	0.922	-10	5e+002	-2.2		
				1.4	0.24	3.1e+002	53		
5 Bus5	1.051	4.64	1 Bus1	1	8	6.3e+002	1.4e+002		
2.6e+002				-0.84	-0.74	-3e+002	-		
1.7e+002			4 Bus4	1.05	7.6	3.5e+002	-		
23					-2	0.2	-2.2e+002		
			2 Bus2	0.922	-10	9.1e+002	-20		
				0.7	0.32	5.2e+002	2.4e+002		
kp 0 kq 0 Iterations 3 dpmax 0.000100 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000099 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000098 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000097 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000096 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000095 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000094 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000093 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000092 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000091 dqmax 0.000000									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs	MW	MVAR	MW	pu/P_u

```
-----
1     Bus1      1     8.28    8.65    50    303    295    389    1.01
3     Bus3      1.05   10.5    11.1    50    606    58.5    520    1.05
-----
Maximum rotor angle difference : 2.48602 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name   Voltage Angle To Name   Voltage Angle Current Angle
                           Zl-real Zl-im   P       Q
-----
1     Bus1   1.000   8.28   5     Bus5   1.05    4.8 1.6e+004 -36
                           0.68    0.66 3e+002 3e+002
2     Bus2   0.922  -9.87   4     Bus4   1.05    7.7 5.8e+002 1.5e+002
                           -1      -0.39 -3e+002 -
1.1e+002
                           5     Bus5   1.05    4.8 9.6e+002 1.5e+002
                           -0.61   -0.2  -5e+002 -
1.6e+002
3     Bus3   1.050   10.49   4     Bus4   1.05    7.7 1.9e+004 8.5
                           0.84    0.029 5.3e+002 19
4     Bus4   1.046   7.75    3     Bus3   1.05    10 8.4e+002 -
1.7e+002
                           6.6
                           5     Bus5   1.05    4.8 3.6e+002 23
                           1.9     -0.5 2.2e+002 -59
                           2     Bus2   0.922  -9.9 5e+002 -2
                           1.4     0.24 3.1e+002 52
5     Bus5   1.051   4.85    1     Bus1   1     8.3 6.3e+002 1.4e+002
                           -0.84   -0.73 -3e+002 -
2.6e+002
                           4     Bus4   1.05    7.7 3.5e+002 -
1.7e+002
                           22
                           2     Bus2   0.922  -9.9 9.1e+002 -20
                           0.7    0.32 5.2e+002 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000090 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000089 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000088 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000088 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000087 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000086 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000085 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000084 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000083 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000082 dqmax 0.000000
-----
Time = 1.12000 Seconds
```



Time = 1.14000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	8.81	9.19	50	312	295	389	1.01
3	Bus3	1.05	10.8	11.4	50	597	58	520	1.05

---

Maximum rotor angle difference : 2.19543 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	8.81	5 Bus5	1.05	5.3	1.7e+004	-35
	0.68			0.64	3.1e+002	3e+002	
2 Bus2	0.923	-9.48	4 Bus4	1.05	8.1	5.7e+002	1.5e+002
				-1	-0.39	-2.9e+002	-
1.2e+002			5 Bus5	1.05	5.3	9.6e+002	1.5e+002
				-0.61		-0.2	-5.1e+002
1.6e+002							-
3 Bus3	1.050	10.75	4 Bus4	1.05	8.1	1.9e+004	8.8
	0.85			0.03	5.2e+002	18	
4 Bus4	1.046	8.06	3 Bus3	1.05	11	8.2e+002	-
1.7e+002				-0.85		0.01	-5.2e+002
6.3			5 Bus5	1.05	5.3	3.5e+002	24
	1.9			-0.53	2.1e+002	-59	
			2 Bus2	0.923	-9.5	4.9e+002	-1.7
				1.4	0.24	3e+002	52
5 Bus5	1.051	5.27	1 Bus1	1	8.8	6.4e+002	1.5e+002
				-0.84		-0.7	-3.1e+002
2.6e+002			4 Bus4	1.05	8.1	3.4e+002	-
1.7e+002				-2.1		0.2	-2.1e+002
21			2 Bus2	0.923	-9.5	9.1e+002	-19
	0.7			0.32	5.2e+002	2.4e+002	
kp 0 kq 0 Iterations 3 dpmax 0.000072 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000							

---

kp 0 kq 0 Iterations 3 dpmax 0.000065 dqmax 0.000000

Time = 1.16000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	9.09	9.48	50	318	295	389	1.01
3	Bus3	1.05	10.9	11.5	50	591	57.7	520	1.05

Maximum rotor angle difference : 2.00767 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To      Name      Voltage      Angle      Current      Angle

								Zl-real	Zl-im	P	Q
1	Bus1	1.000	9.09	5	Bus5	1.05	5.5	1.7e+004	-34		
2	Bus2	0.923	-9.29	4	Bus4	1.05	8.2	5.7e+002	1.5e+002		
						-1	-0.39	-2.9e+002	-		
1.2e+002				5	Bus5	1.05	5.5	9.6e+002	1.5e+002		
						-0.61	-0.2	-5.1e+002	-		
1.6e+002											
3	Bus3	1.050	10.87	4	Bus4	1.05	8.2	1.9e+004	8.9		
						0.86	0.03	5.1e+002	18		
4	Bus4	1.046	8.21	3	Bus3	1.05	11	8.2e+002	-		
1.7e+002											
6						-0.86	0.01	-5.1e+002	-		
				5	Bus5	1.05	5.5	3.4e+002	24		
						2	-0.55	2.1e+002	-58		
				2	Bus2	0.923	-9.3	4.9e+002	-1.5		
						1.4	0.24	3e+002	52		
5	Bus5	1.051	5.48	1	Bus1	1	9.1	6.5e+002	1.5e+002		
						-0.84	-0.69	-3.1e+002	-		
2.6e+002											
1.7e+002				4	Bus4	1.05	8.2	3.3e+002	-		
20							-2.1	0.21	-2.1e+002	-	
				2	Bus2	0.923	-9.3	9.1e+002	-19		
						0.7	0.32	5.2e+002	2.4e+002		

kp 0 kg 0 Iterations 3 dpmax 0.000064 dgmax 0.000000

kp 0 kg 0 Iterations 3 dpmax 0.000063 dgmax 0.000000

kp 0 kg 0 Iterations 3 drmax 0.000063 dcmax 0.000000

kp 0 kg 0 Iterations 3 dpmax 0.000062 dcmax 0.000000

kp 0 kg 0 Iterations 3 dpmax 0.000002 dcmax 0.000000

KP = KQ = Iterations = dmax = dmin = 0.000001

kp 0 kq 0 Iterations 3 dpmax 0.000000 dcmx 0.000000

XP 8 24 8 100% 100% 3 8 0.000000 8 0.000000

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```
kp 0 kq 0 Iterations 3 dpmx 0.000059 dqmx 0.000000  
kp 0 kq 0 Iterations 3 dpmx 0.000058 dqmx 0.000000  
kp 0 kq 0 Iterations 3 dpmx 0.000057 dqmx 0.000000
```

Time = 1.18000 Seconds

### Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	9.39	9.79	50	325	295	389	1.01
3	Bus3	1.05	11	11.6	50	584	57.4	520	1.05

Maximum rotor angle difference : 1.79436 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To Name      Voltage Angle      Current Angle

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	Zl-real	Zl-im	P	Q	
1	Bus1	1.000	9.39	5	Buss5	1.05	5.7	1.7e+004	-33	0.67	0.61	3.2e+002	3e+002
2	Bus2	0.923	-9.11	4	Bus4	1.05	8.3	5.7e+002	1.5e+002	-1	-0.4	-2.9e+002	-
1.2e+002				5	Buss5	1.05	5.7	9.7e+002	1.5e+002	-0.61	-0.2	-5.1e+002	-
1.6e+002													
3	Bus3	1.050	10.97	4	Bus4	1.05	8.3	1.9e+004	9	0.87	0.03	5e+002	17
1.7e+002				3	Bus3	1.05	11	8e+002	-				
						-0.87	0.0099	-5e+002	5.7				
				5	Buss5	1.05	5.7	3.3e+002	24	2	-0.58	2e+002	-58
				2	Bus2	0.923	-9.1	4.9e+002	-1.4	1.4	0.24	3e+002	52
5	Bus5	1.051	5.69	1	Bus1	1	9.4	6.6e+002	1.5e+002	-0.84	-0.67	-3.2e+002	-
2.6e+002				4	Bus4	1.05	8.3	3.2e+002	-				
1.7e+002													
						-2.2	0.21	-2e+002	19				
				2	Bus2	0.923	-9.1	9.1e+002	-19	0.7	0.32	5.2e+002	2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000

kp 0 kg 0 Iterations 3 dpmax 0.000056 dgmax 0.000000

kp 0 kg 0 Iterations 3 dpmax 0.000055 dgmax 0.000000

kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000

kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000054 dqmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations 3  $dpm_{max} = 0.000054$   $dc_{max} = 0.000000$   
 $k_p = 0$   $k_q = 0$  Iterations 3  $dpm_{max} = 0.000053$   $dc_{max} = 0.000000$

kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000  
kp 0 kg 0 Iterations 3 dpmax 0.000053 dgmax 0.000000

$k_p = 0$   $k_q = 0$  Iterations: 3  $\text{dpmax} = 0.000032$   $\text{dqmax} = 0.000000$

# Power Research and Development Consultants Pvt. Ltd.

```

kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000
-----
```

Time = 1.20000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	9.7	10.1	50	332	295	389	1.01
3	Bus3	1.05	11.1	11.7	50	577	57.1	520	1.05

```

Maximum rotor angle difference : 1.55793 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
```

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	9.70	5 Bus5	1.05	5.9	1.7e+004	-32
				0.67	0.6	3.3e+002	3e+002
2 Bus2	0.923	-8.92	4 Bus4	1.05	8.5	5.7e+002	1.5e+002
				-1	-0.4	-2.9e+002	-
1.2e+002			5 Bus5	1.05	5.9	9.7e+002	1.5e+002
				-0.61	-0.2	-5.1e+002	-
1.6e+002							
3 Bus3	1.050	11.06	4 Bus4	1.05	8.5	1.8e+004	9.1
				0.89	0.03	5e+002	17
4 Bus4	1.046	8.47	3 Bus3	1.05	11	7.9e+002	-
1.7e+002							
				-0.88	0.0095	-5e+002	5.3
			5 Bus5	1.05	5.9	3.2e+002	25
				2.1	-0.61	1.9e+002	-57
			2 Bus2	0.923	-8.9	4.9e+002	-1.3
				1.4	0.24	3e+002	52
5 Bus5	1.051	5.91	1 Bus1	1	9.7	6.6e+002	1.5e+002
				-0.84	-0.65	-3.3e+002	-
2.6e+002			4 Bus4	1.05	8.5	3.1e+002	-
1.7e+002					-2.3	0.21	-1.9e+002
18							
			2 Bus2	0.923	-8.9	9.1e+002	-19
				0.7	0.32	5.2e+002	2.4e+002

```

kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000
-----
```

```

kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000
-----
```

Time = 1.22000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	10	10.4	50	340	295	389	1.01
3	Bus3	1.05	11.1	11.7	50	569	56.7	520	1.05

Maximum rotor angle difference : 1.30111 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	10.02	5 Bus5	1.05	6.1	1.7e+004	-31
				0.67	0.58	3.4e+002	3e+002
2 Bus2	0.923	-8.73	4 Bus4	1.05	8.6	5.7e+002	1.5e+002
				-1	-0.4	-2.9e+002	-
1.2e+002			5 Bus5	1.05	6.1	9.7e+002	1.5e+002
				-0.61	-0.19	-5.1e+002	-
1.6e+002							
3 Bus3	1.050	11.14	4 Bus4	1.05	8.6	1.8e+004	9.2
				0.9	0.031	4.9e+002	17
4 Bus4	1.046	8.60	3 Bus3	1.05	10	7.8e+002	-
1.7e+002					-0.9	0.0091	-4.9e+002
4.9			5 Bus5	1.05	6.1	3.1e+002	25
				2.1	-0.65	1.9e+002	-57
			2 Bus2	0.923	-8.7	4.9e+002	-1.1
				1.4	0.24	3e+002	52
5 Bus5	1.051	6.13	1 Bus1	1	10	6.7e+002	1.5e+002
				-0.83	-0.63	-3.4e+002	-
2.5e+002			4 Bus4	1.05	8.6	3e+002	-
1.7e+002				-2.4	0.21	-1.9e+002	-
16			2 Bus2	0.923	-8.7	9.2e+002	-18
				0.7	0.32	5.2e+002	2.4e+002

```

kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000
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```

```

kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000

```

---

Time = 1.24000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	10.3	10.8	50	349	295	389	1.01
3	Bus3	1.05	11.2	11.8	50	560	56.4	520	1.05

---

Maximum rotor angle difference : 1.02684 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
From Name Voltage Angle To Name Voltage Angle Current Angle

					Zl-real	Zl-im	P	Q
1	Bus1	1.000	10.34	5	Bus5	1.05 0.67	6.3 0.57	1.8e+004 3.5e+002
2	Bus2	0.923	-8.55	4	Bus4	1.05 -1	8.7 -0.41	5.7e+002 1.5e+002 -2.9e+002 -
1.2e+002				5	Bus5	1.05 -0.61	6.3 -0.19	9.7e+002 -5.1e+002
1.6e+002								
3	Bus3	1.050	11.21	4	Bus4	1.05 0.92	8.7 0.031	1.8e+004 4.8e+002
1.7e+002				3	Bus3	1.05	11	9.2 16
4.5						-0.91	0.0085	-4.8e+002
2.5e+002				5	Bus5	1.05 2.2	6.3 -0.7	3e+002 1.8e+002
1.7e+002				2	Bus2	0.923 1.4	-8.5 0.24	4.9e+002 3e+002
15				1	Bus1	1 -0.83	10 -0.61	6.8e+002 -3.5e+002
								26 -56 -1 51
				4	Bus4	1.05	8.7	2.8e+002 -
						-2.5	0.21	-1.8e+002
				2	Bus2	0.923 0.7	-8.5 0.32	9.2e+002 5.2e+002
								-18 2.4e+002

---

kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000

kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000

```

kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000

```

---

Time = 1.26000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	10.7	11.1	50	358	295	389	1.01
3	Bus3	1.05	11.3	11.9	50	551	56.2	520	1.05

---

Maximum rotor angle difference : 0.73828 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	10.67	5 Bus5	1.05	6.6	1.8e+004	-29
				0.67	0.55	3.6e+002	3e+002
2 Bus2	0.923	-8.36	4 Bus4	1.05	8.8	5.7e+002	1.5e+002
				-1	-0.41	-2.9e+002	-
1.2e+002			5 Bus5	1.05	6.6	9.7e+002	1.5e+002
				-0.61	-0.19	-5.1e+002	-
1.6e+002							
3 Bus3	1.050	11.28	4 Bus4	1.05	8.8	1.7e+004	9.3
				0.94	0.032	4.7e+002	16
4 Bus4	1.046	8.83	3 Bus3	1.05	11	7.5e+002	-
1.7e+002					-0.93	0.0078	-4.7e+002
3.9			5 Bus5	1.05	6.6	2.9e+002	27
				2.3	-0.75	1.7e+002	-55
			2 Bus2	0.923	-8.4	4.8e+002	-0.91
				1.4	0.24	3e+002	51
5 Bus5	1.051	6.56	1 Bus1	1	11	6.9e+002	1.5e+002
				-0.83	-0.59	-3.5e+002	-
2.5e+002			4 Bus4	1.05	8.8	2.7e+002	-
1.7e+002					-2.6	0.21	-1.7e+002
14			2 Bus2	0.923	-8.4	9.2e+002	-18
				0.7	0.32	5.3e+002	2.4e+002

---

```

kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000
-----
```

Time = 1.28000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	11	11.5	50	368	295	389	1.01
3	Bus3	1.05	11.3	11.9	50	541	55.9	520	1.05

Maximum rotor angle difference : 0.43876 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						z1-real	z1-im	P	Q
1	Bus1	1.000	11.01	5	Bus5	1.05		6.8	1.8e+004
						0.66		0.53	3.7e+002
2	Bus2	0.923	-8.18	4	Bus4	1.05		8.9	5.7e+002
						-1		-0.42	-2.9e+002
1.2e+002				5	Bus5	1.05		6.8	9.7e+002
						-0.61		-0.19	-5.1e+002
1.6e+002									
3	Bus3	1.050	11.34	4	Bus4	1.05		8.9	1.7e+004
						0.96		0.033	4.6e+002
4	Bus4	1.046	8.94	3	Bus3	1.05		11	7.4e+002
1.7e+002									
3.4								-0.95	0.007
				5	Bus5	1.05		6.8	2.7e+002
						2.4		-0.81	1.6e+002
2.5e+002				2	Bus2	0.923		-8.2	4.8e+002
1.7e+002						1.4		0.25	3e+002
5	Bus5	1.051	6.78	1	Bus1	1		11	7e+002
						-0.82		-0.57	-3.6e+002
				4	Bus4	1.05		8.9	2.6e+002
								-2.7	0.2
1.2									-1.6e+002





4 Bus4 1.05 9.2 2.3e+002 -

1.7e+002 -3 0.19 -1.4e+002

9.3 2 Bus2 0.923 -7.8 9.2e+002 -17

0.69 0.31 5.3e+002 2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000

---

Time = 1.34000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	12	12.5	50	398	296	389	1.01
3	Bus3	1.05	11.5	12	50	511	55.5	520	1.05

---

Maximum rotor angle difference : 0.49066 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	12.04	5 Bus5	1.05	7.4	1.9e+004	-25
2 Bus2	0.923	-7.63	4 Bus4	0.65	0.48	4e+002	3e+002
1.2e+002				1.05	9.3	5.6e+002	1.5e+002
				-1	-0.43	-2.8e+002	-
1.6e+002							
3 Bus3	1.050	11.50	4 Bus4	1.05	9.3	1.6e+004	9.4
				1	0.037	4.3e+002	15
4 Bus4	1.046	9.26	3 Bus3	1.05	12	6.9e+002	-
1.7e+002				-1		0.0033	-4.3e+002
1.4							
				5 Bus5	1.05	7.4	2.3e+002
					2.8	-1.1	1.4e+002
				2 Bus2	0.923	-7.6	4.8e+002
					1.4	-0.25	2.9e+002
							50

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Power Research and Development Consultants Pvt. Ltd. Bus1 1 12 7.4e+002 1 Page 107

-0.8 -0.5 -3.9e+002 -

2.5e+002								
	4	Bus4		1.05		9.3	2.2e+002	-
1.7e+002								
				-3.2		0.19	-1.4e+002	
7.8		Bus2	0.923		-7.6	9.3e+002	-17	
			0.69		0.31	5.3e+002	2.4e+002	

kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000

---

Time = 1.36000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	12.4	12.9	50	408	296	389	1.01
3	Bus3	1.05	11.6	12.1	50	501	55.4	520	1.05

---

Maximum rotor angle difference : 0.79882 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
						z1-real	z1-im		
						P	Q		
1	Bus1	1.000	12.38	5	Bus5	1.05	7.7	1.9e+004	-24
						0.64	0.47	4.1e+002	3e+002
2	Bus2	0.923	-7.45	4	Bus4	1.05	9.4	5.6e+002	1.5e+002
						-1	-0.43	-2.8e+002	-
1.2e+002				5	Bus5	1.05	7.7	9.8e+002	1.6e+002
						-0.6	-0.19	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	11.56	4	Bus4	1.05	9.4	1.5e+004	9.5
						1	0.038	4.2e+002	15
4	Bus4	1.046	9.37	3	Bus3	1.05	12	6.7e+002	-
1.7e+002							-1	0.0017	-4.2e+002
0.69									
				5	Bus5	1.05	7.7	2.2e+002	31
						3	-1.2	1.3e+002	-51

---

Power Research and Development Consultants Pvt. Ltd

5 Bus5 1.050 7.67 1 Bus1 1.5 0.25 2.9e+002 50  
 - 1 12 7.5e+002 1.6e+002  
 -0.8 -0.48 -4e+002 -  
 2.5e+002  
 4 Bus4 1.05 9.4 2e+002 -  
 1.7e+002  
 6.3 2 Bus2 0.923 -7.4 9.3e+002 -17  
 0.69 0.31 5.3e+002 2.4e+002  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000

---

Time = 1.38000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	12.7	13.2	50	417	296	389	1.01
3	Bus3	1.05	11.6	12.1	50	492	55.4	520	1.05

---

Maximum rotor angle difference : 1.10018 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	12.72	5 Bus5	1.05	7.9	2e+004	-23
2 Bus2	0.923	-7.26	4 Bus4	1.05	0.64	0.45	4.2e+002 3e+002
1.2e+002					-1	9.5	5.6e+002 1.5e+002
1.6e+002						-0.44	-2.8e+002 -
3 Bus3	1.050	11.62	4 Bus4	1.05	1.05	7.9	9.8e+002 1.6e+002
1.7e+002						-0.6	-0.18 -5.2e+002 -
4 Bus4	1.046	9.48	3 Bus3	1.05	1.1	1.05	12 6.6e+002 -
0.043						-1.1	-0.00011 -4.1e+002 -

---

						3.1	-1.3	1.2e+002	-50
						0.923	-7.3	4.7e+002	-0.26
						1.5	0.25	2.9e+002	50
5	Bus5	1.050	7.89	1	Bus1	1	13	7.6e+002	1.6e+002
						-0.79	-0.47	-4.1e+002	-
2.4e+002				4	Bus4	1.05	9.5	1.9e+002	-
1.7e+002						-3.7	0.15	-1.2e+002	
4.9				2	Bus2	0.923	-7.3	9.3e+002	-16
						0.69	0.31	5.3e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000									
-----									
Time = 1.40000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	13.1	13.6	50	427	297	389	1.01
3	Bus3	1.05	11.7	12.2	50	482	55.5	520	1.05
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
Maximum rotor angle difference : 1.39127 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
				Zl-real	Zl-im	P	Q		
---	---	---	---	---	---	---	---	---	---
1	Bus1	1.000	13.06	5	Bus5	1.05	8.1	2e+004	-22
						0.63	0.44	4.3e+002	3e+002
2	Bus2	0.923	-7.08	4	Bus4	1.05	9.6	5.6e+002	1.5e+002
						-1	-0.44	-2.8e+002	-
1.2e+002				5	Bus5	1.05	8.1	9.8e+002	1.6e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	11.68	4	Bus4	1.05	9.6	1.5e+004	9.5
						1.1	0.042	4e+002	15
4	Bus4	1.046	9.59	3	Bus3	1.05	12	6.4e+002	-
1.7e+002									
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

```

5      Bus5      1.05      8.11      1      Bus1      1      13      7.8e+002 1.6e+002      33
      3.3      -1.5 1.1e+002      -49
      2      Bus2      0.923      -7.1 4.7e+002      -0.15
      1.5      0.25 2.9e+002      50
5      Bus5      1.050      8.11      1      Bus1      1      13      7.8e+002 1.6e+002      -
      -0.79      -0.45  -4.2e+002      -
2.4e+002
      4      Bus4      1.05      9.6 1.8e+002      -
1.7e+002
      -4      0.13  -1.1e+002
3.6
      2      Bus2      0.923      -7.1 9.3e+002      -16
      0.69      0.31 5.3e+002 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000
-----
Time = 1.42000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle      Delta      Freq      Pgen      Qgen      Pmech      Efd/Slip
      pu        Degree     Degree    Hzs.      MW      MVAR      MW      pu/P.U.
-----
1      Bus1      1      13.4      13.9      50      436      297      389      1.01
3      Bus3      1.05      11.7      12.2      50      473      55.6      520      1.05
-----
Maximum rotor angle difference : 1.66870 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle      To      Name      Voltage Angle      Current      Angle
      pu        Degree     pu        Degree     Zl-real     Zl-im      P      Q
-----
1      Bus1      1.000      13.38      5      Bus5      1.05      8.3 2e+004      -21
      0.63      0.43 4.4e+002 3e+002
2      Bus2      0.923      -6.90      4      Bus4      1.05      9.7 5.5e+002 1.5e+002
      -1      -0.44  -2.8e+002      -
1.2e+002
      5      Bus5      1.05      8.3 9.9e+002 1.6e+002
      -0.6      -0.18  -5.2e+002      -
1.6e+002
3      Bus3      1.050      11.75      4      Bus4      1.05      9.7 1.4e+004      9.5
      1.1      0.044 3.9e+002 16
4      Bus4      1.046      9.70      3      Bus3      1.05      12 6.3e+002      -
1.7e+002

```

1.5  
 1.5  
 5 Bus5 1.05 8.3 1.8e+002 35  
 3.5 -1.6 1e+002 -48  
 2 Bus2 0.923 -6.9 4.7e+002 -0.036  
 1.5 0.25 2.9e+002 50  
 5 Bus5 1.050 8.33 1 13 7.9e+002 1.6e+002  
 -0.78 -0.44 -4.3e+002 -  
 2.4e+002  
 4 Bus4 1.05 9.7 1.6e+002 -  
 1.7e+002  
 2 Bus2 -4.3 0.094 -1e+002 2.3  
 0.923 -6.9 9.3e+002 -16  
 0.69 0.31 5.3e+002 2.4e+002  
 kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000  
 -----  
 Time = 1.44000 Seconds  
 Intermediate results for Machines  

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	13.7	14.2	50	444	297	389	1.01
3	Bus3	1.05	11.8	12.3	50	465	55.7	520	1.05

 Maximum rotor angle difference : 1.92926 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028  
 -----  
 Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  

From Name	To Name	Voltage zl-real	Angle zl-im	Current P	Angle Q
1 Bus1	5 Bus5	1.05	8.5	2.1e+004	-20
		0.62	0.42	4.4e+002	3e+002
2 Bus2	4 Bus4	1.05	9.8	5.5e+002	1.5e+002
		-1	-0.45	-2.8e+002	-
1.2e+002	5 Bus5	1.05	8.5	9.9e+002	1.6e+002
		-0.6	-0.18	-5.2e+002	-
1.6e+002	4 Bus4	1.05	9.8	1.4e+004	9.5
		1.1	0.047	3.8e+002	16

4	Bus4	1.046	9.82	3	Bus3	1.05	12	6.1e+002	-
1.7e+002						-1.1	-0.0066	-3.8e+002	-
2.2				5	Bus5	1.05	8.5	1.7e+002	36
						3.7	-1.8	96	-47
				2	Bus2	0.923	-6.7	4.7e+002	0.082
						1.5	0.25	2.9e+002	49
5	Bus5	1.050	8.54	1	Bus1	1	14	8e+002	1.6e+002
						-0.77	-0.42	-4.4e+002	-
2.4e+002				4	Bus4	1.05	9.8	1.5e+002	-
1.7e+002						-4.6	0.05	-96	1
				2	Bus2	0.923	-6.7	9.4e+002	-16
						0.69	0.31	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000									

---

Time = 1.46000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	14	14.6	50	452	298	389	1.01
3	Bus3	1.05	11.9	12.4	50	457	55.8	520	1.05

---

Maximum rotor angle difference : 2.16992 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
				Zl-real	Zl-im	P	Q	
1 Bus1	1.000	14.02	5 Bus5	1.05		8.8	2.1e+004	-19
				0.62		0.41	4.5e+002	3e+002
2 Bus2	0.923	-6.53	4 Bus4	1.05		9.9	5.5e+002	1.5e+002
				-1		-0.45	-2.8e+002	-
1.2e+002			5 Bus5	1.05		8.8	9.9e+002	1.6e+002
				-0.6		-0.18	-5.2e+002	-
1.6e+002			4 Bus4	1.05		9.9	1.4e+004	9.5
3 Bus3	1.050	11.91						

```

        1.2      0.049 3.8e+002      16
        4     Bus4    1.046    9.95      3     Bus3      1.05      12      6e+002      -
1.7e+002
                                -1.2      -0.009 -3.8e+002      -
2.9
                                5     Bus5      1.05      8.8 1.6e+002      37
                                3.9      -2      89      -46
                                2     Bus2      0.923      -6.5 4.7e+002      0.2
                                1.5      0.25 2.9e+002      49
                                5     Bus5    1.050    8.76      1     Bus1      1      14 8.1e+002 1.6e+002      -
2.4e+002
                                4     Bus4      1.05      9.9 1.4e+002      -
1.7e+002
                                -4.9      -0.0044      -89      -0.079
                                2     Bus2      0.923      -6.5 9.4e+002      -15
                                0.69      0.31 5.4e+002 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000054 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000056 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000060 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000
-----
Time = 1.48000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta   Freq   Pgen   Qgen   Pmech   Efd/Slip
      pu       Degree   Degree   Hzs.   MW     MVAR   MW     pu/P.U.
-----
1   Bus1      1       14.3    14.9     50     459     298     389     1.01
3   Bus3      1.05    12       12.5     50     450      56     520     1.05
-----
Maximum rotor angle difference : 2.38789 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To   Name      Voltage Angle   Current Angle
                           Zl-real   Zl-im   P       Q
-----
1   Bus1      1.000    14.32    5   Bus5      1.05      9 2.1e+004      -19
                                0.61      0.4 4.6e+002 3e+002
2   Bus2      0.923    -6.34    4   Bus4      1.05     10 5.5e+002 1.5e+002
                                -1      -0.46 -2.8e+002      -
1.2e+002
                                5   Bus5      1.05      9 9.9e+002 1.6e+002
                                0.6      0.18 5.2e+002      -
-----
```

3 Bus3 1.050 12.01 4 Bus4 1.05 10 1.4e+004 9.5  
 4 Bus4 1.046 10.08 3 Bus3 1.05 12 5.9e+002 -  
 1.7e+002  
 3.5  
 5 Bus5 1.05 9 1.5e+002 39  
 4 -2.2 83 -46  
 2 Bus2 0.923 -6.3 4.6e+002 0.33  
 1.5 0.26 2.9e+002 49  
 5 Bus5 1.05 14 8.2e+002 1.6e+002  
 -0.76 -0.4 -4.5e+002 -  
 2.4e+002  
 4 Bus4 1.05 10 1.3e+002 -  
 1.7e+002  
 -5.3 -0.07 -83 -1.1  
 2 Bus2 0.923 -6.3 9.4e+002 -15  
 0.68 0.3 5.4e+002 2.4e+002

---

kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000062 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000065 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000

---

Time = 1.50000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	14.6	15.2	50	465	299	389	1.01
3	Bus3	1.05	12.1	12.6	50	444	56.1	520	1.05

---

Maximum rotor angle difference : 2.58063 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	14.61	5 Bus5	1.05	9.2	2.1e+004	-18
2 Bus2	0.923	-6.15	4 Bus4	0.61	0.39	4.7e+002	3e+002
1.2e+002				1.05	10	5.5e+002	1.5e+002
				-1	-0.46	-2.8e+002	-
			5 Bus5	1.05	9.2	9.9e+002	1.6e+002

1.6e+002  
 3 Bus3 1.050 12.11 4 Bus4 1.05 10 1.3e+004 9.6  
 1.2 0.054 3.6e+002 16  
 4 Bus4 1.046 10.22 3 Bus3 1.05 12 5.8e+002 -  
 1.7e+002  
 4.1  
 5 Bus5 1.05 9.2 1.4e+002 40  
 4.2 -2.4 78 -45  
 2 Bus2 0.923 -6.1 4.6e+002 0.47  
 1.5 0.26 2.9e+002 49  
 5 Bus5 1.050 9.19 1 Bus1 1 15 8.3e+002 1.6e+002  
 -0.76 -0.39 -4.6e+002 -  
 2.4e+002  
 4 Bus4 1.05 10 1.2e+002 -  
 1.7e+002  
 2 Bus2 0.923 -6.1 9.4e+002 -15  
 0.68 0.3 5.4e+002 2.4e+002  
 kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000072 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000073 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000075 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000076 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000

---

Time = 1.52000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	14.9	15.4	50	471	299	389	1.01
3	Bus3	1.05	12.2	12.7	50	438	56.3	520	1.05

---

Maximum rotor angle difference : 2.74589 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	14.88	5 Bus5	1.05	9.4	2.1e+004	-18
				0.61	0.38	4.7e+002	3e+002
2 Bus2	0.923	-5.96	4 Bus4	1.05	10	5.5e+002	1.5e+002
				-1		-0.46	-2.8e+002

---

1.2e+002

			5	Bus5	1.05 -0.6	9.4 9.9e+002 1.6e+002 -0.18 -5.2e+002 -	
1.6e+002							
3	Bus3	1.050	12.23	4	Bus4	1.05 1.2	10 1.3e+004 9.6 0.056 3.6e+002 16
4	Bus4	1.046	10.37	3	Bus3	1.05	12 5.7e+002 -
1.7e+002						-1.2	-0.016 -3.6e+002 -
4.6							
			5	Bus5	1.05 4.4	9.4 1.4e+002 42 -2.7 73 -44	
			2	Bus2	0.923 1.5	-6 4.6e+002 0.62 0.26 2.8e+002 49	
5	Bus5	1.050	9.40	1	Bus1	1 -0.75	15 8.3e+002 1.6e+002 -0.38 -4.7e+002 -
2.4e+002			4	Bus4	1.05	10 1.2e+002 -	
1.7e+002						-6	-0.23 -73 -2.8
			2	Bus2	0.923 0.68	-6 9.4e+002 -15 0.3 5.4e+002 2.4e+002	
kp 0 kq 0 Iterations 3 dpmax 0.000078 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000079 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000080 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000081 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000082 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000083 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000083 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000084 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000085 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000086 dqmax 0.000000							

Time = 1.54000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	15.1	15.7	50	475	299	389	1.01
3	Bus3	1.05	12.4	12.8	50	434	56.4	520	1.05

Maximum rotor angle difference : 2.88173 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q

1	Bus1	1.000	15.15	5	Bus5	1.05 0.6	9.6 2.2e+004 0.38 4.8e+002	-17 3e+002
2	Bus2	0.922	-5.77	4	Bus4	1.05	11 5.5e+002 1.5e+002	

Time = 1.56000 Seconds

Time = 1.50000 seconds  
Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	15.4	16	50	478	299	389	1.01
3	Bus3	1.05	12.5	13	50	430	56.5	520	1.05

Maximum rotor angle difference : 2.98657 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

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2	Bus2	0.922	-5.58	4	Bus4	1.05	11	5.5e+002	1.5e+002	-	
1.2e+002				-1		-0.46	-0.46	-2.8e+002	-		
1.6e+002				5	Bus5	1.05	9.8	9.9e+002	1.6e+002	-	
				-0.6		-0.18	-0.18	-5.2e+002	-		
3	Bus3	1.050	12.52	4	Bus4	1.05	11	1.3e+004	9.8	-	
1.7e+002				1.3		0.059	3.5e+002	17			
4	Bus4	1.046	10.70	3	Bus3	1.05	13	5.6e+002	-		
5.4				-1.3		-0.019	-0.019	-3.5e+002	-		
				5	Bus5	1.05	9.8	1.3e+002	44	-	
				4.6		-3	-3	66	-43		
				2	Bus2	0.922	-5.6	4.6e+002	0.93	-	
				1.5		0.26	2.8e+002	49			
5	Bus5	1.050	9.81	1	Bus1	1	15	8.4e+002	1.6e+002	-	
2.4e+002				-0.75		-0.37	-0.37	-4.7e+002	-		
1.7e+002				4	Bus4	1.05	11	1.1e+002	-		
				-6.6		-0.39	-0.39	-66	-3.9		
				2	Bus2	0.922	-5.6	9.4e+002	-14		
				0.68		0.3	5.4e+002	2.4e+002			
kp 0 kq 0 Iterations 3 dpmax 0.000097 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000098 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000099 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000100 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000											
Time = 1.58000 Seconds											
Intermediate results for Machines											
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip		
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.		
1	Bus1	1	15.6	16.2	50	481	300	389	1.01		
3	Bus3	1.05	12.7	13.1	50	428	56.6	520	1.05		
Maximum rotor angle difference : 3.05917 b/w buses : 1 and 3											
Island 1 Common system frequency 50.028											
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines											
From Name		Voltage	Angle	To Name		Voltage	Angle	Current	Angle		
		pu	Degree			pu	Degree	Zl-real	Zl-im	P	Q
1	Bus1	1.000	15.63	5	Bus5	1.05	10.2	2.2e+004	-16		

Time = 1.60000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	15.8	16.4	50	482	300	389	1.01
3	Bus3	1.05	12.9	13.3	50	426	56.6	520	1.05

Maximum rotor angle difference : 3.09866 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Time = 1.62000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	16	16.6	50	483	300	389	1.01
3	Bus3	1.05	13.1	13.5	50	426	56.7	520	1.05

Maximum rotor angle difference : 3.10455 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle  
 $Z_l$  real       $Z_l$  im      P      Q

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1	Bus1	1.000	16.05	5	Bus5	1.05	10	2.2e+004	-16
2	Bus2	0.922	-4.99	4	Bus4	1.05	0.37	4.8e+002	3e+002
						-1	11	5.5e+002	1.5e+002
							-0.47	-2.7e+002	-
1.2e+002				5	Bus5	1.05	10	9.9e+002	1.6e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	13.05	4	Bus4	1.05	11	1.3e+004	10
						1.3	0.061	3.5e+002	17
4	Bus4	1.046	11.25	3	Bus3	1.05	13	5.5e+002	-
1.7e+002						-1.3	-0.021	-3.5e+002	-
5.8				5	Bus5	1.05	10	1.2e+002	46
						4.8	-3.3	63	-43
				2	Bus2	0.922	-5	4.6e+002	1.5
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	10.41	1	Bus1	1	16	8.5e+002	1.6e+002
						-0.74	-0.37	-4.8e+002	-
2.4e+002				4	Bus4	1.05	11	1e+002	-
1.7e+002						-7	-0.5	-63	-4.5
				2	Bus2	0.922	-5	9.4e+002	-14
						0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
Time = 1.64000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	16.2	16.8	50	482	300	389	1.01
3	Bus3	1.05	13.3	13.7	50	427	56.6	520	1.05
Maximum rotor angle difference : 3.07674 b/w buses : 1 and 3									
Island 1 Common system frequency 50.028									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		

-----

Time = 1.66000 Seconds

### Intermediate results for Machines

Intermediate Formulas for Bus 1									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	16.4	17	50	480	300	389	1.01
3	Bus3	1.05	13.5	14	50	429	56.6	520	1.05

Maximum rotor angle difference : 3.01554 b/w buses : 1 and 3

Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (BH) and power (MW-MVAR) for lines

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	16.41	5	Bus5	1.05		11	2.2e+004
						0.6	0.37	4.8e+002	3e+002
2	Bus2	0.922	-4.59	4	Bus4	1.05		12	5.5e+002
						-1		-0.46	1.5e+002
1.2e+002				5	Bus5	1.05		11	9.9e+002
						-0.6		-0.18	1.6e+002
1.6e+002									-5.2e+002
3	Bus3	1.050	13.49	4	Bus4	1.05		12	1.3e+004
						1.3	0.06	3.5e+002	11
4	Bus4	1.046	11.67	3	Bus3	1.05		13	5.6e+002
1.7e+002									-
5.5						-1.3		-0.02	-3.5e+002
				5	Bus5	1.05		11	1.2e+002
						4.7	-3.1	65	45
2	Bus2	0.922					-4.6	4.6e+002	1.9
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	10.81	1	Bus1	1		16	8.5e+002
2.4e+002						-0.74		-0.37	1.6e+002
1.7e+002				4	Bus4	1.05		12	1e+002
							-6.8	-0.43	-65
				2	Bus2	0.922		-4.6	9.4e+002
						0.68	0.3	5.4e+002	-13
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
Time = 1.68000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	16.6	17.1	50	477	299	389	1.01
3	Bus3	1.05	13.7	14.2	50	432	56.5	520	1.05
Maximum rotor angle difference : 2.92160 b/w buses : 1 and 3									
Island 1	Common system frequency				50.028				

From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	16.56	5	Bus5	1.05	11	2.2e+004	-16
						0.6	0.38	4.8e+002	3e+002
2	Bus2	0.922	-4.38	4	Bus4	1.05	12	5.5e+002	1.5e+002
						-1		-0.46	-2.8e+002
1.2e+002				5	Bus5	1.05	11	9.9e+002	1.6e+002
						-0.6		-0.18	-5.2e+002
1.6e+002									
3	Bus3	1.050	13.73	4	Bus4	1.05	12	1.3e+004	11
						1.3	0.059	3.5e+002	16
4	Bus4	1.046	11.90	3	Bus3	1.05	14	5.6e+002	-
1.7e+002									
5.2						-1.2		-0.019	-3.5e+002
				5	Bus5	1.05	11	1.3e+002	45
						4.6	-3	67	-44
				2	Bus2	0.922	-4.4	4.6e+002	2.1
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	11.00	1	Bus1	1	17	8.4e+002	1.6e+002
						-0.75		-0.37	-4.7e+002
2.4e+002				4	Bus4	1.05	12	1.1e+002	-
1.7e+002									
						-6.5	-0.36	-67	-3.7
				2	Bus2	0.922	-4.4	9.4e+002	-13
						0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
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kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
Time = 1.70000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	16.7	17.3	50	473	299	389	1.01
3	Bus3	1.05	14	14.5	50	436	56.4	520	1.05
Maximum rotor angle difference : 2.79600 b/w buses : 1 and 3									
Island	1 Common system frequency 50.028								

Time = 1.72000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	16.8	17.4	50	468	299	389	1.01
3	Bus3	1.05	14.3	14.7	50	441	56.2	520	1.05

Maximum rotor angle difference : 2.64016 b/w buses : 1 and 3

Island	1	Common system frequency	50.028						
<hr/>									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle						
To Name		Voltage	Angle						
		Zl-real	Zl-im						
		P	Q						
<hr/>									
1	Bus1	1.000	16.83						
		5	Bus5						
		1.05							
		0.61							
2	Bus2	0.923	-3.97						
		4	Bus4						
		1.05							
		-1							
1.2e+002									
		5	Bus5						
		1.05							
		-0.6							
1.6e+002									
3	Bus3	1.050	14.25						
		4	Bus4						
		1.05							
		1.2							
4	Bus4	1.046	12.38						
		3	Bus3						
		1.05							
1.7e+002									
		-1.2							
4.4									
		5	Bus5						
		1.05							
		4.3							
2.4e+002									
2	Bus2	0.923							
		-4							
		1.5							
1.7e+002									
5	Bus5	1.050	11.38						
		1	Bus1						
		1							
		-0.75							
2.4e+002									
		-5.9							
1.7e+002									
4	Bus4	1.05							
		12	1.2e+002						
		-0.19							
		-75							
		-4							
		0.68							
		9.4e+002							
		0.3							
		5.4e+002							
		2.4e+002							
<hr/>									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
Time = 1.74000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
<hr/>									
1	Bus1	1	16.9	17.5	50	462	298	389	1.01
3	Bus3	1.05	14.5	15	50	446	56.1	520	1.05

Maximum rotor angle difference : 2.45585 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	pu	Degree		pu	Degree	Amp	Degree
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	16.95	5 Bus5	1.05		12 2.1e+004	-16
2 Bus2	0.923	-3.76	4 Bus4	1.05		13 5.5e+002	1.5e+002
				1.05	-1	-0.46	-2.8e+002
			5 Bus5	1.05		12 9.9e+002	1.6e+002
				1.05	-0.6	-0.18	-5.2e+002
1.2e+002							
1.6e+002							
3 Bus3	1.050	14.54	4 Bus4	1.05		13 1.3e+004	12
				1.05	1.2	0.053	3.7e+002
4 Bus4	1.046	12.63	3 Bus3	1.05		15 5.8e+002	-
				1.05	-1.2	-0.013	-3.7e+002
1.7e+002							
3.9							
			5 Bus5	1.05		12 1.5e+002	42
				1.05	4.1	-2.3	80
2 Bus2	0.923		2 Bus2	0.923		-3.8 4.6e+002	2.9
				0.923	1.5	0.26 2.9e+002	49
5 Bus5	1.050	11.56	1 Bus1	1		17 8.2e+002	1.6e+002
				1		-0.39	-4.6e+002
2.4e+002							
1.7e+002							
			4 Bus4	1.05		13 1.3e+002	-
				1.05	-5.5	-0.11	-80
2 Bus2	0.923		2 Bus2	0.923		-3.8 9.4e+002	-12
				0.923	0.68	0.3 5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							

Time = 1.76000 Seconds

Intermediate results for Machines

GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	17	17.6	50	456	298	389	1.01
2	Bus2	1.05	14.8	15.3	50	453	55.9	520	1.05

Maximum rotor angle difference : 2.24517 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	1.000	17.05	5	Bus5	1.05	12	2.1e+004	-16
2	Bus2	0.923	-3.55	4	Bus4	0.61	0.4	4.6e+002	3e+002
					1.05	-1	13	5.5e+002	1.5e+002
							-0.45	-2.8e+002	-
1.2e+002				5	Bus5	1.05	12	9.9e+002	1.6e+002
					-0.6		-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	14.83	4	Bus4	1.05	13	1.4e+004	12
					1.2		0.05	3.7e+002	16
4	Bus4	1.046	12.89	3	Bus3	1.05	15	6e+002	-
1.7e+002						-1.2		-0.01	-3.7e+002
3.3				5	Bus5	1.05	12	1.6e+002	41
					4		-2.1	86	-46
				2	Bus2	0.923	-3.6	4.6e+002	3.1
					1.5		0.26	2.9e+002	49
5	Bus5	1.050	11.74	1	Bus1	1	17	8.1e+002	1.6e+002
					-0.76		-0.4	-4.5e+002	-
2.4e+002				4	Bus4	1.05	13	1.4e+002	-
1.7e+002						-5.1	-0.038	-86	-0.64
				2	Bus2	0.923	-3.6	9.4e+002	-12
						0.68	0.31	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000									
Time = 1.78000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	17	1	17	7	50	448	298
								389	1 01

```

3 Bus3 1.05 15.1 15.6 50 461 55.8 520 1.05
-----
Maximum rotor angle difference : 2.01054 b/w buses : 1 and 3
Island 1 Common system frequency 50.028
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name Voltage Angle To Name Voltage Angle Current Angle
          Zl-real Zl-im P Q
-----
1 Bus1 1.000 17.14 5 Bus5 1.05 12 2.1e+004 -16
          0.62 0.41 4.5e+002 3e+002
2 Bus2 0.923 -3.34 4 Bus4 1.05 13 5.5e+002 1.5e+002
          -1 -0.45 -2.8e+002 -
1.2e+002
          5 Bus5 1.05 12 9.9e+002 1.6e+002
          -0.6 -0.18 -5.2e+002 -
1.6e+002
3 Bus3 1.050 15.14 4 Bus4 1.05 13 1.4e+004 13
          1.2 0.048 3.8e+002 16
4 Bus4 1.046 13.16 3 Bus3 1.05 15 6.1e+002 -
1.7e+002
          -1.2 -0.0079 -3.8e+002 -
2.6
          5 Bus5 1.05 12 1.7e+002 40
          3.8 -1.9 92 -47
          2 Bus2 0.923 -3.3 4.7e+002 3.4
          1.5 0.25 2.9e+002 49
5 Bus5 1.050 11.93 1 Bus1 1 17 8e+002 1.6e+002
          -0.77 -0.42 -4.4e+002 -
2.4e+002
          4 Bus4 1.05 13 1.5e+002 -
1.7e+002
          -4.8 0.022 -92 0.43
          2 Bus2 0.923 -3.3 9.4e+002 -12
          0.69 0.31 5.4e+002 2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
Time = 1.80000 Seconds
Intermediate results for Machines
GNo Name Voltage Angle Delta Freq Pgen Qgen Pmech Efd/Slip
          pu Degree Degree Hzs. MW MVAR MW pu/P.U.

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1	Bus1	1	17.2	17.7	50	440	297	389	1.01
3	Bus3	1.05	15.5	16	50	469	55.6	520	1.05

---

Maximum rotor angle difference : 1.75464 b/w buses : 1 and 3  
Island 1 Common system frequency 50.028

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	17.22	5 Bus5	1.05	12	2e+004	-17
				0.62	0.42	4.4e+002	3e+002
2 Bus2	0.923	-3.13	4 Bus4	1.05	13	5.5e+002	1.5e+002
				-1		-0.45	-2.8e+002
1.2e+002			5 Bus5	1.05	12	9.9e+002	1.6e+002
				-0.6		-0.18	-5.2e+002
1.6e+002							
3 Bus3	1.050	15.45	4 Bus4	1.05	13	1.4e+004	13
				1.1	0.046	3.9e+002	16
4 Bus4	1.046	13.43	3 Bus3	1.05	15	6.2e+002	-
1.7e+002					-1.1	-0.0056	-3.9e+002
1.9			5 Bus5	1.05	12	1.8e+002	39
				3.6	-1.7	1e+002	-48
			2 Bus2	0.923	-3.1	4.7e+002	3.7
				1.5	0.25	2.9e+002	49
5 Bus5	1.050	12.11	1 Bus1	1	17	7.9e+002	1.6e+002
				-0.78		-0.43	-4.4e+002
2.4e+002			4 Bus4	1.05	13	1.6e+002	-
1.7e+002					-4.4	0.072	-99
			2 Bus2	0.923	-3.1	9.3e+002	-12
				0.69	0.31	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							

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Time = 1.82000 Seconds

Intermediate results for Machines

GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs	MW	MVAR	MW	pu/P_u

---

1	Bus1	1	17.3	17.8	50	431	297	389	1.01
3	Bus3	1.05	15.8	16.3	50	478	55.5	520	1.05

---

Maximum rotor angle difference : 1.48042 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.028

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im			P	Q		
1 Bus1	1.000	17.29	5	Bus5	1.05	12	2e+004	-17
					0.63	0.43	4.3e+002	3e+002
2 Bus2	0.923	-2.92	4	Bus4	1.05	14	5.5e+002	1.5e+002
					-1	-0.44	-2.8e+002	-
1.2e+002			5	Bus5	1.05	12	9.8e+002	1.6e+002
					-0.6	-0.18	-5.2e+002	-
1.6e+002								
3 Bus3	1.050	15.78	4	Bus4	1.05	14	1.5e+004	14
					1.1	0.043	4e+002	16
4 Bus4	1.046	13.71	3	Bus3	1.05	16	6.3e+002	-
1.7e+002								
2.4e+002								
5 Bus5	1.050	12.29	1	Bus1	1	17	7.8e+002	1.6e+002
					-0.78	-0.44	-4.3e+002	-
2.4e+002			4	Bus4	1.05	14	1.7e+002	-
1.7e+002						-4.1	0.11	-1.1e+002
2.9			2	Bus2	0.923	-2.9	9.3e+002	-12
					0.69	0.31	5.3e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000								

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Intermediate results for Machines										
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.	
1	Bus1	1	17.4	17.9	50	412	296	389	1.01	
3	Bus3	1.05	16.4	17	50	496	55.4	520	1.05	
<hr/>										
Maximum rotor angle difference : 0.88980 b/w buses : 1 and 3										
Island 1 Common system frequency 50.027										
<hr/>										
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
						Zl-real	Zl-im	P	Q	
1	Bus1	1.000	17.42	5	Bus5	1.05	13	2e+004	-18	
						0.64	0.46	4.1e+002	3e+002	
2	Bus2	0.923	-2.49	4	Bus4	1.05	14	5.6e+002	1.5e+002	
						-1	-0.43	-2.8e+002	-	
1.2e+002				5	Bus5	1.05	13	9.8e+002	1.6e+002	
						-0.6	-0.19	-5.2e+002	-	
1.6e+002										
3	Bus3	1.050	16.45	4	Bus4	1.05	14	1.5e+004	14	
						1.1	0.039	4.2e+002	15	
4	Bus4	1.046	14.28	3	Bus3	1.05	16	6.6e+002	-	
1.7e+002										
0.3										
				5	Bus5	1.05	13	2.1e+002	36	
						3	-1.2	1.2e+002	-50	
				2	Bus2	0.923	-2.5	4.7e+002	4.6	
						1.5	0.25	2.9e+002	50	
5	Bus5	1.050	12.64	1	Bus1	1	17	7.6e+002	1.6e+002	
						-0.8	-0.48	-4.1e+002	-	
2.4e+002				4	Bus4	1.05		14	2e+002	-
1.6e+002								0.16	-1.2e+002	
5.6										
				2	Bus2	0.923	-3.6	0.16	-1.2e+002	
						0.69	-2.5	9.3e+002	-12	
							0.31	5.3e+002	2.4e+002	
<hr/>										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000										

---

Time = 1.88000 Seconds  
 Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	17.5	17.9	50	403	296	389	1.01
3	Bus3	1.05	16.8	17.4	50	506	55.5	520	1.05

---

Maximum rotor angle difference : 0.58020 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	17.47	5 Bus5	1.05	13	1.9e+004	-19
				0.65	0.47	4e+002	3e+002
2 Bus2	0.923	-2.28	4 Bus4	1.05	15	5.6e+002	1.5e+002
				-1	-0.43	-2.8e+002	-
1.2e+002			5 Bus5	1.05	13	9.8e+002	1.6e+002
				-0.6	-0.19	-5.2e+002	-
1.6e+002			3 Bus3	1.050	16.79	4 Bus4	1.05
				1	0.037	1.6e+004	15
4 Bus4	1.046	14.57	3 Bus3	1.05	15	4.3e+002	15
1.7e+002				-1		6.8e+002	-
1			5 Bus5	1.05	13	2.3e+002	36
				2.9	-1.1	1.3e+002	-51
2 Bus2	0.923		2 Bus2	0.923	-2.3	4.8e+002	4.8
				1.5	0.25	2.9e+002	50
5 Bus5	1.050	12.82	1 Bus1	1	17	7.5e+002	1.6e+002
2.5e+002				-0.8	-0.49	-4e+002	-
1.6e+002			4 Bus4	1.05	15	2.1e+002	-
7.1				-3.3		0.18	-1.3e+002
			2 Bus2	0.923	-2.3	9.3e+002	-11
				0.69	0.31	5.3e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000							

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kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
-----
Time = 1.90000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu        Degree   Degree   Hzs.    MW      MVAR    MW      pu/P.U.
-----
1   Bus1       1        17.5     18      50      392     296     389     1.01
3   Bus3       1.05    17.1     17.7     50      516     55.5     520     1.05
-----
Maximum rotor angle difference : 0.26581 b/w buses : 1 and 3
Island 1 Common system frequency 50.027
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To     Name      Voltage Angle   Current Angle
                           Zl-real   Zl-im    P        Q
-----
1   Bus1       1.000    17.52    5     Bus5      1.05      13 1.9e+004 -19
                           0.65      0.49 3.9e+002 3e+002
2   Bus2       0.923    -2.06    4     Bus4      1.05      15 5.6e+002 1.6e+002
                           -1      -0.43 -2.9e+002 -
1.2e+002
                           5     Bus5      1.05      13 9.8e+002 1.6e+002
                           -0.6      -0.19 -5.1e+002 -
1.6e+002
3   Bus3       1.050    17.14    4     Bus4      1.05      15 1.6e+004 15
                           1      0.036 4.4e+002 16
4   Bus4       1.046    14.87    3     Bus3      1.05      17 7e+002 -
1.6e+002
                           -1      0.004 -4.4e+002
1.7
                           5     Bus5      1.05      13 2.4e+002 35
                           2.7      -1 1.4e+002 -52
                           2     Bus2      0.923    -2.1 4.8e+002 5.1
                           1.4      0.25 2.9e+002 50
5   Bus5       1.050    12.99    1     Bus1      1      18 7.3e+002 1.6e+002
                           -0.81    -0.51 -3.9e+002 -
2.5e+002
                           4     Bus4      1.05      15 2.2e+002 -
1.6e+002
                           -3.1      0.19 -1.4e+002
8.6
                           2     Bus2      0.923    -2.1 9.3e+002 -11
                           0.69      0.31 5.3e+002 2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000

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kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000  
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
```

Time = 1.92000 Seconds

## Intermediate results for Machines

Intermediate Results for Machine									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
	pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.	
1	Bus1	1	17.6	18	50	382	295	389	1.01
3	Bus3	1.05	17.5	18.1	50	527	55.7	520	1.05

Maximum rotor angle difference : 0.04974 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

Voltage (pu), Current (AHL's), Impedance (f.s) and power (kW/kVAR) for lines



Time = 1.96000 Seconds

## Intermediate results for Machines

Intermediate Bus No		Name		Voltage		Angle		Delta		Freq	Pgen	Qgen	Pmech	Efd/Slip
GNo	Name	pu		Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.				
1	Bus1		1	17.7	18.1	50	362	295	389	1.01				
3	Bus3	1.05		18.2	18.8	50	547	56.1	520	1.05				

Maximum rotor angle difference : 0.66977 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage      Angle      To Name      Voltage      Angle      Current      Angle

From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	1.000	17.68	5	Bus5	1.05	14	1.8e+004	-21
					0.66	0.54	3.6e+002	3e+002	
2	Bus2	0.923	-1.42	4	Bus4	1.05	16	5.7e+002	1.6e+002
					-1	-0.41	-2.9e+002	-	
1.2e+002				5	Bus5	1.05	14	9.7e+002	1.6e+002
					-0.61	-0.19	-5.1e+002	-	
1.6e+002									
3	Bus3	1.050	18.17	4	Bus4	1.05	16	1.7e+004	16
					0.94	0.033	4.7e+002	16	
4	Bus4	1.046	15.74	3	Bus3	1.05	18	7.4e+002	-
1.6e+002						-0.94	0.0074	-4.7e+002	
3.7									
				5	Bus5	1.05	14	2.8e+002	34
					2.4	-0.77	1.7e+002	-55	
				2	Bus2	0.923	-1.4	4.8e+002	6
					1.4	0.24	3e+002	51	
5	Bus5	1.051	13.52	1	Bus1	1	18	7e+002	1.6e+002
					-0.82	-0.58	-3.6e+002	-	
2.5e+002									
				4	Bus4	1.05	16	2.7e+002	-
1.6e+002						-2.6	0.21	-1.7e+002	
13									
				2	Bus2	0.923	-1.4	9.2e+002	-11
					0.7	0.32	5.3e+002	2.4e+002	

Time = 1.98000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	17.7	18.1	50	353	295	389	1.01
3	Bus3	1.05	18.5	19.1	50	556	56.3	520	1.05

Maximum rotor angle difference : 0.96707 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage      Angle      To      Name      Voltage      Angle      Current      Angle







-0.84 -0.66 -3.2e+002 -

2.6e+002							
	4	Bus4	1.05				
1.6e+002							
	2	Bus2	0.923	-2.2	0.21	-2e+002	18
				0.7	-0.57	9.1e+002	-10
					0.32	5.2e+002	2.4e+002

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kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000

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Time = 2.06000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	18.1	18.4	50	320	295	389	1.01
3	Bus3	1.05	19.8	20.4	50	589	57.6	520	1.05

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Maximum rotor angle difference : 1.99322 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
				Zl-real	Zl-im	P	Q		
1	Bus1	1.000	18.05	5	Bus5	1.05	14	1.7e+004	-25
2	Bus2	0.923	-0.36	4	Bus4	0.68	0.62	3.2e+002	3e+002
						1.05	17	5.7e+002	1.6e+002
						-1		-0.4	-2.9e+002
1.2e+002				5	Bus5	1.05	14	9.6e+002	1.6e+002
						-0.61		-0.2	-5.1e+002
1.6e+002									
3	Bus3	1.050	19.78	4	Bus4	1.05	17	1.9e+004	18
						0.86	0.03	5.1e+002	18
4	Bus4	1.046	17.12	3	Bus3	1.05	14	3.4e+002	33
1.6e+002						-0.86		0.01	-5.1e+002
5.9				5	Bus5	1.05			
						2	-0.56	2e+002	-58
2	Bus2	0.923				0.36	4.9e+002		7.4
						1.4	0.24	3e+002	Page 224



5	Bus5	1.051	14.60	1	Bus1	1.4 -0.84	0.24 18 -0.7	3e+002 6.4e+002 -3.1e+002	52	
2.6e+002				4	Bus4	1.05		17 3.3e+002	-	
1.6e+002						-2.1		0.2	-2.1e+002	
20				2	Bus2	0.923 0.7	-0.16 0.32	9.1e+002 5.2e+002	-10 2.4e+002	
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000										
Time = 2.10000 Seconds										
Intermediate results for Machines										
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.	
1	Bus1	1	18.3	18.6	50	307	295	389	1.01	
3	Bus3	1.05	20.3	21	50	602	58.2	520	1.05	
Maximum rotor angle difference : 2.36756 b/w buses : 1 and 3										
Island 1 Common system frequency 50.027										
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
						Zl-real	Zl-im	P	Q	
1	Bus1	1.000	18.27	5	Bus5	1.05 0.68		15 0.65	1.6e+004 3.1e+002	-26 3e+002
2	Bus2	0.923	0.05	4	Bus4	1.05 -1		18 -0.39	5.7e+002 -3e+002	1.6e+002 -
1.2e+002				5	Bus5	1.05 -0.61		15 -0.2	9.6e+002 -5e+002	1.6e+002 -
1.6e+002										
3	Bus3	1.050	20.35	4	Bus4	1.05 0.84		18 0.03	1.9e+004 5.2e+002	18 18
4	Bus4	1.046	17.63	3	Bus3	1.05 -0.84		20 0.01	8.3e+002 -5.2e+002	-
1.6e+002										
6.4				5	Bus5	1.05		15 3	6e+002	33





4 Bus4 1.046 18.11 3 Bus3 1.05 21 8.5e+002 -
   
 $1.6e+002$  -0.83 0.011 -5.3e+002

6.8 5 Bus5 1.05 15 3.7e+002 33
   
 1.8 -0.49 2.2e+002 -59

2 Bus2 0.922 0.46 5e+002 8.3
   
 1.4 0.24 3.1e+002 53

5 Bus5 1.051 15.16 1 Bus1 1 19 6.3e+002 1.5e+002
   
 $2.6e+002$  -0.84 -0.74 -3e+002 -

$1.6e+002$  4 Bus4 1.05 18 3.5e+002 -
   
 -2 0.2 -2.2e+002

23 2 Bus2 0.922 0.46 9.1e+002 -9.5
   
 0.7 0.32 5.2e+002 2.4e+002

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000

Time = 2.16000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	18.7	19.1	50	296	296	389	1.01
3	Bus3	1.05	21.1	21.8	50	613	58.9	520	1.05

Maximum rotor angle difference : 2.70520 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	18.70	5 Bus5	1.05	15	1.6e+004	-26
				0.68	0.68	3e+002	3e+002
2 Bus2	0.922	0.66	4 Bus4	1.05	18	5.8e+002	1.6e+002
				-1	-0.39	-3e+002	-

$1.1e+002$

Power Research and Development Consultants Pvt. Ltd. 5 Bus5 1.05 15 9.6e+002 1.6e+002

$1.7e+002$  -0.61 -0.2 -5e+002

Page 229

3 Bus3 1.050 21.10 4 Bus4 1.05 18 2e+004 19  
 4 Bus4 1.046 18.33 3 Bus3 1.05 21 8.5e+002 -  
 1.6e+002  
 6.9  
 5 Bus5 1.05 15 3.7e+002 33  
 1.8 -0.48 2.2e+002 -60  
 2 Bus2 0.922 0.66 5e+002 8.6  
 1.4 0.24 3.1e+002 53  
 5 Bus5 1.051 15.35 1 Bus1 1 19 6.3e+002 1.5e+002  
 2.6e+002  
 1.6e+002  
 4 Bus4 1.05 18 3.6e+002 -  
 2.6e+002  
 1.6e+002  
 23  
 2 Bus2 0.922 0.66 9.1e+002 -9.3  
 0.7 0.32 5.2e+002 2.4e+002  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000  
 Time = 2.18000 Seconds  
 Intermediate results for Machines  

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu.P.U.
1	Bus1	1	18.9	19.2	50	295	296	389	1.01
3	Bus3	1.05	21.3	22	50	614	59	520	1.05

  
 Maximum rotor angle difference : 2.75240 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027  
 Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q
1 Bus1	1.000	18.88	5 Bus5	1.05	16	1.6e+004	-26
2 Bus2	0.922	0.86	4 Bus4	0.68	0.68	2.9e+002	3e+002
				1.05	19	5.8e+002	1.6e+002
				-1	-0.39	-3e+002	-

 1.1e+002  
 5 Bus5 1.05 16 9.6e+002 1.6e+002



Time = 2.22000 Seconds

### Intermediate results for Machines

GNO	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	19.3	19.6	50	295	296	389	1.01
3	Bus3	1.05	21.7	22.4	50	614	59	520	1.05

Maximum rotor angle difference : 3.74474 b/w buses : 1 and 3

Island 1 Common system frequency 50.037

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle  
                         Zl-real    Zl-im    P    Q

2	Bus2	0.922	1.26	4	Bus4	0.68 1.05 -1	0.68 19 5.8e+002 -0.39	2.9e+002 1.6e+002 -3e+002 -	3e+002
1.1e+002				5	Bus5	1.05 -0.61	16 -0.2	9.6e+002 -5e+002	-1.6e+002
1.7e+002				4	Bus4	1.05 0.82	19 0.029	2e+004 5.3e+002	20 19
3	Bus3	1.050	21.72	4	Bus4	1.05 0.82	1.05	22	8.5e+002
4	Bus4	1.046	18.93	3	Bus3	-0.82	0.011	-5.3e+002	-
1.6e+002				5	Bus5	1.05 1.8	16 -0.48	3.7e+002 2.3e+002	34 -60
7				2	Bus2	0.922 1.4	1.3 0.24	5e+002 3.1e+002	9.2 53
5	Bus5	1.051	15.94	1	Bus1	1 -0.84	19 -0.75	6.2e+002 -2.9e+002	1.5e+002 -
2.6e+002				4	Bus4	1.05		19	3.6e+002
1.6e+002						-1.9		0.2	-2.3e+002
23				2	Bus2	0.922 0.71	1.3 0.32	9.1e+002 5.2e+002	-8.7 2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									

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Time = 2.24000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	19.5	19.9	50	296	296	389	1.01
3	Bus3	1.05	21.9	22.5	50	613	58.9	520	1.05

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Maximum rotor angle difference : 2.68993 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	71-real	71-im		P	Q		

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1	Bus1	1.000	19.49	5	Bus5	1.05 0.68	16 0.68	1.6e+004 3e+002	-25 3e+002
2	Bus2	0.922	1.45	4	Bus4	1.05 -1	19 -0.39	5.8e+002 -3e+002	1.6e+002 -
1.1e+002				5	Bus5	1.05 -0.61	16 -0.2	9.6e+002 -5e+002	1.6e+002 -
1.7e+002				3	Bus3	1.05 0.83	19 0.029	2e+004 5.3e+002	20 19
3	Bus3	1.050	21.89	4	Bus4	1.05 0.83	1.05	22 0.011	8.5e+002 -5.3e+002
4	Bus4	1.046	19.12	3	Bus3	-0.82			
1.6e+002				5	Bus5	1.05 1.8	16 -0.48	3.7e+002 2.2e+002	34 -60
6.9				2	Bus2	0.922 1.4	1.4 0.24	5e+002 3.1e+002	9.3 53
5	Bus5	1.051	16.14	1	Bus1	1 -0.84	19 -0.75	6.3e+002 -2.9e+002	1.5e+002 -
2.6e+002				4	Bus4	1.05		19 0.2	3.6e+002 -2.2e+002
1.6e+002						-2			
23				2	Bus2	0.922 0.7	1.4 0.32	9.1e+002 5.2e+002	-8.5 2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000005 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000100 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000099 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000098 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000097 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000096 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000095 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000094 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000093 dqmax 0.000000									

Time = 2.26000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	19.7	20.1	50	299	296	389	1.01
3	Bus3	1.05	22	22.7	50	610	58.7	520	1.05

Maximum rotor angle difference : 2.60179 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	19.73	5	Bus5	1.05		16	1.6e+004
						0.68	0.67	3e+002	3e+002
2	Bus2	0.922	1.64	4	Bus4	1.05		19	5.8e+002
						-1		1.6e+002	-0.39
1.1e+002				5	Bus5	1.05		16	9.6e+002
						-0.61		-0.2	-5e+002
1.7e+002									
3	Bus3	1.050	22.05	4	Bus4	1.05		19	1.9e+004
						0.83	0.029	5.3e+002	20
4	Bus4	1.046	19.29	3	Bus3	1.05		22	8.5e+002
						-0.83		0.011	-5.3e+002
1.6e+002									
6.8				5	Bus5	1.05		16	3.7e+002
						1.8	-0.49	2.2e+002	34
				2	Bus2	0.922		1.6	5e+002
						1.4	0.24	3.1e+002	9.5
5	Bus5	1.051	16.34	1	Bus1	1		20	6.3e+002
						-0.84		-0.74	-3e+002
2.6e+002				4	Bus4	1.05		19	3.5e+002
1.6e+002						-2		0.2	-2.2e+002
23				2	Bus2	0.922		1.6	9.1e+002
						0.7	0.32	5.2e+002	-8.3
									2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.0000092 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000091 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000090 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000089 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000088 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000087 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000086 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000085 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000084 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.0000083 dqmax 0.000000									

Time = 2.28000 Seconds

#### Intermediate results for Machines

GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	20	20.3	50	303	295	389	1.01
3	Bus3	1.05	22.2	22.8	50	606	58.5	520	1.05

Maximum rotor angle difference = 2.46132 b/w buses : 1 and 3

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	1.000	19.98	5	Bus5	1.05 0.68	17 0.66	1.6e+004 3e+002	-24 3e+002
2	Bus2	0.922	1.83	4	Bus4	1.05 -1	19 -0.39	5.8e+002 -3e+002	1.6e+002 -
1.1e+002				5	Bus5	1.05 -0.61	17 -0.2	9.6e+002 -5e+002	1.6e+002 -
1.6e+002				3	Bus3	1.05 0.84	19 0.029	1.9e+004 5.3e+002	20 18
3	Bus3	1.050	22.19	4	Bus4	1.05 0.84	19 0.029	1.9e+004 5.3e+002	20 18
4	Bus4	1.046	19.45	3	Bus3	1.05 -0.83	22	8.4e+002 0.011	-
1.6e+002				6.6	Bus5	1.05 1.9	17 -0.5	3.6e+002 2.2e+002	35 -59
2.6e+002				5	Bus5	1.05 1.9	17 -0.5	3.6e+002 2.2e+002	35 -59
1.6e+002				2	Bus2	0.922 1.4	1.8 0.24	5e+002 3.1e+002	9.7 52
2.6e+002				5	Bus5	1.05 -0.84	20 -0.73	6.3e+002 -3e+002	1.6e+002 -
1.6e+002				4	Bus4	1.05 -2	19	3.5e+002 0.2	-
22				2	Bus2	0.922 0.7	1.8 0.32	9.1e+002 5.2e+002	-8.1 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000082 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000081 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000080 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000079 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000078 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000076 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000075 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000									

Time = 2.30000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	20.2	20.6	50	307	295	389	1.01
3	Bus3	1.05	22.3	23	50	601	58.2	520	1.05

Maximum rotor angle difference : 2.32988 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
					z1-real	z1-im	P	Q	
1	Bus1	1.000	20.24	5	Bus5	1.05	17	1.6e+004	-24
					0.68	0.65	3.1e+002	3e+002	
2	Bus2	0.923	2.02	4	Bus4	1.05	20	5.7e+002	1.6e+002
					-1	-0.39	-3e+002	-	
1.2e+002				5	Bus5	1.05	17	9.6e+002	1.6e+002
					-0.61	-0.2	-5e+002	-	
1.6e+002				4	Bus4	1.05	20	1.9e+004	20
3	Bus3	1.050	22.32	4	Bus4	1.05	0.03	5.2e+002	18
					0.84	0.24	3e+002	52	
1.6e+002				3	Bus3	1.05	22	8.3e+002	-
4	Bus4	1.046	19.60						
						-0.84	0.01	-5.2e+002	
6.5				5	Bus5	1.05	17	3.6e+002	35
					1.9	-0.52	2.2e+002	-59	
				2	Bus2	0.923	2	4.9e+002	9.8
					1.4	0.24	3e+002	52	
5	Bus5	1.051	16.76	1	Bus1	1	20	6.4e+002	1.6e+002
					-0.84	-0.71	-3e+002	-	
2.6e+002				4	Bus4	1.05	20	3.4e+002	-
1.6e+002						-2	0.2	-2.1e+002	
21				2	Bus2	0.923	2	9.1e+002	-7.9
					0.7	0.32	5.2e+002	2.4e+002	
kp 0 kq 0 Iterations 3 dpmax 0.000073 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000072 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000065 dqmax 0.000000									

Time = 2.32000 Seconds

Intermediate results for Machines

GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.

3 Bus3 1.05 22.4 23.1 50 596 57.9 520 1.05

---

Maximum rotor angle difference : 2.14919 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name Voltage Angle To Name Voltage Angle Current Angle  
 Zl-real Zl-im P Q

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1	Bus1	1.000	20.52	5	Bus5	1.05	17	1.7e+004	-23
						0.68	0.64	3.1e+002	3e+002
2	Bus2	0.923	2.21	4	Bus4	1.05	20	5.7e+002	1.6e+002
						-1	-0.39	-2.9e+002	-
1.2e+002				5	Bus5	1.05	17	9.6e+002	1.6e+002
						-0.61	-0.2	-5.1e+002	-
1.6e+002									
3	Bus3	1.050	22.43	4	Bus4	1.05	20	1.9e+004	20
						0.85	0.03	5.2e+002	18
4	Bus4	1.046	19.75	3	Bus3	1.05	22	8.2e+002	-
1.6e+002							-0.85	0.01	-5.1e+002
6.2				5	Bus5	1.05	17	3.5e+002	35
						1.9	-0.54	2.1e+002	-58
				2	Bus2	0.923	2.2	4.9e+002	10
						1.4	0.24	3e+002	52
5	Bus5	1.051	16.97	1	Bus1	1	21	6.4e+002	1.6e+002
						-0.84	-0.7	-3.1e+002	-
2.6e+002				4	Bus4	1.05	20	3.3e+002	-
1.6e+002							-2.1	0.2	-2.1e+002
20				2	Bus2	0.923	2.2	9.1e+002	-7.6
						0.7	0.32	5.2e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000062 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000060 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000									
Time = 2.34000 Seconds									
Intermediate results for Machines									
CNO Name Voltage Angle Delta Freq Pgen Open Pmech Mfd/Slip									
Power Research and Development Consultants Ltd.	Power	Consultants	Hzs.	MW	MVAR	MW	Pv	Page	238

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1	Bus1	1	20.8	21.2	50	320	295	389	1.01
3	Bus3	1.05	22.5	23.2	50	589	57.6	520	1.05

-----

Maximum rotor angle difference : 1.94131 b/w buses : 1 and 3  
Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	20.81	5 Bus5	1.05	17	1.7e+004	-22
				0.68	0.62	3.2e+002	3e+002
2 Bus2	0.923	2.40	4 Bus4	1.05	20	5.7e+002	1.6e+002
				-1	-0.4	-2.9e+002	-
1.2e+002			5 Bus5	1.05	17	9.6e+002	1.6e+002
				-0.61	-0.2	-5.1e+002	-
1.6e+002							
3 Bus3	1.050	22.53	4 Bus4	1.05	20	1.9e+004	21
				0.87	0.03	5.1e+002	18
4 Bus4	1.046	19.88	3 Bus3	1.05	23	8.1e+002	-
1.6e+002					-0.86	0.01	-5.1e+002
5.9			5 Bus5	1.05	17	3.4e+002	36
				2	-0.56	2e+002	-58
2 Bus2	0.923	2.4	4 Bus4	1.05	20	4.9e+002	10
				1.4	0.24	3e+002	52
5 Bus5	1.051	17.18	1 Bus1	1	21	6.5e+002	1.6e+002
				-0.84	-0.68	-3.2e+002	-
2.6e+002			4 Bus4	1.05	20	3.3e+002	-
1.6e+002					-2.2	0.21	-2e+002
2 Bus2	0.923	2.4			0.7	0.32	9.1e+002
							-7.4
							2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000056 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000054 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000  
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000

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Time = 2.36000 Seconds  
Intermediate results for Machines

CNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
-----	------	---------	-------	-------	------	------	------	-------	----------

	pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.		
1	Bus1	1	21.1	21.5	50	327	295	389	1.01	
3	Bus3	1.05	22.6	23.2	50	582	57.3	520	1.05	
-----										
Maximum rotor angle difference : 1.70864 b/w buses : 1 and 3										
Island 1 Common system frequency 50.027										
-----										
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle		
					Zl-real	Zl-im	P	Q		
1	Bus1	1.000	21.12	5	Bus5	1.05		17	1.7e+004	-21
						0.67	0.61	3.3e+002	3e+002	-
2	Bus2	0.923	2.58	4	Bus4	1.05		20	5.7e+002	1.6e+002
						-1		-0.4	-2.9e+002	-
1.2e+002				5	Bus5	1.05		17	9.7e+002	1.6e+002
						-0.61		-0.2	-5.1e+002	-
1.6e+002										
3	Bus3	1.050	22.62	4	Bus4	1.05		20	1.8e+004	21
						0.88	0.03	5e+002	17	-
4	Bus4	1.046	20.01	3	Bus3	1.05		23	8e+002	-
1.6e+002						-0.87	0.0098	-5e+002	5.6	
				5	Bus5	1.05		17	3.3e+002	36
						2	-0.59	2e+002	-57	-
				2	Bus2	0.923		2.6	4.9e+002	10
						1.4	0.24	3e+002	52	-
5	Bus5	1.051	17.39	1	Bus1	1		21	6.6e+002	1.6e+002
						-0.84		-0.66	-3.2e+002	-
2.6e+002				4	Bus4	1.05		20	3.2e+002	-
1.6e+002						-2.2	0.21	-2e+002	18	
				2	Bus2	0.923		2.6	9.1e+002	-7.1
						0.7	0.32	5.2e+002	2.4e+002	-
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000										
Time = 2.38000 Seconds										
Intermediate results for Machines										
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip	

Power Research and Development

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	21.8	22.2	50	344	295	389	1.01
3	Bus3	1.05	22.8	23.4	50	565	56.6	520	1.05

Maximum rotor angle difference : 1.17980 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

## Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name		Voltage	Angle	To Name		Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	21.75	5	Bus5	1.05	18	1.7e+004	-19
						0.67	0.57	3.4e+002	3e+002
2	Bus2	0.923	2.95	4	Bus4	1.05	20	5.7e+002	1.6e+002
						-1	-0.41	-2.9e+002	-
1.2e+002				5	Bus5	1.05	18	9.7e+002	1.7e+002
						-0.61	-0.19	-5.1e+002	-
1.6e+002				4	Bus4	1.05	20	1.8e+004	21
						0.91	0.031	4.8e+002	17
4	Bus4	1.046	20.25	3	Bus3	1.05	23	7.7e+002	-
1.6e+002						-0.91	0.0089	-4.8e+002	
4.7				5	Bus5	1.05	18	3.1e+002	37
						2.2	-0.67	1.8e+002	-56
				2	Bus2	0.923	2.9	4.9e+002	11
						1.4	0.24	3e+002	52
5	Bus5	1.051	17.82	1	Bus1	1	22	6.8e+002	1.6e+002
						-0.83	-0.62	-3.4e+002	-
2.5e+002				4	Bus4	1.05	20	2.9e+002	-
1.6e+002						-2.4	0.21	-1.8e+002	
16				2	Bus2	0.923	2.9	9.2e+002	-6.6
						0.7	0.32	5.2e+002	2.4e+002

```

kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000

```

Time = 2.42000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	22.1	22.5	50	353	295	389	1.01
3	Bus3	1.05	22.8	23.4	50	556	56.3	520	1.05

Maximum rotor angle difference : 0.88972 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	22.09	5 Bus5	1.05		18 1.8e+004	-18
				0.67		0.56 3.5e+002	3e+002
2 Bus2	0.923	3.13	4 Bus4	1.05		20 5.7e+002	1.6e+002
				-1		-0.41 -2.9e+002	-
1.2e+002			5 Bus5	1.05		18 9.7e+002	1.7e+002
				-0.61		-0.19 -5.1e+002	-
1.6e+002							
3 Bus3	1.050	22.83	4 Bus4	1.05		20 1.7e+004	21
				0.93		0.032 4.8e+002	16
4 Bus4	1.046	20.36	3 Bus3	1.05		23 7.6e+002	-
1.6e+002						-0.92	0.0082 -4.7e+002
4.2			5 Bus5	1.05		18 2.9e+002	38
				2.3		-0.72 1.8e+002	-56
2 Bus2	0.923			0.923		3.1 4.9e+002	11
				1.4		0.24 3e+002	51
5 Bus5	1.051	18.04	1 Bus1	1		22 6.9e+002	1.6e+002
				-0.83		-0.6 -3.5e+002	-
2.5e+002			4 Bus4	1.05		20 2.8e+002	-
1.6e+002						-2.5	0.21 -1.7e+002
14			2 Bus2	0.923		3.1 9.2e+002	-6.4
				0.7		0.32 5.2e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000							
kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000							

kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000

Time = 2.44000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	22.4	22.9	50	363	295	389	1.01
3	Bus3	1.05	22.9	23.5	50	546	56	520	1.05

Maximum rotor angle difference : 0.58692 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
				z1-real	z1-im	P	Q	
1	Bus1	1.000	22.42	5	Bus5	1.05	18 1.8e+004	-17
					0.66	0.54 3.6e+002	3e+002	
2	Bus2	0.923	3.31	4	Bus4	1.05	20 5.7e+002	1.6e+002
					-1	-0.41 -2.9e+002	-	
1.2e+002				5	Bus5	1.05	18 9.7e+002	1.7e+002
					-0.61	-0.19 -5.1e+002	-	
1.6e+002				3	Bus4	1.05	20 1.7e+004	21
3	Bus3	1.050	22.89	4	Bus4	1.05	0.033 4.7e+002	16
4	Bus4	1.046	20.46	3	Bus3	1.05	23 7.4e+002	-
1.6e+002						-0.94	0.0074	-4.6e+002
3.7				5	Bus5	1.05	18 2.8e+002	39
					2.4	-0.78 1.7e+002	-55	
				2	Bus2	0.923	3.3 4.8e+002	11
					1.4	0.24 3e+002	51	
5	Bus5	1.051	18.25	1	Bus1	1	22 7e+002	1.6e+002
					-0.82	-0.58 -3.6e+002	-	
2.5e+002				4	Bus4	1.05	20 2.7e+002	-
1.6e+002						-2.6	0.21	-1.7e+002
13				2	Bus2	0.923	3.3 9.2e+002	-6.1
					0.7	0.32 5.3e+002	2.4e+002	

kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000

```

kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
-----
```

Time = 2.46000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	22.8	23.2	50	373	295	389	1.01
3	Bus3	1.05	22.9	23.5	50	536	55.8	520	1.05

Maximum rotor angle difference : 0.27489 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
	Zl-real	Zl-im		P	Q		
1 Bus1	1.000	22.76	5 Bus5	1.05		18	1.8e+004
				0.66		0.52	3.7e+002
2 Bus2	0.923	3.49	4 Bus4	1.05		21	5.6e+002
				-1		-0.42	-2.9e+002
1.2e+002			5 Bus5	1.05		18	9.7e+002
				-0.6		-0.19	-5.1e+002
1.6e+002							
3 Bus3	1.050	22.94	4 Bus4	1.05		21	1.7e+004
				0.97		0.034	4.6e+002
4 Bus4	1.046	20.57	3 Bus3	1.05		23	7.3e+002
1.6e+002						-0.96	0.0065
3							-4.5e+002
			5 Bus5	1.05		18	2.7e+002
				2.5		-0.85	1.6e+002
			2 Bus2	0.923		3.5	4.8e+002
				1.4		0.25	3e+002
5 Bus5	1.051	18.47	1 Bus1	1		23	7.1e+002
				-0.82		-0.55	-3.7e+002
2.5e+002			4 Bus4	1.05		21	2.5e+002
1.6e+002						-2.8	0.2
11							-1.6e+002
			2 Bus2	0.923		3.5	9.2e+002
				0.7		0.31	5.3e+002
							2.4e+002

```

kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000026 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000026 dqmax 0.000000
-----
```



Time = 2.50000 Seconds

## Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	23.4	23.9	50	394	296	389	1.01
3	Bus3	1.05	23	23.6	50	515	55.5	520	1.05

Maximum rotor angle difference : 0.36237 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To Name      Voltage Angle      Current Angle

Bus Name	Voltage	Angle	Re	Im	Bus Name	Voltage	Angle	Re	Im	Current	Angle	Re	Im	
1	Bus1	1.000	23.45	5	Bus5	1.05		19	1.9e+004	-13				
						0.65		0.49	3.9e+002	3e+002				
2	Bus2	0.923	3.85	4	Bus4	1.05		21	5.6e+002	1.6e+002				
						-1		-0.43	-2.9e+002	-				
1.2e+002					5	Bus5	1.05		19	9.8e+002	1.7e+002			
						-0.6		-0.19	-5.1e+002	-				
1.6e+002					3	Bus3	1.050	23.03	4	Bus4	1.05		21	
						1		0.036	4.4e+002	21				
1.6e+002					4	Bus4	1.046	20.77	3	Bus3	1.05		23	
									6.9e+002	16				
1.7								-1		0.0039	-4.3e+002			
						5	Bus5	1.05		19	2.4e+002	41		
							2.7		-1	1.4e+002	-52			
						2	Bus2	0.923		3.8	4.8e+002	11		
							1.4		0.25	2.9e+002	50			
					5	Bus5	1.050	18.91	1	Bus1	1		23	
								-0.81		-0.51	-3.9e+002	-		
2.5e+002														
1.6e+002						4	Bus4		1.05		21	2.2e+002	-	
8.4								-3.1		0.19	-1.4e+002			
						2	Bus2	0.923		3.8	9.3e+002	-5.4		
							0.69		0.31	5.3e+002	2.4e+002			

Time = 2.52000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	23.8	24.3	50	404	296	389	1.01
3	Bus3	1.05	23.1	23.6	50	505	55.4	520	1.05

Maximum rotor angle difference : 0.68025 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name      Voltage Angle      To Name      Voltage Angle      Current Angle

```

2      Bus2      0.923      4 9.3e+002      -5.1
                                0.69      0.31 5.3e+002 2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000026 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000027 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000028 dqmax 0.000000

Time = 2.54000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta   Freq   Pgen   Qgen   Pmech   Efd/Slip
          pu       Degree  Degree  Hzs.    MW     MVAR    MW    pu/P.U.
-----
1     Bus1      1        24.1    24.6    50      414     296     389     1.01
3     Bus3      1.05    23.1    23.6    50      495     55.4    520     1.05

Maximum rotor angle difference : 0.99272 b/w buses : 1 and 3
Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To      Name      Voltage Angle   Current Angle
          pu       Degree  pu       Degree  Zl-real Zl-im   P         Q
-----
1     Bus1      1.000    24.13   5      Bus5      1.05      19 2e+004      -11
                                0.64      0.46 4.1e+002 3e+002
2     Bus2      0.923    4.21    4      Bus4      1.05      21 5.6e+002 1.6e+002
                                -1      -0.44 -2.8e+002 -
1.2e+002
                                5      Bus5      1.05      19 9.8e+002 1.7e+002
                                -0.6      -0.19 -5.2e+002 -
1.6e+002
3     Bus3      1.050    23.13   4      Bus4      1.05      21 1.5e+004      21
                                1.1      0.039 4.2e+002 15
4     Bus4      1.046    20.97   3      Bus3      1.05      23 6.6e+002      -
1.6e+002
                                5      Bus5      1.05      19 2.1e+002      43
                                3.1      -1.3 1.2e+002      -50
                                2      Bus2      0.923      4.2 4.7e+002      11
                                1.5      0.25 2.9e+002      50
5     Bus5      1.050    19.34   1      Bus1      1        24 7.6e+002 1.7e+002
                                -0.79      -0.47 -4.1e+002 -
2.4e+002
                                4      Bus4      1.05      21 1.9e+002      -
1.6e+002

```

-3.6                    0.16    -1.2e+002

5.4

2	Bus2	0.923	4.2	9.3e+002	-4.8
		0.69	0.31	5.3e+002	2.4e+002

kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000029 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000030 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000  
 kp 0 kq 0 Iterations 3 dpmax 0.000031 dqmax 0.000000

---

Time = 2.56000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	24.5	25	50	424	297	389	1.01
3	Bus3	1.05	23.2	23.7	50	485	55.5	520	1.05

---

Maximum rotor angle difference : 1.29616 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
	Zl-real	Zl-im		P	Q			
1 Bus1	1.000	24.47	5 Bus5	1.05		20	2e+004	-11
				0.63		0.44	4.2e+002	3e+002
2 Bus2	0.923	4.39	4 Bus4	1.05		21	5.6e+002	1.6e+002
				-1		-0.44	-2.8e+002	-
1.2e+002			5 Bus5	1.05		20	9.8e+002	1.7e+002
				-0.6		-0.18	-5.2e+002	-
1.6e+002								
3 Bus3	1.050	23.18	4 Bus4	1.05		21	1.5e+004	21
				1.1		0.041	4.1e+002	15
4 Bus4	1.046	21.08	3 Bus3	1.05		23	6.5e+002	-
1.6e+002								
				-1.1		-0.0014	-4e+002	-0.53
			5 Bus5	1.05		20	2e+002	44
				3.2		-1.4	1.1e+002	-49
			2 Bus2	0.923		4.4	4.7e+002	11
				1.5		0.25	2.9e+002	50
5 Bus5	1.050	19.56	1 Bus1	1		24	7.7e+002	1.7e+002
2.4e+002				-0.79		-0.46	-4.2e+002	-

```

        4           Bus4          1.05          21  1.8e+002  -
1.6e+002
                                -3.9          0.14  -1.1e+002
4
        2           Bus2          0.923         4.4  9.3e+002  -4.6
                                0.69         0.31  5.3e+002  2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000032 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000033 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000034 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000035 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000
-----
Time = 2.58000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle   Delta     Freq    Pgen    Qgen    Pmech   Efd/Slip
      pu       Degree   Degree   Hzs.    MW      MVAR    MW      pu/P.U.
-----
1   Bus1       1       24.8     25.3     50      433     297     389     1.01
3   Bus3       1.05    23.2     23.7     50      476     55.5     520     1.05
-----
Maximum rotor angle difference : 1.58706 b/w buses : 1 and 3
Island 1 Common system frequency 50.027
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle   To      Name      Voltage Angle   Current Angle
                           Zl-real   Zl-im   P        Q
-----
1   Bus1       1.000    24.80    5   Bus5      1.05      20  2e+004  -9.6
                               0.63      0.43 4.3e+002  3e+002
2   Bus2       0.923    4.57     4   Bus4      1.05      21  5.5e+002  1.6e+002
                               -1      -0.44  -2.8e+002  -
1.2e+002
                               5   Bus5      1.05      20  9.8e+002  1.7e+002
                               -0.6      -0.18  -5.2e+002  -
1.6e+002
3   Bus3       1.050    23.24    4   Bus4      1.05      21  1.5e+004  21
                               1.1      0.044 4e+002  16
4   Bus4       1.046    21.19    3   Bus3      1.05      23  6.3e+002  -
1.6e+002
                               -1.1      -0.0036 -3.9e+002  -
1.3
                               5   Bus5      1.05      20  1.9e+002  46
                               3.4      -1.6  1.1e+002  -48
2   Bus2       0.923      1.5      0.25 2.9e+002  50
-----
```

-0.78 -0.44 -4.3e+002 -

2.4e+002								
	4	Bus4		1.05				
1.6e+002								
				-4.2				
2.6		Bus2	0.923		4.6 9.3e+002		-4.3	
			0.69		0.31 5.3e+002	2.4e+002		
kp 0 kq 0 Iterations 3 dpmax 0.000036 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000037 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000038 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000039 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000040 dqmax 0.000000								
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000								

---

Time = 2.60000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	25.1	25.7	50	442	297	389	1.01
3	Bus3	1.05	23.3	23.8	50	467	55.6	520	1.05

---

Maximum rotor angle difference : 1.86203 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

---

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle		
						z1-real	z1-im	P	Q
1	Bus1	1.000	25.13	5	Bus5	1.05		20	2.1e+004 -8.8
						0.62		0.42	4.4e+002 3e+002
2	Bus2	0.923	4.75	4	Bus4	1.05		21	5.5e+002 1.6e+002
						-1		-0.45	-2.8e+002 -
1.2e+002				5	Bus5	1.05		20	9.9e+002 1.7e+002
						-0.6		-0.18	-5.2e+002 -
1.6e+002									
3	Bus3	1.050	23.31	4	Bus4	1.05		21	1.4e+004 21
						1.1		0.046	3.9e+002 16
4	Bus4	1.046	21.30	3	Bus3	1.05		23	6.2e+002 -
1.6e+002								-1.1	-0.006 -3.9e+002 -
2									
				5	Bus5	1.05		20	1.7e+002 47
						3.6		-1.7	98 -47

---

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5	Bus5	1.050	19.99	1	Bus1	1.5	0.25	2.9e+002	49
						1	25	8e+002	1.7e+002
						-0.77	-0.43	-4.4e+002	-
2.4e+002				4	Bus4	1.05		21	1.6e+002
1.6e+002							-4.5	0.063	-98
				2	Bus2	0.923	4.7	9.3e+002	-4.1
						0.69	0.31	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000041 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000042 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000043 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000044 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000045 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000046 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000047 dqmax 0.000000									
<hr/>									
Time = 2.62000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	25.4	26	50	450	298	389	1.01
3	Bus3	1.05	23.4	23.9	50	459	55.8	520	1.05
<hr/>									
Maximum rotor angle difference : 2.11791 b/w buses : 1 and 3									
Island 1 Common system frequency 50.027									
<hr/>									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
1	Bus1	1.000	25.44	5	Bus5	1.05	20	2.1e+004	-8
					0.62	0.41	4.5e+002	3e+002	
2	Bus2	0.923	4.93	4	Bus4	1.05	21	5.5e+002	1.6e+002
					-1	-0.45	-2.8e+002	-	
1.2e+002				5	Bus5	1.05	20	9.9e+002	1.7e+002
					-0.6	-0.18	-5.2e+002	-	
1.6e+002									
3	Bus3	1.050	23.39	4	Bus4	1.05	21	1.4e+004	21
					1.2	0.048	3.8e+002	16	
4	Bus4	1.046	21.42	3	Bus3	1.05	23	6e+002	-
1.6e+002						-1.2	-0.0084	-3.8e+002	-
2.8				5	Bus5	1.05	20	1.6e+002	49
					3.8	-2	-91	-47	

				2	Bus2	0.923	4.9	4.7e+002	12		
						1.5	0.25	2.9e+002	49		
5	Bus5	1.050	20.21	1	Bus1	1	25	8.1e+002	1.7e+002		
						-0.77	-0.41	-4.5e+002	-		
2.4e+002				4	Bus4	1.05	21	1.4e+002	-		
1.6e+002						-4.9	0.009	-91	0.17		
				2	Bus2	0.923	4.9	9.4e+002	-3.8		
						0.69	0.31	5.4e+002	2.4e+002		
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000048 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000049 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000050 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000051 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000052 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000053 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000054 dqmax 0.000000											
-----											
Time = 2.64000 Seconds											
Intermediate results for Machines											
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.		
1	Bus1	1	25.7	26.3	50	458	298	389	1.01		
3	Bus3	1.05	23.5	23.9	50	451	55.9	520	1.05		
-----											
Maximum rotor angle difference : 2.35169 b/w buses : 1 and 3											
Island 1 Common system frequency 50.027											
-----											
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines											
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	Zl-real	Zl-im	P	Q
-----											
1	Bus1	1.000	25.75	5	Bus5	1.05	20	2.1e+004	-7.3		
						0.61	0.4	4.6e+002	3e+002		
2	Bus2	0.923	5.11	4	Bus4	1.05	22	5.5e+002	1.6e+002		
						-1	-0.45	-2.8e+002	-		
1.2e+002				5	Bus5	1.05	20	9.9e+002	1.7e+002		
						-0.6	-0.18	-5.2e+002	-		
1.6e+002											
3	Bus3	1.050	23.47	4	Bus4	1.05	22	1.4e+004	21		
						1.2	0.051	3.7e+002	16		
4	Bus4	1.046	21.54	3	Bus3	1.05	23	5.9e+002	-		
1.6e+002							-1.2	-0.011	-3.7e+002	-	
3.4				5	Bus5	1.05	20	1.5e+002	50		

```

        4      -2.2      84      -46
        2      Bus2      0.923    5.1 4.6e+002    12
                  1.5      0.26 2.9e+002    49
      5      Bus5      1.050    20.42     1      Bus1      1      26 8.2e+002 1.7e+002
                  -0.76    -0.4  -4.5e+002   -
2.4e+002
1.6e+002
        4      Bus4      1.05      22 1.3e+002   -
        -5.2      -0.057     -84      -0.92
        2      Bus2      0.923    5.1 9.4e+002    -3.6
                  0.68    0.31 5.4e+002 2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000055 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000056 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000057 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000058 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000059 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000060 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000061 dqmax 0.000000
kp 0 kq 0 Iterations 3 dpmax 0.000062 dqmax 0.000000
-----
Time = 2.66000 Seconds
Intermediate results for Machines
GNo Name      Voltage Angle Delta Freq Pgen Qgen Pmech Efd/Slip
      pu       Degree  Degree Hzs. MW  MVAR MW  pu/P.U.
----- -----
  1  Bus1       1       26    26.6   50    464   299   389   1.01
  3  Bus3      1.05    23.6    24     50    444   56.1   520   1.05
-----
Maximum rotor angle difference : 2.56068 b/w buses : 1 and 3
Island 1 Common system frequency 50.027
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name      Voltage Angle To Name      Voltage Angle Current Angle
      pu       Degree   pu       Degree   Zl-real Zl-im   P       Q
----- -----
  1  Bus1      1.000  26.04   5  Bus5      1.05      21 2.1e+004   -6.7
                  0.61      0.39 4.6e+002 3e+002
  2  Bus2      0.923  5.30    4  Bus4      1.05      22 5.5e+002 1.6e+002
                  -1      -0.46  -2.8e+002   -
1.2e+002
                  5  Bus5      1.05      21 9.9e+002 1.7e+002
                  -0.6      -0.18  -5.2e+002   -
1.6e+002
  3  Bus3      1.050  23.57   4  Bus4      1.05      22 1.3e+004   21
                  1.2      0.053 3.6e+002 16
  4  Bus4      1.046  21.68   3  Bus3      1.05      24 5.8e+002   -
1.6e+002
                  -1.2      -0.013 -3.6e+002   -
4

```

				5	Bus5	1.05	21	1.4e+002	52
						4.2	-2.4	78	-45
				2	Bus2	0.923	5.3	4.6e+002	12
						1.5	0.26	2.9e+002	49
5	Bus5	1.050	20.63	1	Bus1	1	26	8.3e+002	1.7e+002
						-0.76	-0.39	-4.6e+002	-
2.4e+002				4	Bus4	1.05	22	1.2e+002	-
1.6e+002						-5.6	-0.14	-78	-1.9
				2	Bus2	0.923	5.3	9.4e+002	-3.4
						0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000063 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000064 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000065 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000066 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000067 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000068 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000069 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000070 dqmax 0.000000									
-----									
Time = 2.68000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	26.3	26.9	50	470	299	389	1.01
3	Bus3	1.05	23.7	24.1	50	438	56.3	520	1.05
-----									
Maximum rotor angle difference : 2.74244 b/w buses : 1 and 3									
Island 1 Common system frequency 50.027									
-----									
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name		Voltage	Angle	To Name	Voltage	Angle	Current	Angle	
-----	-----	-----	-----	-----	Zl-real	Zl-im	P	Q	-----
1	Bus1	1.000	26.32	5	Bus5	1.05	21	2.1e+004	-6.1
					0.61	0.38	4.7e+002	3e+002	
2	Bus2	0.923	5.48	4	Bus4	1.05	22	5.5e+002	1.6e+002
					-1	-0.46	-2.8e+002	-	
1.2e+002				5	Bus5	1.05	21	9.9e+002	1.7e+002
					-0.6	-0.18	-5.2e+002	-	
1.6e+002									
3	Bus3	1.050	23.68	4	Bus4	1.05	22	1.3e+004	21
					1.2	0.056	3.6e+002	16	
4	Bus4	1.046	21.82	3	Bus3	1.05	24	5.7e+002	-
1.6e+002									

						-1.2	-0.016	-3.6e+002	-		
4.6											
		5	Bus5		1.05	21	1.4e+002	53			
					4.4	-2.7	73	-44			
		2	Bus2		0.923	5.5	4.6e+002	12			
					1.5	0.26	2.8e+002	49			
5	Bus5	1.050	20.84	1	Bus1	1	26	8.3e+002	1.7e+002		
						-0.75	-0.38	-4.7e+002	-		
2.4e+002				4	Bus4		1.05				
1.6e+002						-6	-0.23	-73	-2.7		
				2	Bus2	0.923	5.5	9.4e+002	-3.1		
						0.68	0.3	5.4e+002	2.4e+002		
kp 0 kq 0 Iterations 3 dpmax 0.000071 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000072 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000073 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000074 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000075 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000076 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000077 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000078 dqmax 0.000000											
kp 0 kq 0 Iterations 3 dpmax 0.000079 dqmax 0.000000											
-----											
Time = 2.70000 Seconds											
Intermediate results for Machines											
GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.		
---	---	---	---	---	---	---	---	---	---		
1	Bus1	1	26.6	27.2	50	475	299	389	1.01		
3	Bus3	1.05	23.8	24.3	50	433	56.4	520	1.05		
-----											
Maximum rotor angle difference : 2.89483 b/w buses : 1 and 3											
Island 1 Common system frequency 50.027											
-----											
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines											
From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle	Zl-real	Zl-im	P	Q
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
1	Bus1	1.000	26.59	5	Bus5	1.05	21	2.2e+004	-5.6		
						0.6	0.38	4.8e+002	3e+002		
2	Bus2	0.922	5.67	4	Bus4	1.05	22	5.5e+002	1.6e+002		
						-1	-0.46	-2.8e+002	-		
1.2e+002				5	Bus5	1.05	21	9.9e+002	1.7e+002		
						-0.6	-0.18	-5.2e+002	-		
1.6e+002											
3	Bus3	1.050	23.80	4	Bus4	1.05	22	1.3e+004	21		
						1.2	0.058	3.5e+002	16		

4	Bus4	1.046	21.97	3	Bus3	1.05	24	5.6e+002	-	
1.6e+002						-1.2	-0.018	-3.5e+002	-	
5.1				5	Bus5	1.05	21	1.3e+002	54	
						4.5	-2.9	69	-44	
				2	Bus2	0.922	5.7	4.6e+002	12	
						1.5	0.26	2.8e+002	49	
5	Bus5	1.050	21.05	1	Bus1	1	27	8.4e+002	1.7e+002	
2.4e+002						-0.75	-0.38	-4.7e+002	-	
1.6e+002				4	Bus4	1.05	22	1.1e+002	-	
						-6.4	-0.32	-69	-3.4	
				2	Bus2	0.922	5.7	9.4e+002	-2.9	
						0.68	0.3	5.4e+002	2.4e+002	
kp 0 kq 0 Iterations 3 dpmax 0.000080 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000081 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000082 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000083 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000084 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000085 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000086 dqmax 0.000002										
kp 0 kq 0 Iterations 3 dpmax 0.000087 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000088 dqmax 0.000000										
kp 0 kq 0 Iterations 3 dpmax 0.000089 dqmax 0.000001										
<hr/>										
Time = 2.72000 Seconds										
Intermediate results for Machines										
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip	
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.	
---	---	---	---	---	---	---	---	---	---	
1	Bus1	1	26.8	27.4	50	479	300	389	1.01	
3	Bus3	1.05	23.9	24.4	50	429	56.6	520	1.05	
---	---	---	---	---	---	---	---	---	---	
Maximum rotor angle difference : 3.01609 b/w buses : 1 and 3										
Island 1 Common system frequency 50.027										
<hr/>										
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From	Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
						Zl-real	Zl-im	P	Q	
---	---	---	---	---	---	---	---	---	---	
1	Bus1	1.000	26.85	5	Bus5	1.05	21	2.2e+004	-5.2	
						0.6	0.37	4.8e+002	3e+002	
2	Bus2	0.922	5.86	4	Bus4	1.05	22	5.5e+002	1.6e+002	
						-1	-0.46	-2.7e+002	-	
1.2e+002				5	Bus5	1.05	21	9.9e+002	1.7e+002	
						-0.6	-0.18	-5.2e+002	-	
1.6e+002	3	Bus3	1.050	23.94	4	Bus4	1.05	22	1.3e+004	21

4	Bus4	1.046	22.12	3	Bus3	1.3	0.06	3.5e+002	17
1.6e+002						1.05	24	5.6e+002	-
						-1.3	-0.02	-3.5e+002	-
5.5				5	Bus5	1.05	21	1.3e+002	56
						4.7	-3.1	65	-43
				2	Bus2	0.922	5.9	4.6e+002	12
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	21.25	1	Bus1	1	27	8.4e+002	1.7e+002
2.4e+002						-0.75	-0.37	-4.7e+002	-
1.6e+002				4	Bus4	1.05	22	1e+002	-
						-6.7	-0.41	-65	-4
				2	Bus2	0.922	5.9	9.4e+002	-2.7
						0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 3 dpmax 0.000090 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000091 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000092 dqmax 0.000001									
kp 0 kq 0 Iterations 3 dpmax 0.000093 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000094 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000095 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000096 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000097 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000098 dqmax 0.000000									
kp 0 kq 0 Iterations 3 dpmax 0.000099 dqmax 0.000000									

---

Time = 2.74000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	27.1	27.7	50	482	300	389	1.01
3	Bus3	1.05	24.1	24.6	50	426	56.7	520	1.05

---

Maximum rotor angle difference : 3.10477 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

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Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle			
	pu	Degree		pu	Degree	Zl-real	Zl-im	P	Q	
1	Bus1	1.000	27.08	5	Bus5	1.05		21	2.2e+004	-4.8
						0.6		0.37	4.8e+002	3e+002
2	Bus2	0.922	6.05	4	Bus4	1.05		22	5.5e+002	1.6e+002
						-1		-0.47	-2.7e+002	-
1.2e+002				5	Bus5	1.05		21	9.9e+002	1.7e+002
						-0.6		-0.18	-5.2e+002	-
1.6e+002										

3	Bus3	1.050	24.09	4	Bus4	1.05	22	1.3e+004	21
						1.3	0.061	3.5e+002	17
4	Bus4	1.046	22.29	3	Bus3	1.05	24	5.5e+002	-
1.6e+002						-1.3	-0.021	-3.5e+002	-
5.8									
				5	Bus5	1.05	21	1.2e+002	57
						4.8	-3.2	63	-43
				2	Bus2	0.922	6.1	4.6e+002	13
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	21.45	1	Bus1	1	27	8.5e+002	1.8e+002
2.4e+002						-0.74	-0.37	-4.8e+002	-
				4	Bus4	1.05	22	1e+002	-
1.6e+002						-7	-0.49	-63	-4.4
				2	Bus2	0.922	6.1	9.4e+002	-2.5
						0.68	0.3	5.4e+002	2.4e+002

Time = 2.76000 Seconds

## Intermediate results for Machines

Intermediate Results for Machine									
GNO	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	27.3	27.9	50	484	300	389	1.01
3	Bus3	1.05	24.3	24.7	50	425	56.7	520	1.05

Maximum rotor angle difference : 3.15983 b/w buses : 1 and 3  
Island 1 Common system frequency 50.027



				5		Bus5		1.05		22	9.9e+002	1.7e+002			
								-0.6		-0.18	-5.3e+002		-		
1.6e+002															
	3		Bus3	1.050	24.45	4		Bus4	1.05		23	1.3e+004		22	
									1.3	0.062	3.4e+002		17		
	4			Bus4	1.046	22.66	3		Bus3	1.05		24	5.5e+002		
1.6e+002										-1.3	-0.022	-3.4e+002			
	6												-		
							5		Bus5	1.05		22	1.2e+002	58	
								4.8		-3.4		61		-43	
							2		Bus2	0.922		6.4	4.6e+002	13	
								1.5		0.26	2.8e+002		49		
	5			Bus5	1.050	21.85	1		Bus1	1		28	8.5e+002	1.8e+002	
2.3e+002										-0.74		-0.36	-4.8e+002		
1.6e+002							4		Bus4	1.05		23		97	
										-7.2	-0.58		-60		-4.8
							2		Bus2	0.922		6.4	9.4e+002		-2.1
										0.68		0.3	5.4e+002	2.4e+002	
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000006 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000															
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000															

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Time = 2.80000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	27.7	28.3	50	485	300	389	1.01
3	Bus3	1.05	24.6	25.1	50	424	56.8	520	1.05

---

Maximum rotor angle difference : 3.16682 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name	Voltage	Angle	To Name	Voltage	Angle	Current	Angle
				Zl-real	Zl-im	P	Q

---

1	Bus1	1.000	27.70	5	Bus5	1.05		22	2.2e+004	-4
						0.6		0.37	4.8e+002	3e+002

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1.2e+002						-1	-0.47	-2.7e+002	-
				5	Bus5	1.05	22	9.9e+002	1.7e+002
						-0.6	-0.18	-5.3e+002	-
1.6e+002									
3	Bus3	1.050	24.65	4	Bus4	1.05	23	1.3e+004	22
						1.3	0.062	3.4e+002	17
4	Bus4	1.046	22.86	3	Bus3	1.05	25	5.5e+002	-
1.6e+002						-1.3	-0.022	-3.4e+002	-
6				5	Bus5	1.05	22	1.2e+002	58
						4.8	-3.4	61	-43
				2	Bus2	0.922	6.6	4.6e+002	13
						1.5	0.26	2.8e+002	49
5	Bus5	1.050	22.04	1	Bus1	1	28	8.5e+002	1.8e+002
						-0.74	-0.36	-4.8e+002	-
2.3e+002				4	Bus4	1.05	23		97
1.6e+002						-7.2	-0.57	-61	-4.8
				2	Bus2	0.922	6.6	9.4e+002	-1.9
						0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000									
Time = 2.82000 Seconds									
Intermediate results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
---	---	---	---	---	---	---	---	---	---
1	Bus1	1	27.9	28.4	50	483	300	389	1.01
3	Bus3	1.05	24.9	25.3	50	426	56.7	520	1.05
---	---	---	---	---	---	---	---	---	---
Maximum rotor angle difference : 3.11860 b/w buses : 1 and 3									
Island 1 Common system frequency 50.027									
-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines									
From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	
					Zl-real	Zl-im	P	Q	
---	---	---	---	---	---	---	---	---	---
1	Bus1	1.000	27.88	5	Bus5	1.05	22	2.2e+004	-3.9
					0.6	0.37	4.8e+002	3e+002	

2	Bus2	0.922	6.83	4	Bus4	1.05 -1	23	5.5e+002	1.6e+002	-
1.2e+002				5	Bus5	1.05 -0.6	22	9.9e+002	1.7e+002	-
1.6e+002				4	Bus4	1.05 1.3	23	1.3e+004	22	0.062 3.5e+002
3	Bus3	1.050	24.86	4	Bus4	1.05 1.3	23	1.3e+004	22	0.062 3.5e+002
1.6e+002				3	Bus3	1.05	25	5.5e+002	17	-
4	Bus4	1.046	23.07	3	Bus3	-1.3	-0.022	-3.4e+002	-	-
1.6e+002						5	Bus5	1.05 4.8	22	1.2e+002
5.8						2	Bus2	0.922 1.5	6.8	4.6e+002
2.4e+002						5	Bus1	1 -0.74	0.26	2.8e+002
1.6e+002						4	Bus4	1.05	28	8.5e+002
Time =	2.84000	Seconds				23			99	-
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000							-7.1	-0.52	-62	-4.6
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000							2	0.922	6.8	9.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000							0.68	0.3	5.4e+002	2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000007 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000										
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000										

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hz.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	28	28.6	50	481	300	389	1.01
3	Bus3	1.05	25.1	25.6	50	428	56.6	520	1.05

Maximum rotor angle difference : 3.03648 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name Voltage Angle To Name Voltage Angle Current Angle  
 Zl-real Zl-im P Q

Time = 2.86000 Seconds

## Intermediate results for Machines

Intermediate Results for Machines										
GNO	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.	
1	Bus1		1	28.2	28.7	50	477	299	389	1.01
3	Bus3	1.05		25.3	25.8	50	432	56.5	520	1.05

Maximum rotor angle difference : 2.92138 b/w buses : 1 and 3  
Island 1 Common system frequency 50.027

## MiP-PSCT

TRS

1	Bus1	1.000	28.18	5	Bus5	1.05	23	2.2e+004	-3.9
2	Bus2	0.922	7.23	4	Bus4	1.05	24	5.5e+002	1.6e+002
						-1		-0.46	-2.8e+002
1.2e+002				5	Bus5	1.05	23	9.9e+002	1.7e+002
						-0.6		-0.18	-5.2e+002
1.6e+002									-
3	Bus3	1.050	25.34	4	Bus4	1.05	24	1.3e+004	23
						1.3		0.059	3.5e+002
4	Bus4	1.046	23.51	3	Bus3	1.05	25	5.6e+002	16
1.6e+002									-
5.2						-1.2		-0.019	-3.5e+002
				5	Bus5	1.05	23	1.3e+002	56
						4.6		-3	67
				2	Bus2	0.922		7.2	4.6e+002
						1.5		0.26	2.8e+002
5	Bus5	1.050	22.61	1	Bus1	1	28	8.4e+002	1.8e+002
						-0.75		-0.37	-4.7e+002
2.4e+002				4	Bus4		1.05		24 1.1e+002
1.6e+002								-6.5	-0.36
								2	7.2 9.4e+002
								0.68	0.3 5.4e+002
									2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000008 dqmax 0.000000									
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kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									
kp 0 kq 0 Iterations 4 dpmax 0.000009 dqmax 0.000000									

Time = 2.88000 Seconds

Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	28.3	28.9	50	472	299	389	1.01
3	Bus3	1.05	25.6	26.1	50	436	56.3	520	1.05

Maximum rotor angle difference : 2.77459 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name Voltage Angle To Name Voltage Angle Current Angle  
 Zl-real Zl-im P Q

Time = 2.90000 Seconds

### Intermediate results for Machines

Intermediate Results for Machines									
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.
1	Bus1	1	28.4	29	50	467	299	389	1.01
3	Bus3	1.05	25.9	26.4	50	442	56.2	520	1.05

Maximum rotor angle difference : 2.59779 b/w buses : 1 and 3  
Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines  
 From Name      Voltage Angle      To      Name      Voltage Angle      Current Angle

Time = 2.92000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmehc MW	Efd/Slip pu/P.U.
1	Bus1	1	28.5	29.1	50	460	298	389	1.01
3	Bus3	1.05	26.2	26.7	50	448	56	520	1.05

Maximum rotor angle difference : 2.39299 b/w buses : 1 and 3

Island 1 Common system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PII) and power (MW-MVAR) for lines

Time = 2.94000 Seconds

## Intermediate results for Machines

Intermediate Results for Machines									
GNO	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmehc	Efd/Slip
	pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.	

1	Bus1	1	28.6	29.1	50	453	298	389	1.01
3	Bus3	1.05	26.5	27	50	456	55.8	520	1.05

Maximum rotor angle difference : 2.16253 b/w buses : 1 and 3  
Island 1. German system frequency 50.027

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines

From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle		
						Zl-real	Zl-im	P	Q		
1	Bus1	1.000	28.62	5	Bus5	1.05		23	2.1e+004	-4.7	
						0.62	0.41	4.5e+002	3e+002		
2	Bus2	0.923	8.05	4	Bus4	1.05		25	5.5e+002	1.6e+002	
						-1		-0.45	-2.8e+002	-	
1.2e+002				5	Bus5	1.05		23	9.9e+002	1.7e+002	
						-0.6		-0.18	-5.2e+002	-	
1.6e+002											
3	Bus3	1.050	26.47	4	Bus4	1.05		25	1.4e+004	24	
						1.2	0.049	3.8e+002	16		
4	Bus4	1.046	24.52	3	Bus3	1.05		26	6e+002	-	
1.6e+002								-1.2	-0.0095	-3.7e+002	-
3				5	Bus5	1.05		23	1.6e+002	52	
						3.9	-2	88	-46		
				2	Bus2	0.923		8.1	4.6e+002	15	
						1.5	0.26	2.9e+002	49		
5	Bus5	1.050	23.34	1	Bus1	1		29	8.1e+002	1.8e+002	
2.4e+002						-0.77		-0.41	-4.5e+002	-	
1.6e+002				4	Bus4		1.05		25	1.4e+002	-
							-5	-0.015	-88	-0.27	
				2	Bus2	0.923		8.1	9.4e+002	-0.69	
						0.69	0.31	5.4e+002	2.4e+002		
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
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kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000											
Time = 2.96000 Seconds											
Intermediate results for Machines											
GNo	Name	Voltage	Angle	Delta	Freq	Pgen	Qgen	Pmech	Efd/Slip		
		pu	Degree	Degree	Hzs.	MW	MVAR	MW	pu/P.U.		
1	Bus1	1	28.7	29.2	50	445	298	389	1.01		
3	Bus3	1.05	26.8	27.3	50	464	55.7	520	1.05		
Maximum rotor angle difference : 1.90906 b/w buses : 1 and 3											
Island	1	Common system frequency			50.027						

Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines										
From Name	Voltage	Angle	To	Name	Voltage	Angle	Current	Angle	Zl-real	Zl-im
							P	Q		
1	Bus1	1.000	28.69	5	Bus5	1.05	24	2.1e+004	-5.1	
2	Bus2	0.923	8.26	4	Bus4	0.62	0.42	4.5e+002	3e+002	
						1.05	25	5.5e+002	1.6e+002	
						-1	-0.45	-2.8e+002	-	
1.2e+002				5	Bus5	1.05	24	9.9e+002	1.7e+002	
						-0.6	-0.18	-5.2e+002	-	
1.6e+002										
3	Bus3	1.050	26.78	4	Bus4	1.05	25	1.4e+004	24	
						1.1	0.047	3.8e+002	16	
4	Bus4	1.046	24.79	3	Bus3	1.05	27	6.1e+002	-	
1.6e+002						-1.1	-0.007	-3.8e+002	-	
2.3				5	Bus5	1.05	24	1.7e+002	51	
						3.7	-1.8	95	-47	
				2	Bus2	0.923	8.3	4.7e+002	15	
						1.5	0.25	2.9e+002	49	
5	Bus5	1.050	23.52	1	Bus1	1	29	8e+002	1.7e+002	
						-0.77	-0.42	-4.4e+002	-	
2.4e+002				4	Bus4	1.05	25	1.5e+002	-	
1.6e+002										
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000						-4.6	0.043	-95	0.89	
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000				2	Bus2	0.923	8.3	9.4e+002	-0.54	
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000						0.69	0.31	5.4e+002	2.4e+002	

Time = 2.98000 Seconds

## Intermediate results for Machines

GNo	Name	Voltage pu	Angle Degree	Delta Degree	Freq Hzs.	Pgen MW	Qgen MVAR	Pmech MW	Efd/Slip pu/P.U.
1	Bus1	1	28.8	29.3	50	436	297	389	1.01
3	Bus3	1.05	27.1	27.6	50	473	55.6	520	1.05

Maximum rotor angle difference : 1.63548 b/w buses : 1 and 3

```

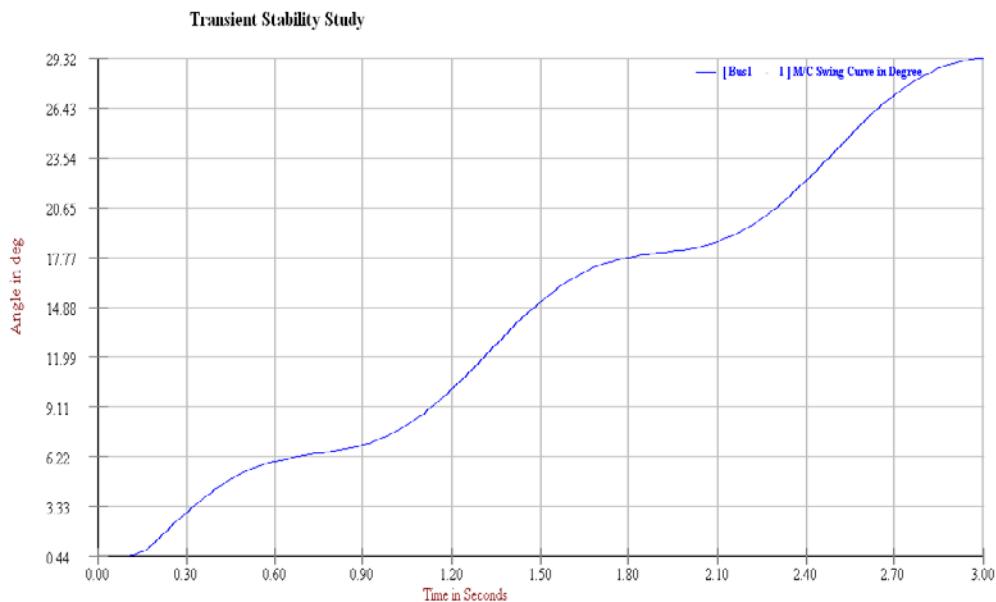
Island      1 Common system frequency      50.027
-----
Voltage (pu), Current (AMPS), impedance (PU) and power (MW-MVAR) for lines
From Name    Voltage Angle   To     Name    Voltage Angle   Current Angle
                                         Zl-real  Zl-im    P        Q
-----
1       Bus1    1.000    28.76   5     Bus5    1.05      24  2e+004  -5.5
                                         0.63      0.43  4.4e+002  3e+002
2       Bus2    0.923    8.47    4     Bus4    1.05      25  5.5e+002  1.6e+002
                                         -1      -0.44  -2.8e+002  -
1.2e+002
                                         5     Bus5    1.05      24  9.9e+002  1.7e+002
                                         -0.6      -0.18  -5.2e+002  -
1.6e+002
3       Bus3    1.050    27.11   4     Bus4    1.05      25  1.4e+004  25
                                         1.1      0.045  3.9e+002  16
4       Bus4    1.046    25.07   3     Bus3    1.05      27  6.3e+002  -
1.6e+002
                                         -1.1      -0.0046 -3.9e+002  -
1.6
                                         5     Bus5    1.05      24  1.8e+002  50
                                         3.5      -1.6   1e+002   -48
                                         2     Bus2    0.923    8.5  4.7e+002  15
                                         1.5      0.25   2.9e+002  50
5       Bus5    1.050    23.70   1     Bus1    1         29  7.9e+002  1.7e+002
                                         -0.78      -0.43  -4.3e+002  -
2.4e+002
                                         4     Bus4    1.05      25  1.6e+002  -
1.6e+002
                                         -4.3      0.09   -1e+002   2.2
                                         2     Bus2    0.923    8.5  9.3e+002  -0.4
                                         0.69      0.31   5.3e+002  2.4e+002
kp 0 kq 0 Iterations 4 dpmax 0.000010 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
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kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
kp 0 kq 0 Iterations 4 dpmax 0.000011 dqmax 0.000000
Time = 3.00000 Seconds
Intermediate results for Machines
GNo Name    Voltage Angle   Delta   Freq   Pgen   Qgen   Pmehc   Efd/Slip
          pu        Degree  Degree Hzs.    MW     MVAR    MW    pu/P.U.
-----
1       Bus1    1           28.8   29.3    50     427    297    389    1.01
3       Bus3    1.05       27.4   28      50     482    55.5    520    1.05

```

Maximum rotor angle difference : 1.34494 b/w buses : 1 and 3  
 Island 1 Common system frequency 50.027

From Name		Voltage	Angle	To	Name	Voltage	Angle	Current	Angle
						Zl-real	Zl-im	P	Q
1	Bus1	1.000	28.83	5	Bus5	1.05	24	2e+004	-6
						0.63	0.44	4.3e+002	3e+002
2	Bus2	0.923	8.68	4	Bus4	1.05	25	5.6e+002	1.7e+002
						-1	-0.44	-2.8e+002	-
1.2e+002				5	Bus5	1.05	24	9.8e+002	1.7e+002
						-0.6	-0.18	-5.2e+002	-
1.6e+002									
3	Bus3	1.050	27.44	4	Bus4	1.05	25	1.5e+004	25
						1.1	0.042	4e+002	16
4	Bus4	1.046	25.35	3	Bus3	1.05	27	6.4e+002	-
1.5e+002									
						-1.1	-0.0023	-4e+002	-0.84
				5	Bus5	1.05	24	1.9e+002	49
						3.3	-1.5	1.1e+002	-49
				2	Bus2	0.923	8.7	4.7e+002	16
						1.5	0.25	2.9e+002	50
5	Bus5	1.050	23.87	1	Bus1	1	29	7.8e+002	1.7e+002
						-0.78	-0.45	-4.2e+002	-
2.4e+002				4	Bus4	1.05	25	1.8e+002	-
1.5e+002						-4		0.13	-1.1e+002
3.5									
				2	Bus2	0.923	8.7	9.3e+002	-0.26
						0.69	0.31	5.3e+002	2.4e+002

Date and Time : Wed Apr 30 10:59:49 2014

**Transient Stability Sample output - Swing – Curve**



## Power Research & Development Consultants Pvt. Ltd.

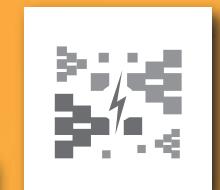
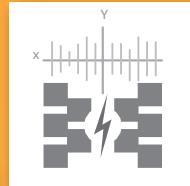
# 5, 11th Cross, 2nd Stage, West of Chord Road, Bengaluru India - 560086.

Tel: +91-80-4245 5555 / 23192209, Fax: +91-80-4245 5556 / 23192210

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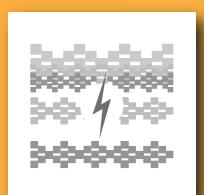
**Free Programmable Block**



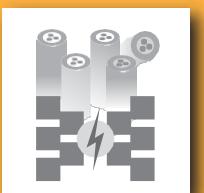
**Power System Network Editor**



**Database Manager**



**COMTRADE Viewer**



**LPC/CPC**